

# ON IMPLICIT LES FOR TURBULENT FLOWS

**Fernando F. Grinstein**

**Applied Physics Division, X-7, LANL**

C. Fureby (FOI), B. Rider & L. Margolin (LANL), D. Youngs (AWE), D. Drikakis (Cranfield), G. Patnaik & J. Boris (NRL)

**What is ILES (MILES) ?**

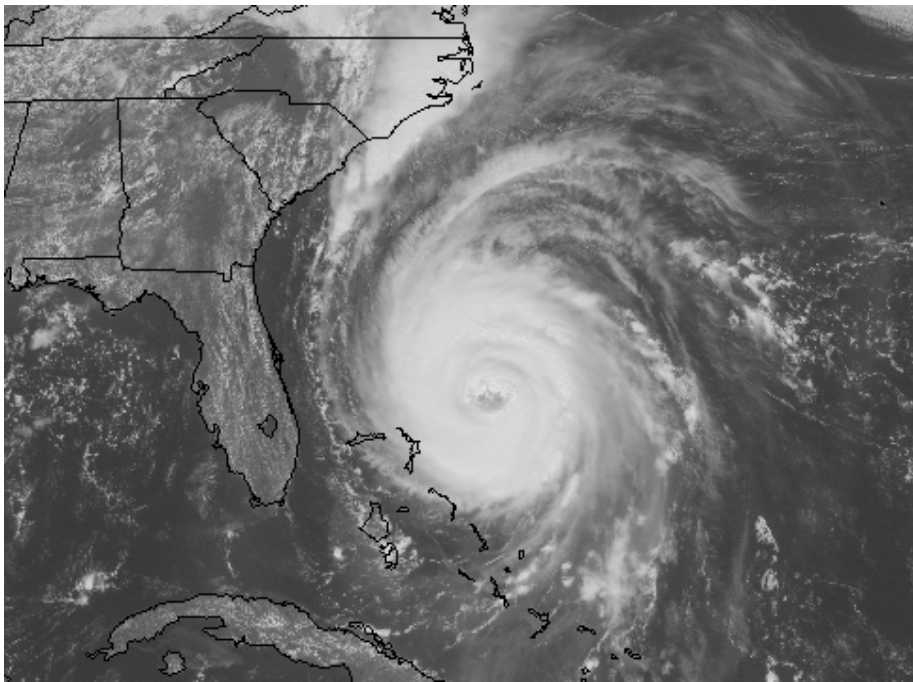
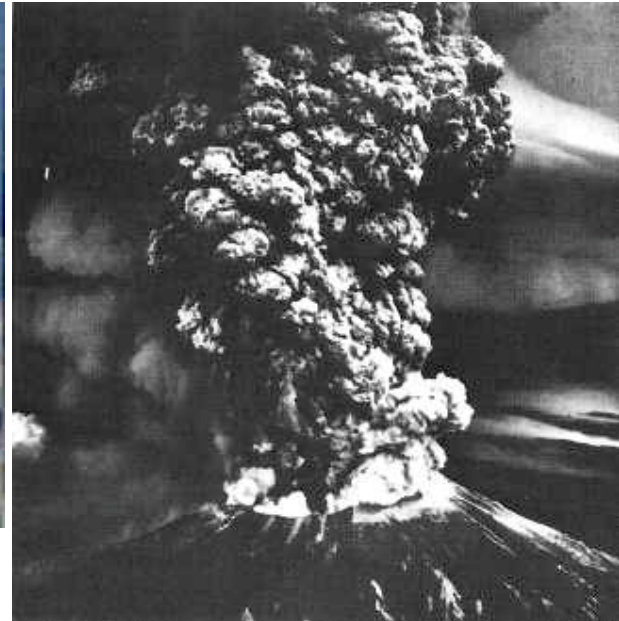
**Historical Perspective & Motivation**

**Capturing Physics with Numerics**

**Applications**

canonical --> complex flow cases

**Outlook**

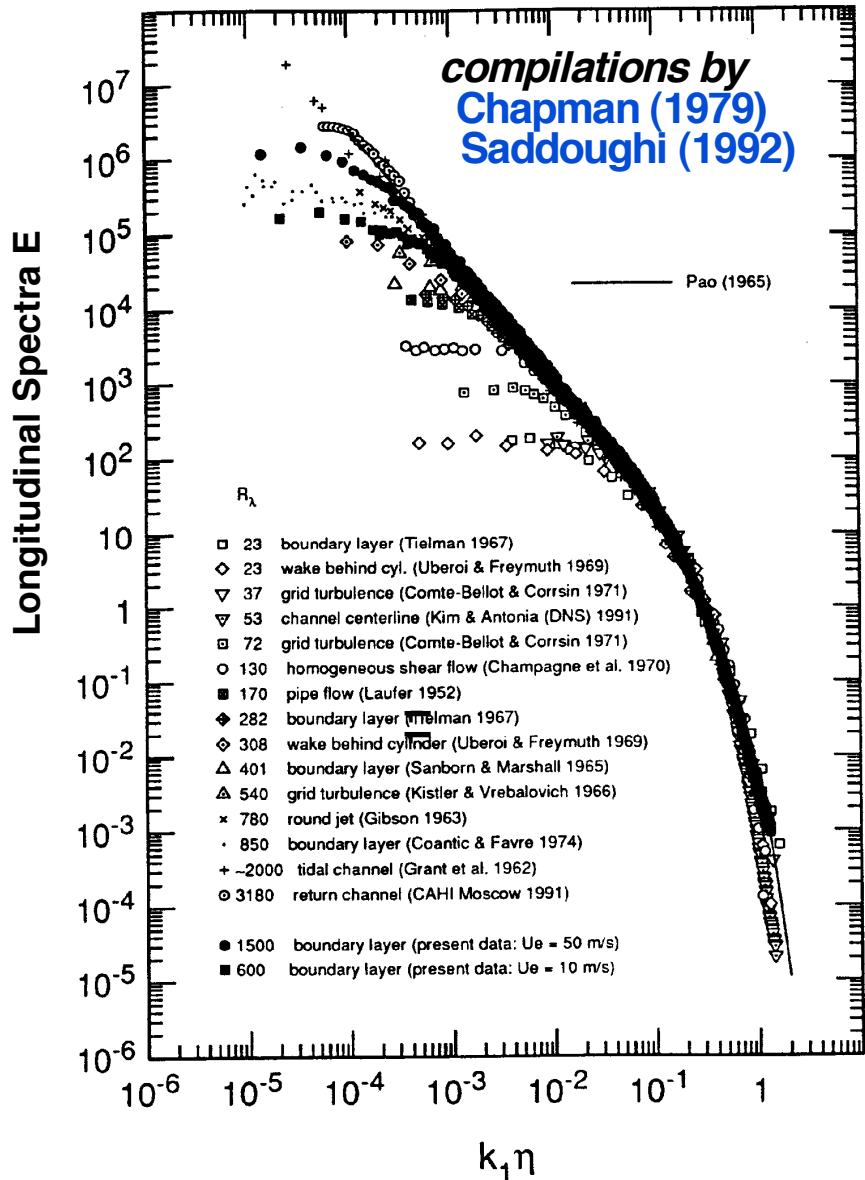


**Numerical Simulation  
of Turbulent Flows is  
based on the N-S eqs.**

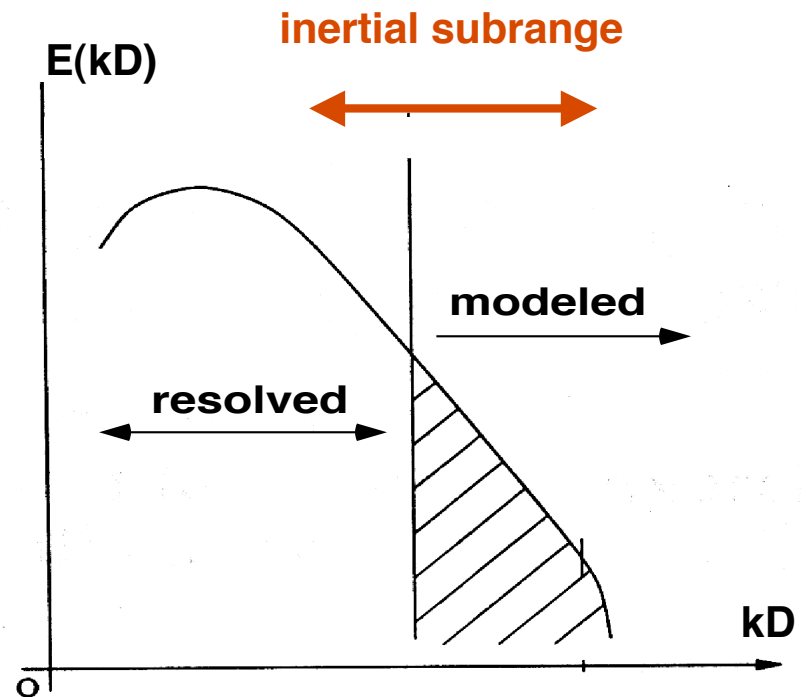
- **DNS, LES, RANS, ....**

**DNS – *solution for all scales without further assumptions*  
is prohibitive for most practical flows of interest !**

# Turbulent Flow Energy Spectra



# Large Eddy Simulation (LES) Approach



## LES Assumptions & Issues:

- based on unsteady N-S equations
- large scales resolved
- smaller scale features modeled
- desirable modeling choices
  - cutoff within inertial subrange
  - smooth transition at cutoff

## The Modified Equation (ME) A framework for LES analysis

- The **Modified Equation** provides the effective differential equation satisfied by the numerical solution by the given method

reproduces the original PDE, and includes the implicit SGS models associated with “error” terms as effective source terms

$$U_t + \nabla \cdot F(U) = \nabla \cdot \tau(U)$$

“error” in divergence form (FV formulation ...)

