1	ELECTRIC MOTOR WITH NONMOTOR	568
	DRIVING MEANS (E.G., AXLE	
	DRIVE, MANUAL DRIVE)	568
2	.Manual driving means	568
3	WITH PARTICULAR MOTOR-DRIVEN LOAD	
	DEVICE	568
4	.Plural, diverse or diversely	
	controlled load device	568
5	Plural motor drive	
6	.Tension-maintaining type of	
0	motor-control system	568
7	Plural, diverse or diversely	568
,	controlled motors	
8	.Plural, diverse or diversely	568
0	controlled driving motors	
	(e.g., driving differential	
	gearing)	
9	.Power- or motion-transmitting	
J	mechanism	568
10	Reversible drive mechanism	
10		
	Variable speed mechanism	568
12	Gearing	
13	Differential type	568
14	Motion-converting mechanism	
15	Mechanical gearing	568
16	SUPPLIED OR CONTROLLED BY SPACE-	000
	TRANSMITTED ELECTROMAGNETIC OR	
	ELECTROSTATIC ENERGY (E.G., BY	568
	RADIO)	569
17	PORTABLE-MOUNTED MOTOR AND/OR	570
	PORTABLE-MOUNTED ELECTRICAL	571
	SYSTEMS THEREFOR	572
560	POSITIONAL SERVO SYSTEMS (E.G.,	572
	SERVOMECHANISMS)	E 7 -
561	.Adaptive or optimizing systems	573
	including "bang-bang" servos	574
562	.Time-sharing or multiplexing	
	systems	575
563	.With protective or reliability	576
	increasing features (e.g.,	
	"fail-safe" systems)	577
564	"Redundant" operating channels	
565	Monitoring systems	578
566	Maneuver, force, or load-	579
	limiting	580
567	.Program- or pattern-controlled	
	systems	581
568.1	With program recording or	582
	composing means	583
568.11		584
	(i.e., Robot)	585
568.12		586
		585

568.13	With particular program teaching method
568.14	Manual lead through
568.15	With particular interpolation
200.12	means
568.16	
200.10	With particular sensing device
568.17	
300.17	With multimode control (e.g.,
	course-fine, position-force,
FC0 10	etc.)
568.18	Including velocity control
568.19	With particular coordinate
	transformation means
568.2	With plural control systems
	(e.g., the interaction of
	plural processors to control
	the plural joints of a single robot):
568.21	,
300.21	<pre>Including end effector (e.g., gripping jaw,</pre>
	micromanipulator, etc.)
568.22	With particular compensation
500.22	(e.g., gain, offset, etc.)
568.23	Including program
500.25	modification
568.24	With reliability enhancement
000121	means (e.g., monitoring,
	redundant circuits, etc.)
568.25	Including display device
569	Digital or numerical systems
570	Contouring systems
571	With "feed-rate" control
572	With "zero-offset" or tool
-	radius correction
573	With interpolating means
574	Multiple axes point to point
	systems
575	Multiple axes analog systems
576	Nonmechanical line, seam or
	edge followers
577	Optical or photoelectric line
	followers
578	Cam or template followers
579	Multiple pass systems
580	.Vehicular guidance systems with
	single axis control
581	Radio-controlled
582	Celestial navigation
583	Landing systems
584	Altitude or pitch control
585	Roll control
586	Yaw control
587	Land vehicles