- Derived via Taylor series expansion
- Compliments standard numerical analysis  
provides nonlinear “error” contributions as well ...

# ME analysis of LES

## LES ingredients

- low-pass filter the Navier-Stokes equations
- finite volume, element or difference discretization

$$\bar{f}(\mathbf{x}_P) = \frac{1}{\delta V_P} \int_{\Omega_P} f(\mathbf{x}') G(\mathbf{x}' - \mathbf{x}_P, \Delta) dV'$$

$$\mathbf{v} \rightarrow \bar{\mathbf{v}}_N$$

## Modified LES Equations

(satisfied by numerical solutions)

$$\mathbf{B} = \overline{\mathbf{v} \otimes \mathbf{v}} - \bar{\mathbf{v}} \otimes \bar{\mathbf{v}}$$

explicit SGS stress model

$$\partial(\bar{\mathbf{v}}) + \nabla \cdot (\bar{\mathbf{v}} \otimes \bar{\mathbf{v}}) = -\nabla \bar{p} + \nabla \cdot \bar{\mathbf{S}}$$

$$- \nabla \cdot \mathbf{B} + \boldsymbol{\tau} + \mathbf{m}$$

commutation error term

discretization "error" term

"well-resolved"

LES requires:

$$\boldsymbol{\tau} \ll \nabla \cdot \mathbf{B} + \mathbf{m}$$

**NOTE:** In the absence of an accepted turbulence theory, SGS modeling must be based on

➔ rational use of empirical info ➔ *pragmatic practice ...*

$$\mathbf{B} = \overline{\mathbf{v} \otimes \mathbf{v}} - \bar{\mathbf{v}} \otimes \bar{\mathbf{v}}$$

$$\partial(\bar{\mathbf{v}}) + \nabla \cdot (\bar{\mathbf{v}} \otimes \bar{\mathbf{v}}) = -\nabla \bar{p} + \nabla \cdot \bar{\mathbf{S}} - \nabla \cdot \mathbf{B} + \dots$$

conventional (explicit) SGS stress models

**Functional models:** most popular, e.g., Smagorinsky eddy-viscosity (involving *isotropic* SGS's):

$$\mathbf{B} = -2\nu_k \bar{\mathbf{D}}_N \quad \nu_k = c_D \Delta^2 \|\bar{\mathbf{D}}_N\| \quad \bar{\mathbf{D}}_N = \frac{1}{2}(\nabla \cdot \bar{\mathbf{v}}_N + \nabla \cdot \bar{\mathbf{v}}_N^T)$$

basic limitation: (B) and strain rate (D) are largely uncorrelated & topologically different  $\rightarrow$  assumption (B  $\propto$  D) is inappropriate !

**Structural models:** better, e.g., scale-similarity & approx. deconvolution (involving *anisotropic* SGS's):

$$\mathbf{B}_2 = \overline{\bar{\mathbf{v}} \otimes \bar{\mathbf{v}}} - \bar{\bar{\mathbf{v}}}_N \otimes \bar{\bar{\mathbf{v}}}_N$$

- significantly more complex computationally
- typically, not dissipative enough by itself
- used with scalar eddy-viscosity type term in 'mixed' models,  $\mathbf{B} = \mathbf{B}_1 + \mathbf{B}_2$   
e.g., with  $\mathbf{B}_1 = -2\nu_k \bar{\mathbf{D}}_N \rightarrow$  which may defeat the potential gains ...

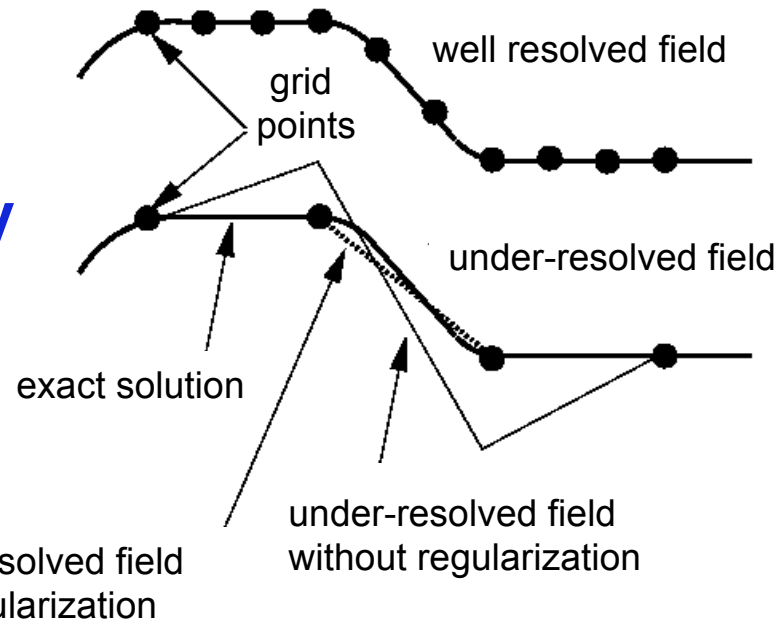
--> non-conventional SGS modeling approaches need to be explored !

# “Alternative” LES

- **hyperviscosity**  
Borue & Orszag
- **approximate deconvolution**  
Domaradzki, Adams
- ***ab-initio* scale separation**  
Temam, Hughes
- **spectral vanishing viscosity**  
Karniadakis
- **implicit SGS modeling**  
**--> ILES, MILES**

focus on:

- convectively dominated dynamics
- under-resolution
- regularization
- weak solutions



# Implicit LES

- FV framework  
"error" term  $\rightarrow \nabla \cdot \tau$
- ME analysis

$$\partial(\bar{\mathbf{v}}) + \nabla \cdot (\bar{\mathbf{v}} \otimes \bar{\mathbf{v}}) = -\nabla \bar{p} + \nabla \cdot \bar{\mathbf{S}} - \nabla \cdot \mathbf{B} + \nabla \cdot \tau + \mathbf{m}$$

$$\mathbf{B} = \overline{\mathbf{v} \otimes \mathbf{v}} - \bar{\mathbf{v}}_N \otimes \bar{\mathbf{v}}_N$$

- **No explicit filtering:** no commutation error term ( $\mathbf{m} \equiv 0$ ); discretization provides top-hat-shaped-kernel filtered values through  $\bar{f}_P \equiv 1/\delta V_P \int_{\Omega_P} f dV$
- **$\mathbf{B} \equiv 0$ :** minimal SGS model, decoupled GS's & SGS's

When based on stable (consistent) numerics, ILES converges to DNS *to the same extent expected from any LES*

(*cutoff length* determined by explicit **or** implicit filter  $\rightarrow 0$ )

When based on NFV numerics, ILES is competitive with classical LES in the LES realm proper (convectively dominated flows driven by large scale features)



## ILES = Free Lunch ?

**Not all implicit SGS modeling will work !**

The numerical scheme has to be constructed such that lead truncation “errors” satisfy required SGS-model properties

i.e., **SGS physics must be built into the numerics !**

→ nonlinear discretization is required

Analogy:

Shock-capturing schemes designed under the requirements:

- Convergence to weak solution
- Entropy condition satisfied

**Likewise: sharp-gradient capturing FV schemes can be viewed as relevant for ILES -- if we focus on the small scale characteristic features of turbulence ....**

## Implicit LES: Historical Precedents (courtesy, Bill Rider, LANL)

### Smagorinsky's EV based on von Neumann-Richtmyer viscosity in 3D

$$C_{AV} h^2 |u_x| u_x \Rightarrow C_{Smag} h^2 \|\nabla u\| \nabla u$$

- J. Smagorinsky, *Advances in Geophysics*, Vol. 25, 1983, gives a history of the first weather calculations (Phillips) and a meeting where they were discussed. S's work followed from using vN's viscosity to cure ringing.

→ first shock capturing and first LES have same basis !

### Artificial viscosities (Q's) have become adaptive to the flow physics

- In 1955 Rosenbluth suggested Q's be turned off in expansions.
- Q's have been connected to the properties of the materials (Kurapatenko) and Riemann solvers (Dukowicz)
- Q's are now **dynamic**. Using methods from the high-resolution world (i.e., limiters) the Q's turn off in smooth resolved flow  
→ *philosophically suggestive of the dynamic Smagorinsky model ...*

→ shock capturing methods and LES have evolved similarly !

# Physical Requirements for nonlinear Implicit SGS Models

**Inherent small-scale anisotropy  
of high-Re turbulent flows**

- adaptiveness to local flow physics
- sharp velocity-gradient capturing

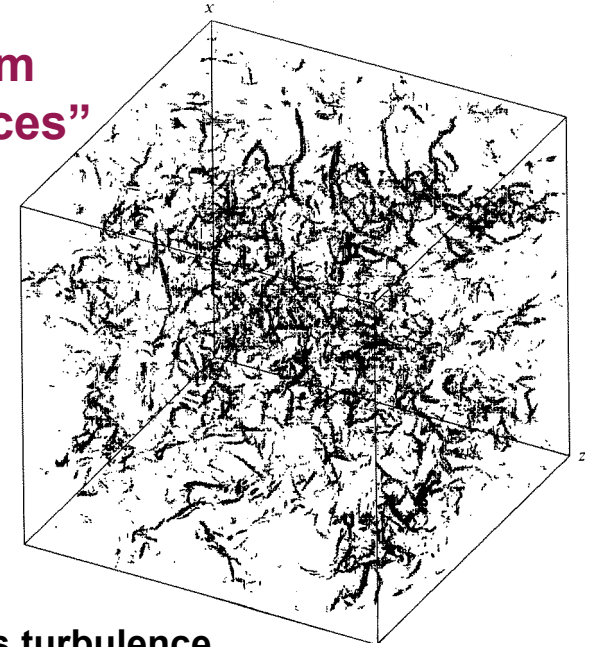
**Inherently discrete nature  
of laboratory observables:**

- conservative FV schemes

**Other desirable requirements**

- dissipative relevant solutions
- nonlinear stability
- positivity (where needed)

“worm  
vortices”



homogeneous turbulence  
DNS, Vincent & Meneguzzi 1991

- **Nonoscillatory FV (NFV)**
- **FCT, PPM, MPDATA**
- **Other NFV: e.g., Hybrid**

# Implicitly-Implemented SGS Modeling --> ILES

## Local monotonicity preservation (MILES)

eng

FCT [Boris '89, Boris, FFG, et al. '92, Fureby & FFG '99-'04]

astro

PPM [Porter, Woodward, et al., '94, '98, '00, ...]

eng

Godunov's Riemann solvers [Knight et al. '00, ...]

## Upwinding

eng

Third-Order Upwind-Biased Scheme [Kuwahara, ..., '89, ...]

geo

MPDATA [Margolin, Smolarkiewicz, Rider '00, '02, ...]

## Vorticity confinement [Steinhoff et al. '92, ...]

eng

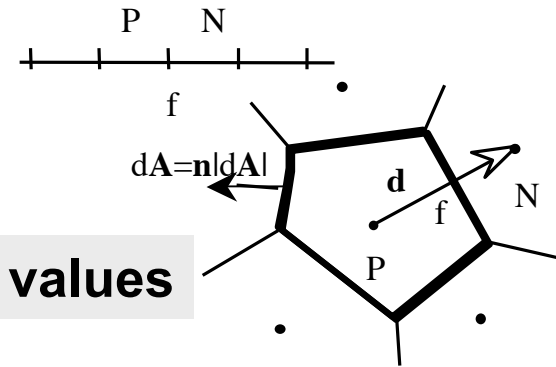
Hybrid methods [Youngs, '91, ... Garnier et al. '99, Drikakis '02, ...]

Other related: approx. deconvolution [Adams, Domaradzki, ...]

## Modified LES Equation used as theoretical framework for ILES

- lead discretization "error" terms introduced by NFV schemes provide:
  - implicit SGS models of *mixed anisotropic* type (Fureby & Grinstein 1999)
  - regularized motion of *discrete observables* (Margolin & Rider 2002)

**Finite Volume Discretization  
of the raw N-S eqs. for MILES  
(momentum equations exemplified)**  
Fureby & Grinstein, AIAAJ '99, JCP '02



**Finite-volume (top-hat-shaped kernel filtered) values**

$$f_P = \frac{1}{\delta V_P} \int_{\Omega_P} f dV$$

**Use Gauss' theorem to obtain semi-discretized NSE; integrate over time with a multi-step method parametrized by  $m$ ,  $\{\alpha_i, \beta_i\}$ ,**

$$\begin{aligned} & \sum_{i=0}^m (\alpha_i (\mathbf{v})_P^{n+i} + \frac{\beta_i \Delta t}{\delta V_P} \sum_f [\mathbf{F}_f^{C,v} + \mathbf{F}_f^{D,v}]^{n+i}) \\ & = - \sum_{i=0}^m \beta_i (\nabla p)_P^{n+i} \Delta t, \end{aligned}$$

**where, the  $\{F$ 's $\}$  are convective, diffusive, and auxiliary fluxes**

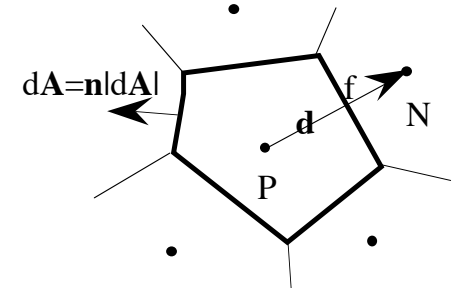
# Functional reconstruction based on Flux-Limiting

Example: momentum equation, 2nd. order fluxes

Blend **High- & Low-order convective fluxes**  
using flux limiter  $\Gamma$

$$\mathbf{v}_f^C = \Gamma \mathbf{v}_f^{C,H} + (1 - \Gamma) \mathbf{v}_f^{C,L}, \quad \Gamma = \Gamma(\mathbf{v}, \mathbf{x}, t)$$

$$\left\{ \begin{array}{l} \mathbf{F}_f^{C,v,H} = F_f^{C,\rho} [l \mathbf{v}_P + (1-l) \mathbf{v}_N - \frac{1}{8} (\mathbf{d} \otimes \mathbf{d}) \nabla^2 \mathbf{v} + \dots], \\ \mathbf{F}_f^{C,v,L} = F_f^{C,\rho} [\beta^+ \mathbf{v}_P + \beta^- \mathbf{v}_N + (\beta^+ - \beta^-) (\nabla \mathbf{v}) \mathbf{d} + \dots]; \\ \beta^\pm = \frac{1}{2} (\mathbf{v}_f \cdot d\mathbf{A} \pm |\mathbf{v}_f \cdot d\mathbf{A}|) / |\mathbf{v}_f \cdot d\mathbf{A}|, \end{array} \right.$$



$$\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = -\nabla p + \nabla \cdot \mathbf{S} + \rho \mathbf{f} \\ + \nabla \cdot \{ \rho (\mathbf{C} \mathbf{L}^T + \mathbf{L} \mathbf{C}^T + \chi^2 \mathbf{L} \mathbf{d} \otimes \mathbf{L} \mathbf{d}) + \frac{1}{6} \mu (\mathbf{d} \otimes \mathbf{d}) \nabla^3 \mathbf{v} + \dots \},$$

$$\mathbf{C} = \chi (\mathbf{v} \otimes \mathbf{d}) \quad \mathbf{L} = \nabla \mathbf{v} \quad \chi = \frac{1}{2} (1 - \Gamma) (\beta^- - \beta^+)$$

# MILES Modified Equation Analysis (CF & FFG, '99, '02,...)

## Functional reconstruction based on Flux-Limiting (e.g., momentum equation, 2nd. order fluxes)

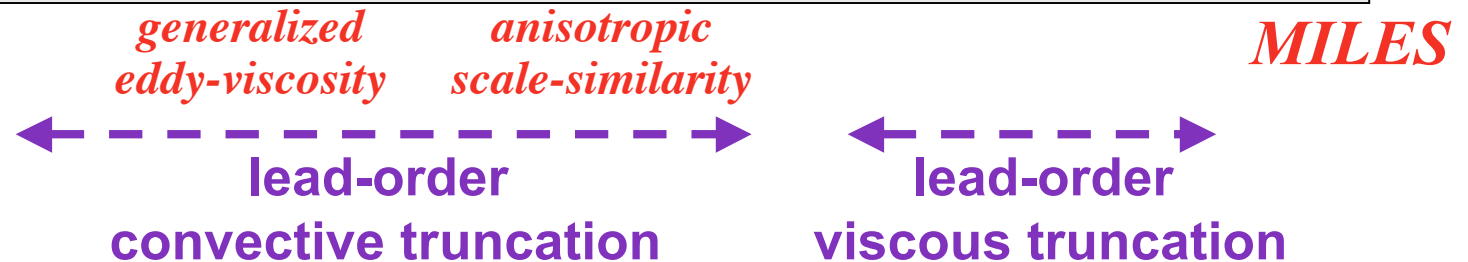
Blend **High- & Low-order**  
convective fluxes  
using flux limiter  $\Gamma$

$$\mathbf{v}_f^C = \Gamma \mathbf{v}_f^{C,H} + (1 - \Gamma) \mathbf{v}_f^{C,L}, \quad \Gamma = \Gamma(\mathbf{v}, \mathbf{x}, t)$$