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588	Marine vehicles	625	.Plural servomotors
589	Submarine and torpedo systems	626	.Limit or end-stop control
590	.Multiple mode systems	627	Secto-scanning systems
591	With mode-engagement features	628	."Feelback" systems
	(e.g., manual to automatic)	629	.Unwanted harmonic or voltage
592	Fine and coarse systems		component elimination
593	Separate fine and coarse		quadrature rejection systems
	motors	630	.Antibacklash systems (e.g., with
594	Digital systems		unidirectional approach to
595	Multiple speed synchro systems		balance)
596	Combined "on-off" and	631	.Antistatic friction features
000	proportional control		(e.g., "dither" voltage)
597	Slewing systems	632	.With compensating features
598	With a separate slewing motor	633	"Two-cycle error" compensation
599	.Pulse-width modulated power	634	Temperature compensation
	input to motor (e.g., "duty	635	.With signal-, voltage-, or
	cycle" systems)	035	current-limiting
600	.Digital or numerical systems	636	."Sampling" systems including
601	Digital comparison	050	miscellaneous "sampled data"
602			control systems
602	Commutating switch-type encoder	637	Analog computation
603		638	.With particular "error-
	Pulse-counting systems	050	detecting means
604	Analogue comparison	639	Plural, diverse conditions
605	Synchro or resolver (e.g.,	640	Photoelectric or optical-type
C 0 C	transmitter simulators)	040	measuring instruments
606	.Frequency- or phase-modulated	641	With particular temperature
C 0 17	systems	041	
607	Frequency comparison	(1)	measuring instrument
608	Phase comparison	642	With liquid level measuring
609	."Reset" systems (P.I.)	C 4 2	instruments
610	With rate (P. I. D.) (e.g.,	643	With moisture content or
	reset windup prevention)	CAA	wetness measuring instruments
611	.With stabilizing features (e.g.,	644	With flow measuring instruments
	anti-hunting, damping)	645	With fluid pressure measuring
612	Electric braking near balance	<b>C</b> A <b>C</b>	instruments
	(e.g., dynamic)	646	With force or weight measuring
613	D.C. in A.C. windings	645	instruments
614	Friction-braking near balance	647	With magnetic field measuring
	including magnetic or eddy		instruments
	current brakes	648	With inertial, direction or
615	By auxiliary feedback loop		inclination measuring
616	Rate feedback		instrument
617	Variable rate feedback	649	Stable platforms
618	Tachometer feedback	650	With current, voltage or
619	Variable gain bandwidth		electrical power measuring
620	Nonlinear circuits		instruments
621	Lead or lag networks	651	With acceleration measuring
622	A.C. networks		instruments
623	Load stabilization (e.g.,	652	With particular position
	viscous, magnetic or friction		measuring instruments
	dampers)	653	Magnetic transducers
624	By deadband at null (e.g.,	654	Synchro control transmitter-
	threshold circuits)		transformer systems
		655	With synchro differential

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656	Differential transformer systems	692	.Having induction or "selsyn" type transmitter
657	Linear differential transformer	693	.Having impedance-type transmitter
658	"E" type transformer	694	.Having commutated dynamoelectric
659	"Microsyn" type	094	machine transmitter
660	"Inductosyn" systems	695	.Having commutating switch-type
661		095	transmitter
662	Resolver systems	696	OPEN-LOOP STEPPING MOTOR CONTROL
663	Variable capacitor systems	090	SYSTEMS
003	Potentiometer systems	34	PLURAL, DIVERSE OR DIVERSELY
	including autotransformers and Wheatstone bridges	54	CONTROLLED ELECTRIC MOTORS
664	Minor arc seeking	35	.Motors with diverse motions
665	Continuous rotation,	55	(e.g., reciprocating and
005	unlimited range		rotary motors)
666	Controlled tap and slidewire	37	.Plural reciprocating or
667	With a bridge in the feedback	57	oscillating motors
007	circuit	38	.Plural linear-movement motors
668	Recalibrating systems	39	.Work and feed motors (e.g.,
669	Standing wave	0,0	indexing)
670	Contact resistance	40	.Motor biased against rotation
671	With particular motor control	41	.Having electrical synchronizing
071	system responsive to the	11	interconnections
	"actuating signal"	42	Between windings on auxiliary
672	Discontinuous or "on-off"		dynamo-electric machines
072	control	43	D.C. or A.C. commutator motors
673	Seeking switch type		with slip rings
674	Wheatstone bridge type	44	Between induction motor
675	One transmitter or controller		secondaries
0,0	element follows another	45	.Mechanically coupled in fixed
676	Transmitter or controller		ratio of movement
0,0	element returned (e.g., force	46	Motors having unlike operating
	balance systems)		characteristics
677	With particular servoamplifier	47	Synchronous and nonsynchronous
678	Differential amplifier		motors
679	Diverse types of amplifiers in	48	Mechanically coupled in torque
	different stage		opposition
680	Magnetic servoamplifiers	49	.Motors electrically connected in
681	Solid-state servoamplifiers		cascade or tandem
682	Rotating amplifier (e.g.,	50	With means for effecting other
	"Ward Leonard" control)		motor interconnections
683	With particular phase	51	.Plural, diverse motor controls
	discriminator		for different motors
684	With particular modulator or	52	.Slipping and/or racing control
	detector (e.g., choppers)		for electric motors
685	"Step-by-step" motors in	53	.Plural, diverse motor controls
	closed-loop servos	54	Motor-reversing
686	Reciprocating or oscillating	55	With running-speed control
	motors	56	And braking
687	Linear movement motors	57	And braking
688	Shaded pole motors	58	And acceleration control
689	TORQUING MOTORS	59	Running-speed control
690	SELF-SYNCHRONOUS TYPE OF MOTOR	60	And braking
691	.With means to amplify	61	And acceleration control
	transmitter signals		