$$\mathbf{C} = \chi(\mathbf{v} \otimes \mathbf{d}) \quad \mathbf{L} = \nabla \mathbf{v} \quad \chi = \frac{1}{2}(1 - \Gamma)(\beta^- - \beta^+)$$

$$\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = -\nabla p + \nabla \cdot \mathbf{S} + \rho \mathbf{f}$$

$$+ \nabla \cdot \{ \rho(\mathbf{C}\mathbf{L}^T + \mathbf{L}\mathbf{C}^T + \chi^2 \mathbf{L}\mathbf{d} \otimes \mathbf{L}\mathbf{d}) + \frac{1}{6} \mu(\mathbf{d} \otimes \mathbf{d}) \nabla^3 \mathbf{v} + \dots \},$$



$$\partial_t(\bar{\rho} \tilde{\mathbf{v}}) + \nabla \cdot (\bar{\rho} \tilde{\mathbf{v}} \otimes \tilde{\mathbf{v}}) = -\nabla \bar{p} + \nabla \cdot (\bar{\mathbf{S}}) + \bar{\rho} \tilde{\mathbf{f}} \quad \text{conventional LES}$$

$$- \nabla \cdot (\mathbf{B}) - \frac{1}{8} \nabla \cdot \{ (\mathbf{d} \otimes \mathbf{d}) \nabla^2 \tilde{\mathbf{v}} + \frac{1}{6} \mu \nabla \cdot (\mathbf{d} \otimes \mathbf{d}) \nabla^3 \tilde{\mathbf{v}} + \dots$$

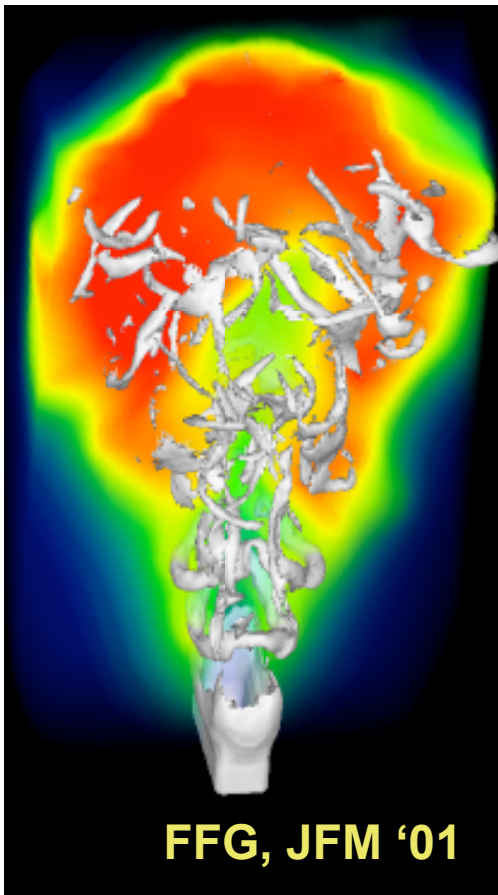
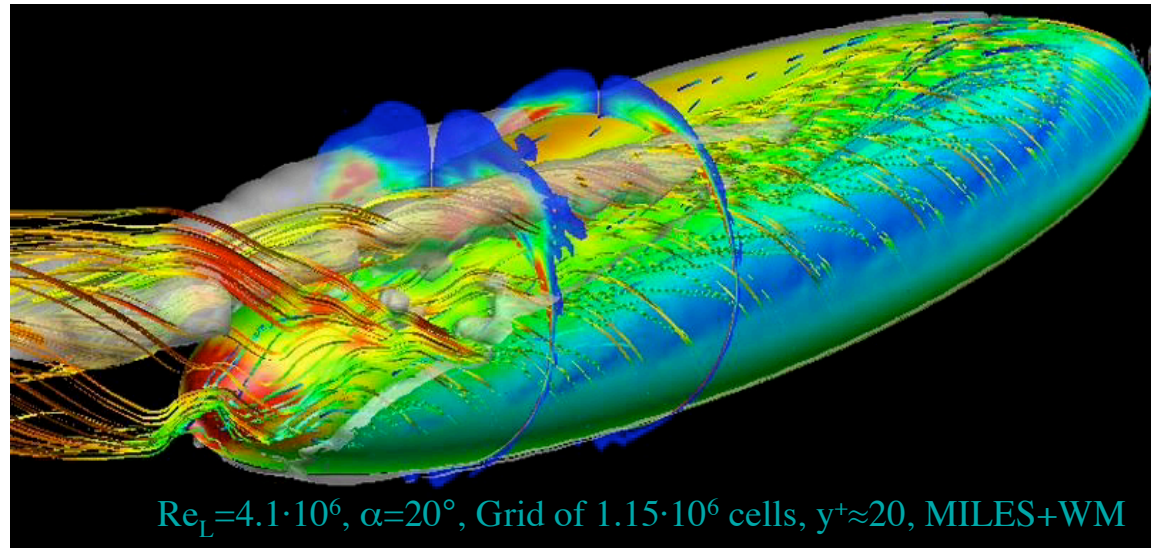
explicit SGS model

lead truncation terms

Fureby et al., AIAA J. '04

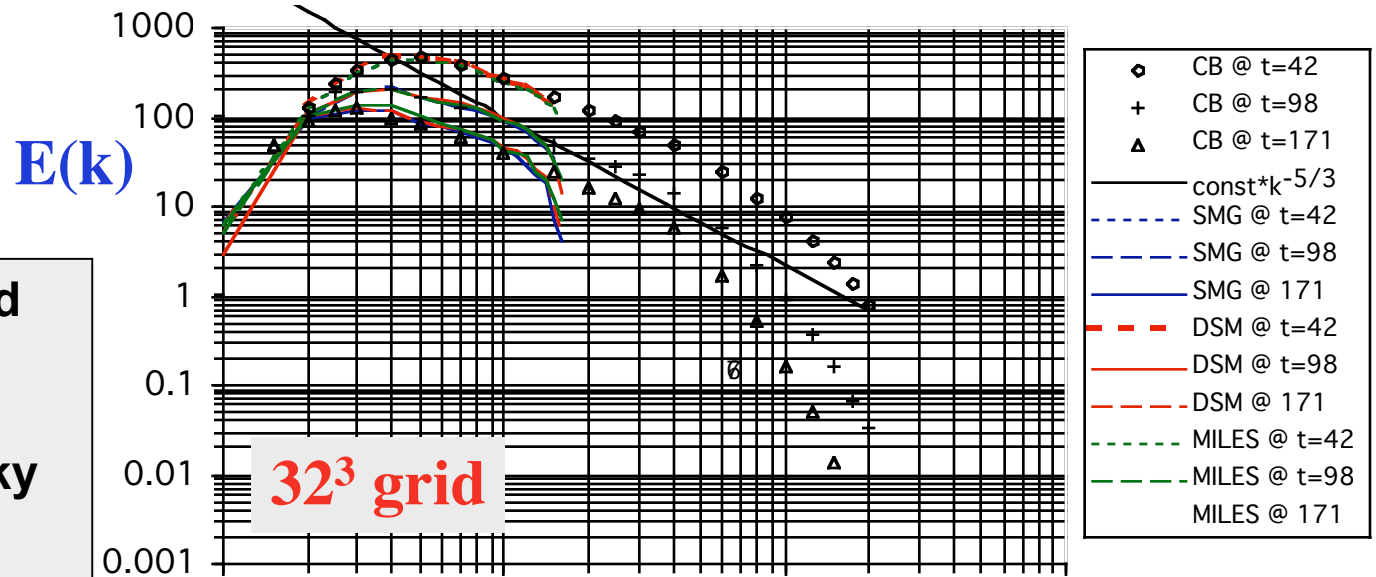
## Extensive MILES applications ...

- canonical --> complex
- free & wall bounded
- **competitive with LES !**





# TURBULENCE DECAY RATES CAPTURED WITH LES

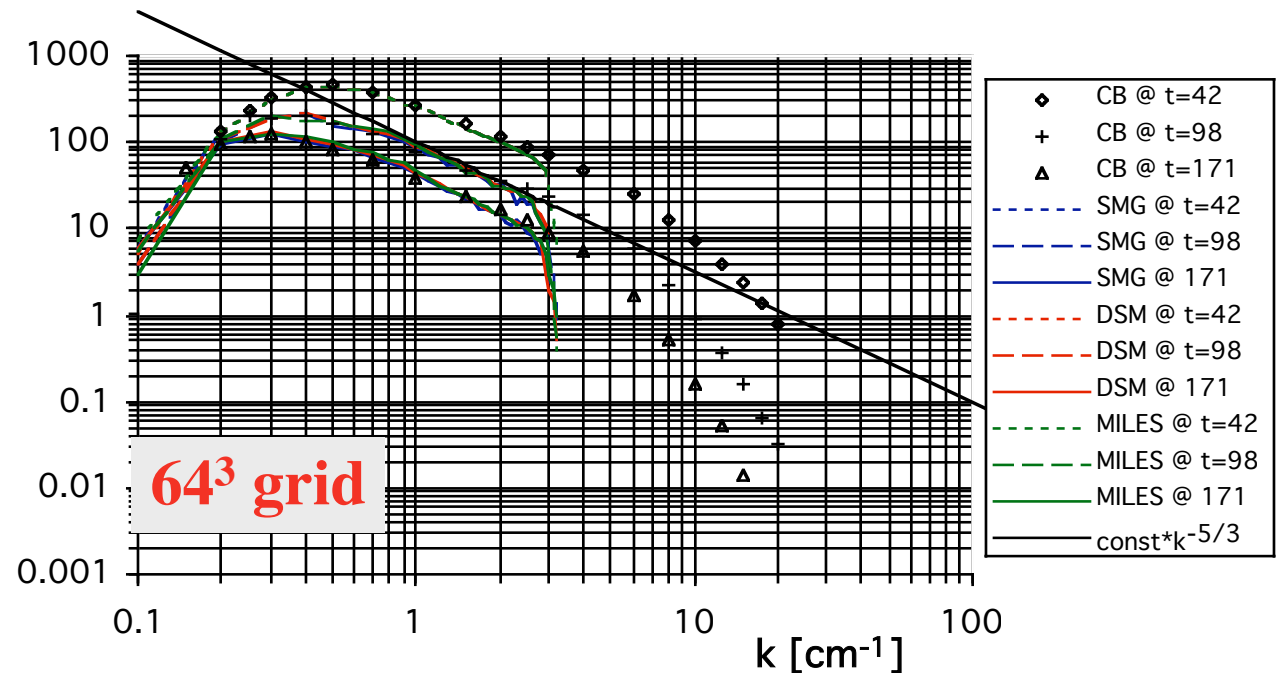


**MILES** : FCT-based  
**DSM** : Differential  
 Stress Model  
**SMG** : Smagorinsky  
 Model

**CB** : Comte-Bellot  
 Laboratory Data  
 (JFM '71)

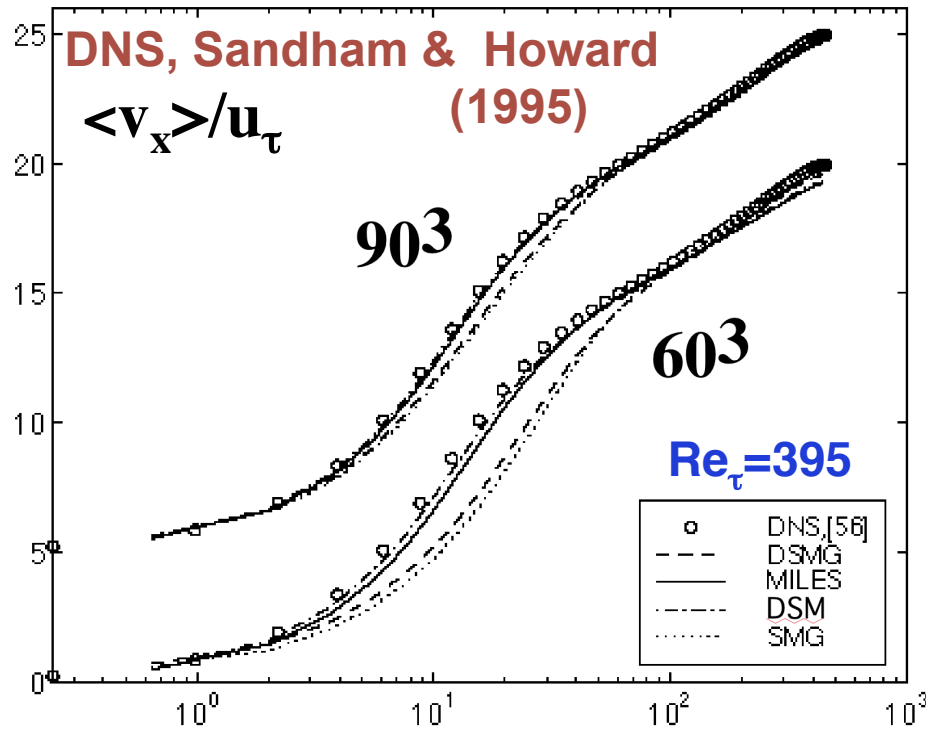
Fureby & Grinstein  
 JCP (Sept. '02)

Excellent recent  
 comparisons with  
 JHU data  
 (B.Rider, X-7)



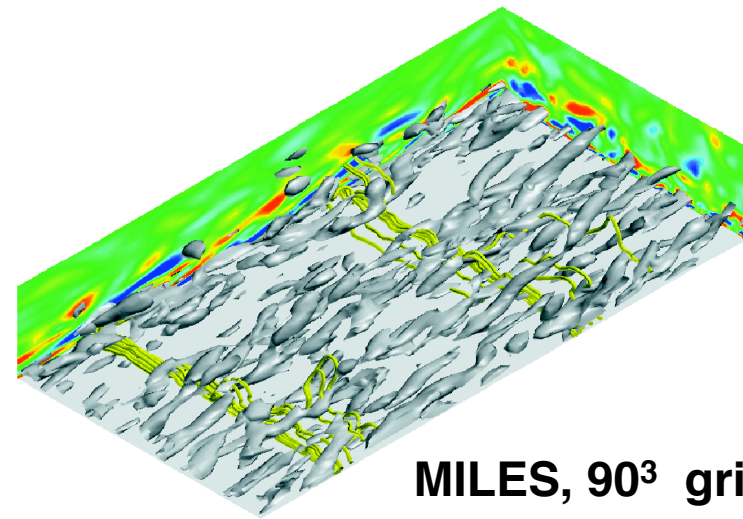
# Turbulent Channel Flows

Fureby & Grinstein, JCP 2002



typical cost:

SMG=1, MILES=0.90, DSM=1.60



$y^+$

MILES : FCT-based

DSM : Differential Stress Model

SMG : Smagorinsky Model

DSMG : Dynamic Smagorinsky Model

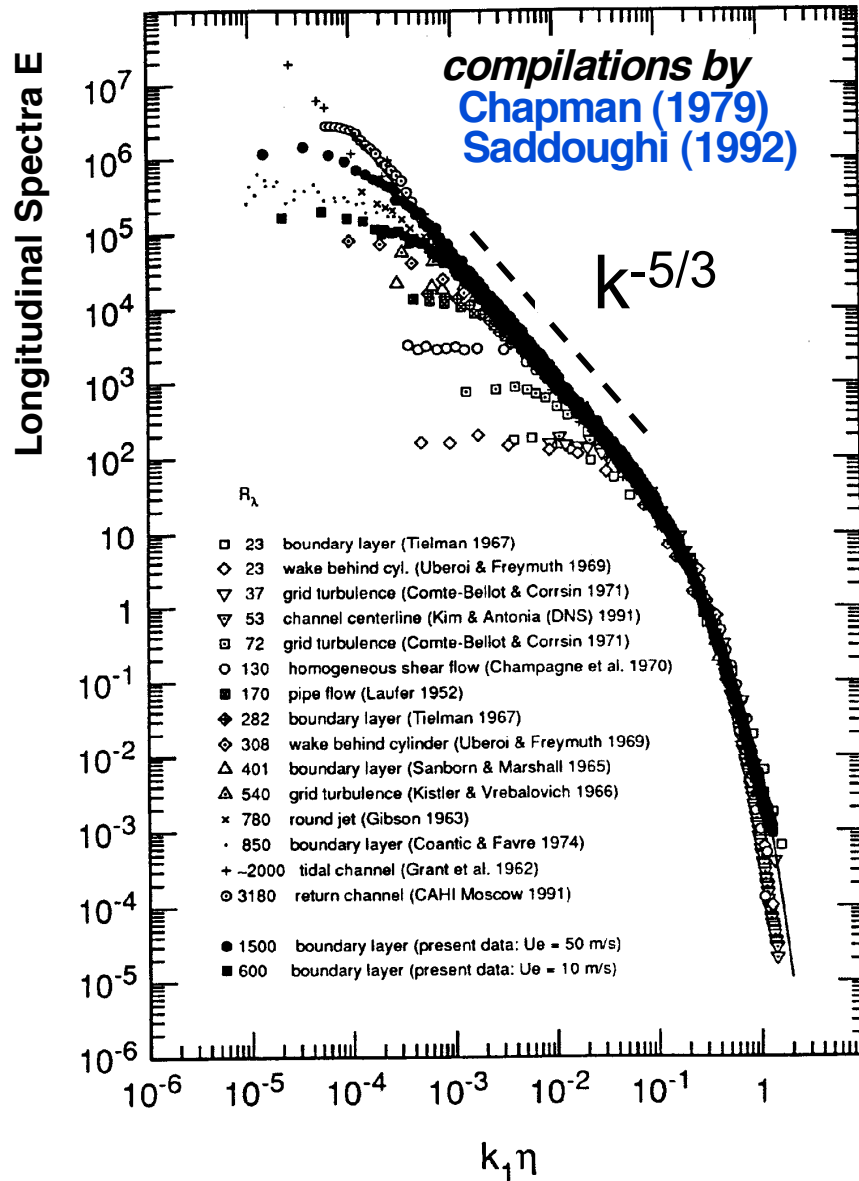
**MILES reproduces first & second order moments of the velocity field**

- almost as accurately as significantly more-complex SGS models
- better than isotropic eddy viscosity models

**Recent Validation Studies:**  
Transition & turbulence decay in  
the Taylor-Green Vortex

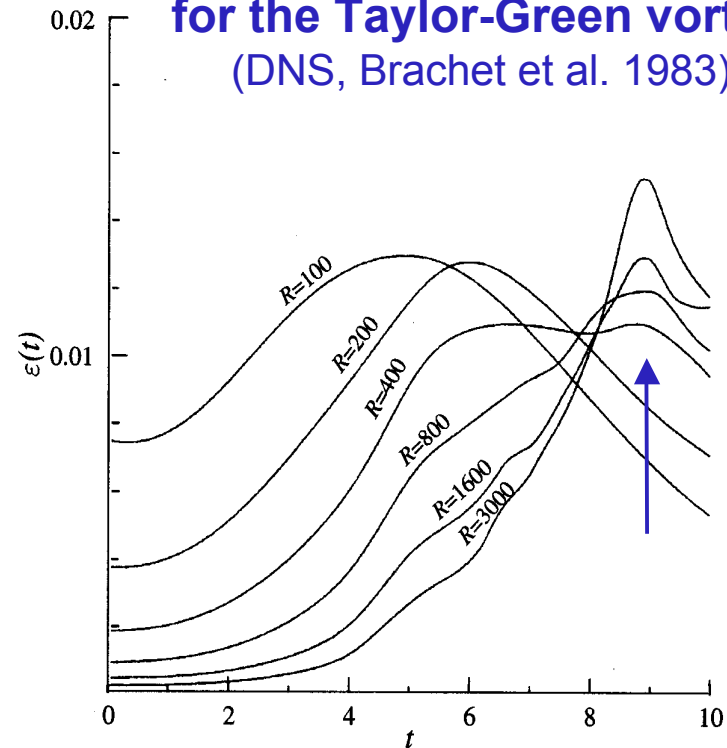
# Empirical Laws of High-Re Developed Turbulence

## Inertial Subrange



## Finite Energy Dissipation

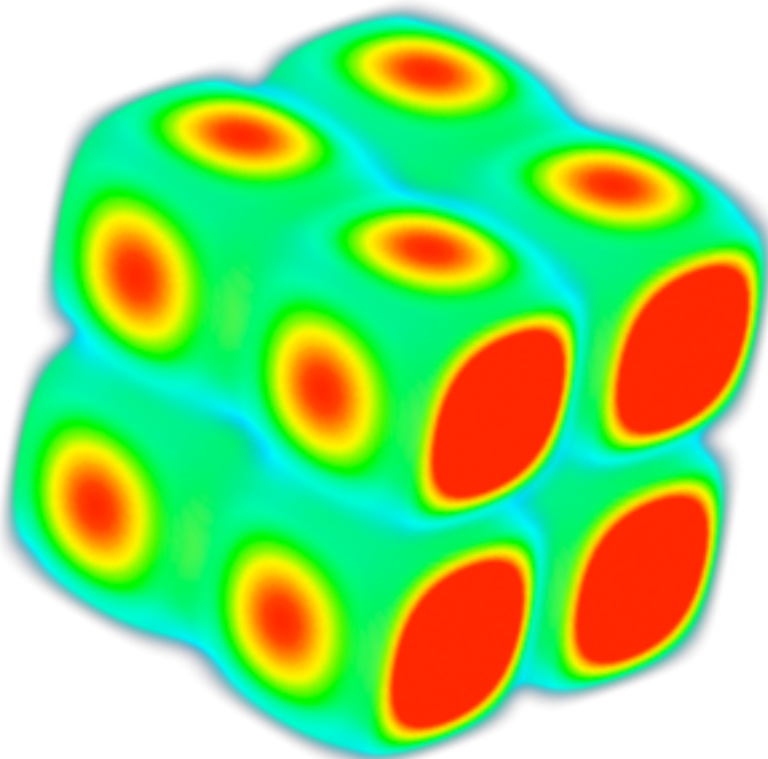
### Energy Dissipation Evolution for the Taylor-Green vortex (DNS, Brachet et al. 1983)



finite positive  
( $\nu$ -independent)  
limit for high-Re

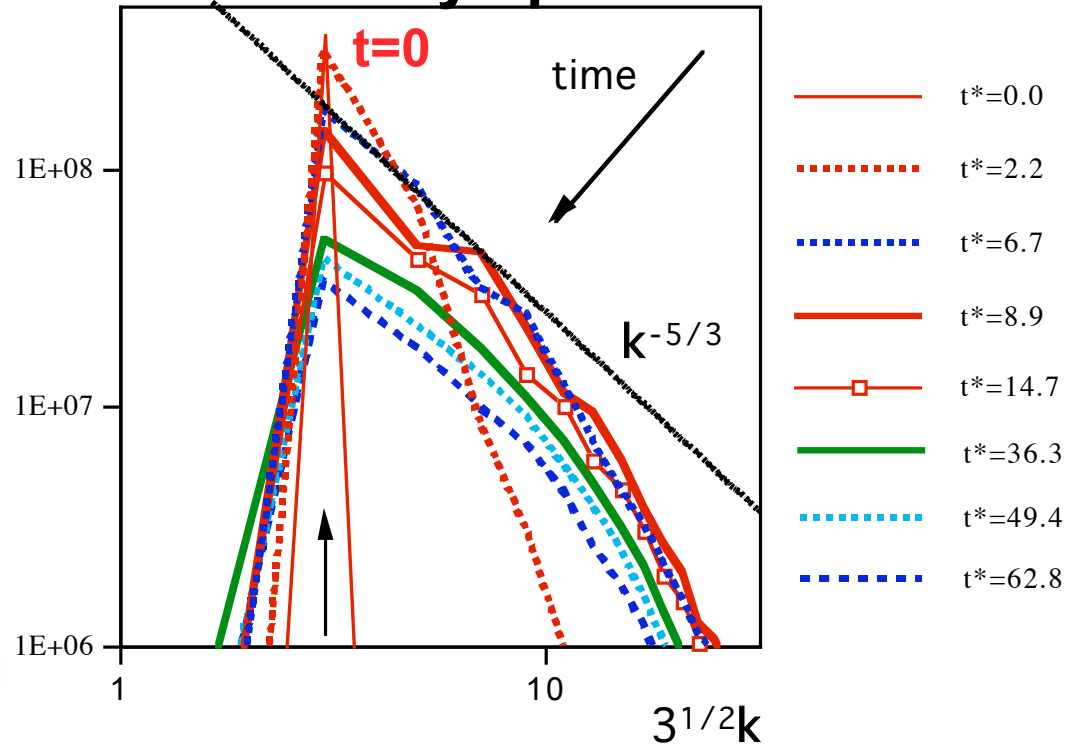
# Evolution of the Taylor-Green Vortex

LES vs. MILES, various limiters (FCT, hybrid ...)



vorticity magnitude

## 3D velocity spectra



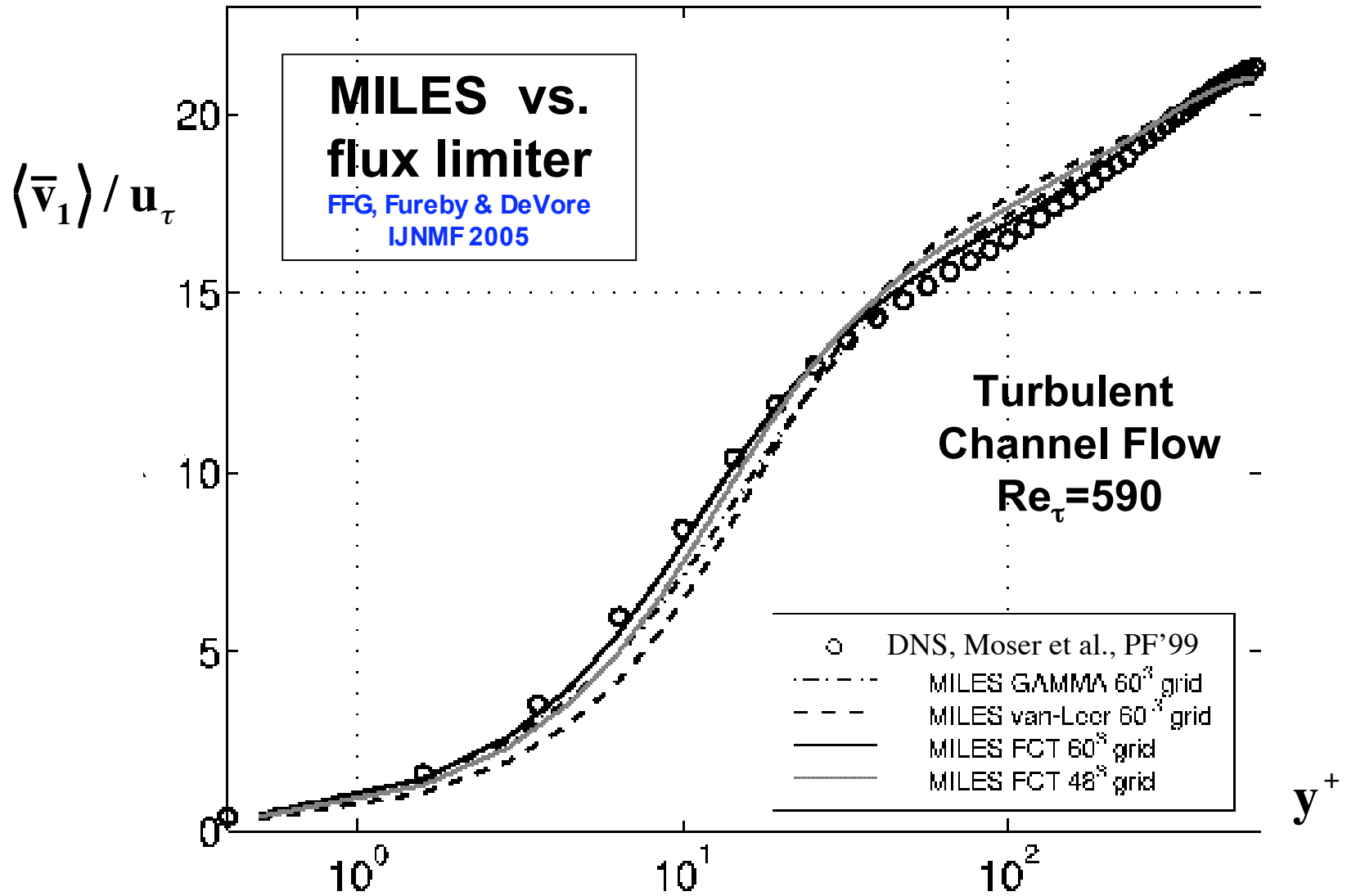
$$\begin{aligned}
 u_o &= U_o \sin(x) \cos(y) \cos(z), \\
 v_o &= -U_o \cos(x) \sin(y) \cos(z), \\
 w_o &= 0, \\
 P_o &= P_{oo} + [\rho(U_o)^2/16] \\
 &\quad \times [2 + \cos(2z)] \cdot [\cos(2x) + \cos(2y)]
 \end{aligned}$$

Mach number  $\sim 0.3$

FFG, Drikakis, Fureby, Youngs, DLES6, Poitiers, 2005

## ILES of Turbulent Flows with NFV Schemes

- *A “natural” extension of shock-capturing concepts for compressible turbulent flow ...*
- *The effects of the SGS physics on the GS’s are incorporated in the functional reconstruction of the convective fluxes; focus on **near cutoff emulation of***
  - *inherently discrete nature of observables*
  - *small-scale vorticity organization: worms*
- *ILES has been successfully applied to broad range of free and wall-bounded flows in engineering, geophysics, and astrophysics; canonical --> complex flows*
- **Modified LES Equation as theoretical framework for ILES**
  - ➔ **lead discretization “error” terms provide:**
    - ➔ **implicit SGS models of mixed anisotropic type**
    - ➔ **regularized motion of discrete observables**
- *implicit SGS model depends on scheme specifics, ...*



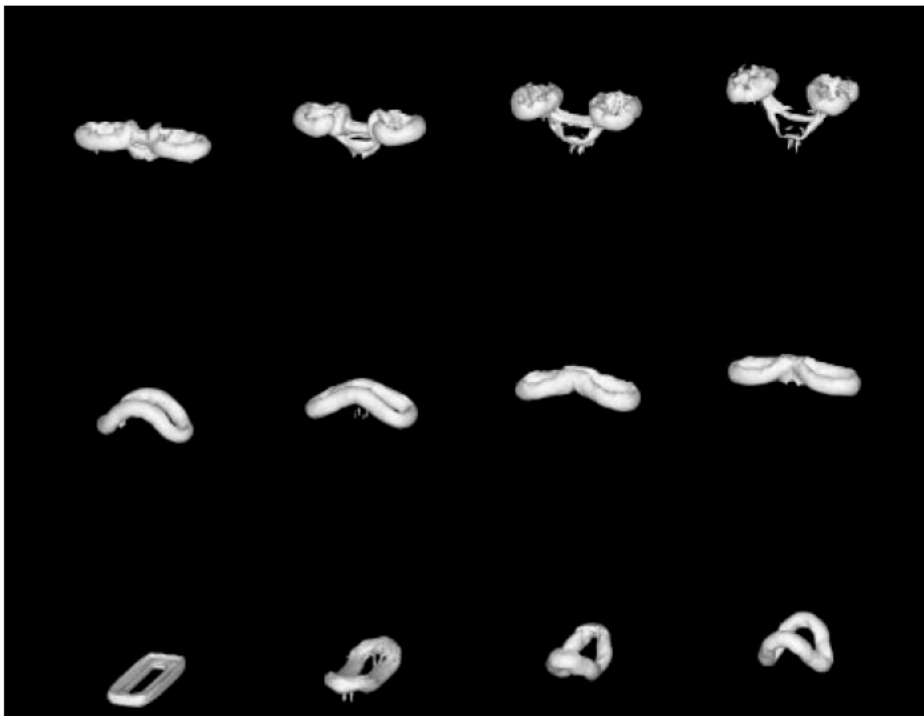
**TVD is generally too diffusive ... locally monotonic schemes, e.g., FCT, GAMMA, (and PPM) appear to work best for ILES (“better” worm emulation ...)**

# FCT-based MILES of Rectangular Jets with $2D \otimes 1D$ splitting (transverse $\otimes$ streamwise)

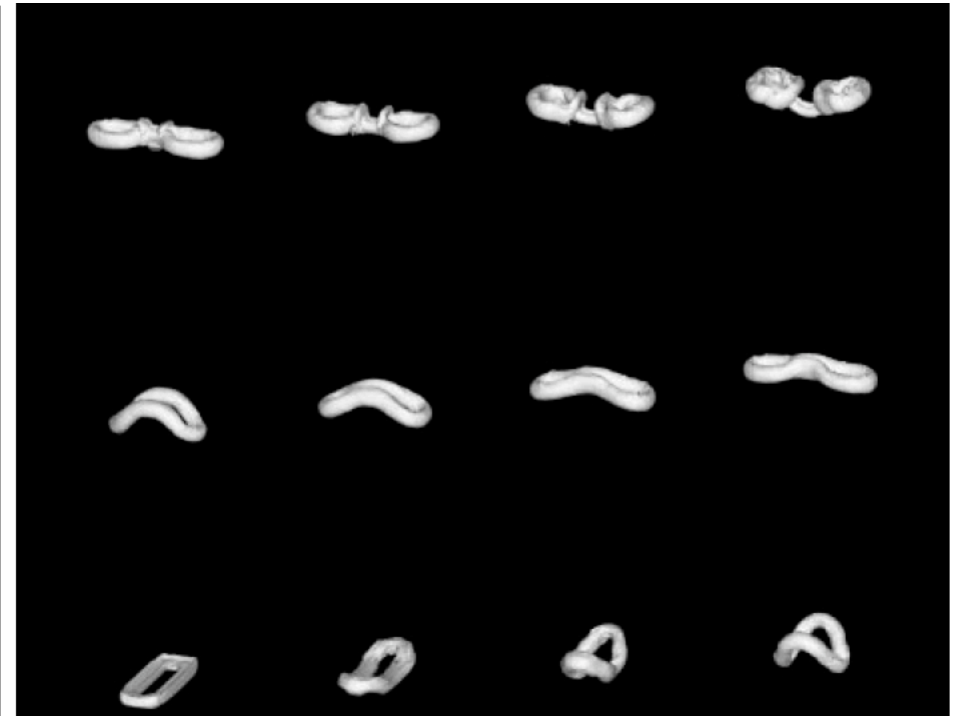
FFG, Fureby & DeVore, IJNMF 2005

positivity- but not monotonicity-preserving

with additional pre-limiting step enforcing local (FCT) monotonicity in each direction



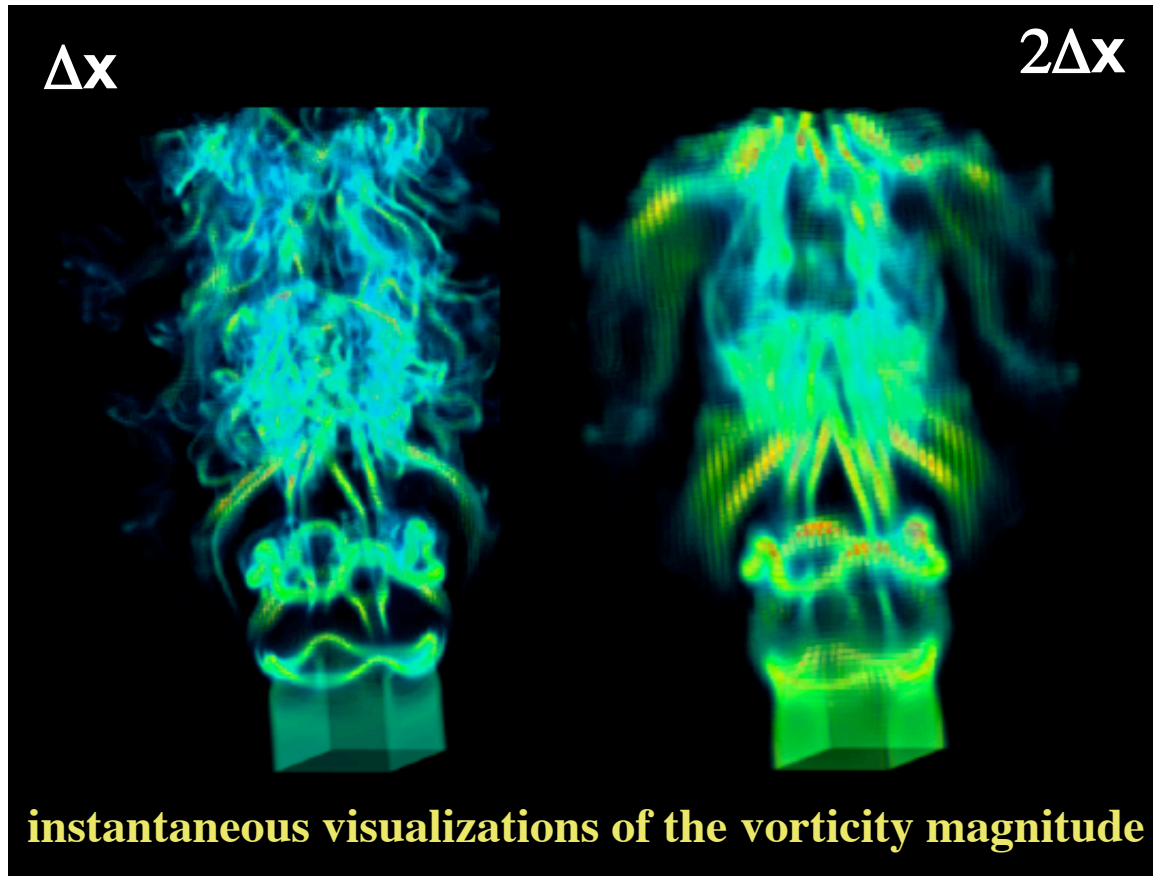
using Zalesak's 2D FCT limiter



using DeVore's 2D FCT limiter

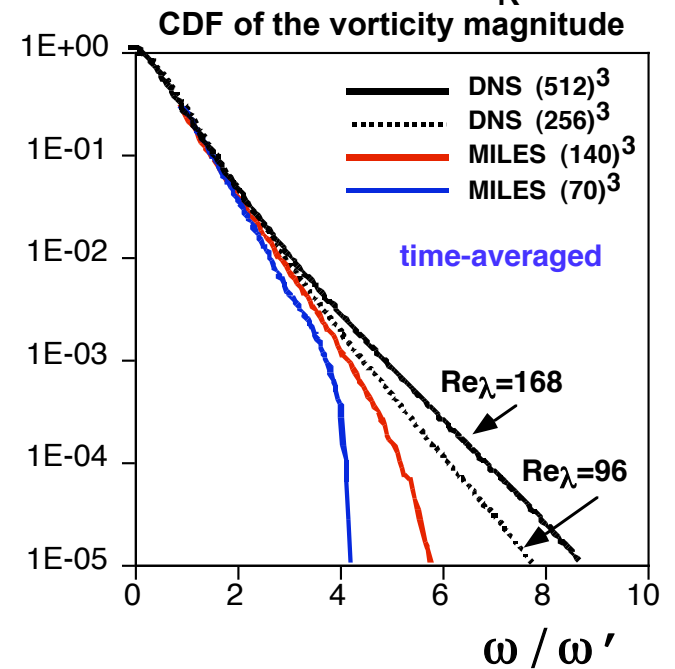
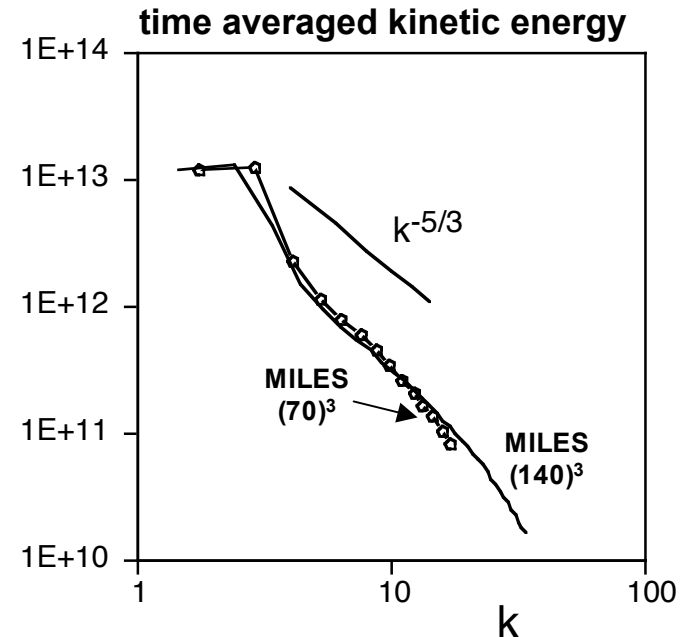


# ILES (or LES) “convergence” ....



FFG & Devore PF '96, FFG JFM '01

- LES “observations” directly affected by (explicit or implicit) filter-length cutoff ...



## Some Open Issues of ILES based on NFV schemes

- *relevant differences / similarities*
  - *flux-limiting vs. upwinding*
  - *interplay between discrete & continuous equations*
  - *scale separation, filtering analogues*
- *building physics into scheme to improve on*
  - *global performance, dissipation & backscatter*
- *dependence on algorithm specifics (the ILES “knobs”), e.g.,*
  - *flux limiter, low & high order schemes, gridding*

## Challenges and Directions for Future ILES Development

- *appropriate theoretical framework (ME, ...)*
- *a priori vs. a posteriori tests: what’s meaningful for ILES ?*
- *effective “mixed” explicit / implicit SGS modeling of small-scale driven mixing & combustion, stochastic backscatter (inherently difficult for all LES !)*

# Implicit LES

## Recent Background

### Invited Special Sessions

“VLES”, 2001 ECCOMAS, Swansea UK

--> **special section of 2002 IJNMF**

“Alternative LES”, 2002 AIAA-ASM, Reno NV

--> **special section of 2002 ASME JFE**

“ILES”

2003 CSE-SIAM, San Diego CA

2003 AIAA-CFD, Orlando FL

2004 IGPP-CNLS LANL Workshops

--> **Cambridge UP ILES Book, 2006**

# **IMPLICIT LARGE EDDY SIMULATION: COMPUTING TURBULENT FLUID DYNAMICS (Cambridge University Press, 2005-2006)**

## **Editors:**

**Fernando F. Grinstein, Len Margolin, and Bill Rider**

## **INTRODUCTION**

### **SECTION A - MOTIVATION**

- 1. Historical Introduction (Boris)**
- 2. ILES for Turbulent Flows: A Rationale (Grinstein, Margolin, Rider)**

### **SECTION B - CAPTURING PHYSICS WITH NUMERICS**

- 3. Subgrid Scale Modeling: Issues and Approaches (Sagaut)**
- 4. Numerics for ILES**
  - a. Limiting Algorithms (Drikakis, Grinstein, Fureby, Youngs)**
  - b. Piecewise Parabolic Method (Woodward, Porter)**
  - c. Lagrangean Remap Method (Youngs)**
  - d. MPDATA (Smolarkiewicz, Margolin)**
  - e. Vorticity Confinement (Steinhoff)**
- 5. Numerical Regularization (Rider, Margolin, Fureby)**
- 6. Approximate Deconvolution (Adams, Domaradzki)**

### **SECTION C - VERIFICATION AND VALIDATION**

- 7. Homogeneous Turbulence (Woodward, Porter)**
- 8. Vortex Dynamics and Transition to Turbulence (Grinstein)**
- 9. Instabilities and Symmetry Breaking (Drikakis)**
- 10. Incompressible Wall Bounded Flows (Fureby)**
- 11. Compressible Turbulent Shear Flows (Knight, Adams, Fureby)**
- 12. Studies Based on Vorticity Confinement (Steinhoff)**
- 13. Rayleigh-Taylor and Richtmyer Meshkov Mixing (Youngs)**

### **SECTION D - FRONTIER FLOWS**

- 14. Studies of Geophysics (Smolarkiewicz, Margolin)**
- 15. Studies of Astrophysics (Porter, Woodward)**
- 16. Complex Engineering Turbulent Flows (Fureby)**
- 17. Large Scale Urban Simulations (Patnaik, Grinstein, Boris)**

## Bibliography

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