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62	And automatic starting and/or stopping and/or with time delay	92	Control of both armature (or primary) and field (or secondary) circuits
63	Braking	93	Series-parallel connected
64	Acceleration control		armature or primary circuits
65	.Motor-reversing	94	Armature or primary circuit
66	.Running-speed control		control
67	Diverse speeds for different	95	Series-parallel connections
07	motors	96	With armature circuit
68	Relative motor speed control		impedance
69	With speed-difference detector	97	Field or secondary circuit
70	Electrical-type detectors	2	control
70	Voltage and/or current	98	Load control
/ 1	difference detector	99	Fixed ratio of load or current
72		<i></i>	division
12	Dynamoelectric machine detector	100	
<b>P</b> 2		TOO	By field or secondary circuit control
73	Synchronously operated	101	
	impedance detectors	101	.Starting and/or stopping
74	Synchronously actuated	102	Sequential or successive
	switch detectors	100	starting and/or stopping
75	Plural switches connected	103	Selective starting and/or
	in series		stopping
76	Differential-gearing detector	104	Armature (or primary) circuit
77	Controlling motor speed in		control
	response to speed of another	105	.Plural, diverse or diversely
	motor		controlled sources of armature
78	Controlling A.C. frequency or		(or primary) supply
	rate of electrical impulses to	106	Diverse sources
	other motor	107	A.C. and D.C.
79	Control of both armature (or	108	Different voltages
	primary) and field (or	109	Different voltages
	secondary) circuits	110	Different frequencies
80	Armature or primary circuit	111	.Series-parallel connected motors
	control	112	.Parallel connected motors
81	Field secondary circuit	113	.Series connected motors
	control	114	IMPACT, MECHANICAL SHOCK, OR
82	Armature or primary circuit	<b>T T T</b>	VIBRATION-PRODUCING MOTORS
-	control	115	MOTOR WITH DIVERSE MOTIONS (E.G.,
83	Series-parallel armature	115	ROTARY AND RECIPROCATING)
00	circuit connections	116	NONMAGNETIC MOTOR
84	Field or secondary circuit		
04	control	117	.Thermoelectric motor
85	.Synchronizing or phasing control	118	MAGNETOSTRICTIVE MOTOR
86		119	RECIPROCATING OR OSCILLATING
	.Braking	100	MOTOR
87	Motor used as braking generator	120	.Stopping after predetermined
0.0	(dynamic braking)		number of reciprocations or
88	Load or current division		cycles (including single
	during braking		cycle)
89	Motor as exciter for another	121	.Having means to produce a
	motor		progressing or traveling motor
90	.Acceleration control		field flux
91	Accelerating motors in	122	.Plural, diverse or diversely
	succession or selectively		controlled motor windings

123	Polyphase or diverse or diversely controlled sources	150	.With flywheel on generator or on motor
104	of motor supply	151	.Control of both the generator
124	A.C. and D.C. sources	150	and the circuit to the motor
125	Unidirectionally conductive	152	With motor control
100	devices in energizing circuit	153	.Control of both the generator
126	.Energizing winding circuit		and the motor
	control	154	Control of excitation (field)
127	Automatic in response to		circuit of both
	predetermined position,	156	.Plural, diverse or diversely
	movement or condition in or of the motor or driven device		actuated, generator control
100		4	means
128	Noise, sound, vibration,	157	.Generator speed control
100	movement or position of motor	158	.Generator field circuit control
129	By means for producing periodic	159	HAVING ROTOR ELEMENT BIASED
	electrical pulses in the		AGAINST ROTATION
120	energizing circuit	160	.By resilient biasing means
130	Electrical oscillation or		(e.g., spring)
	condenser charging and/or	161	WITH FLYWHEEL OR MASSIVE ROTARY
131	discharging circuits		MEMBER
TOT	Motor or escapement-controlled means	162	CONTROL BY PATTERNS OR OTHER
132		1.60	PREDETERMINED SCHEDULE MEANS
132	By space-discharge or	163	.Motor running-speed control
	unidirectionally conductive devices in energizing circuit	164	Cyclically varying or repeated
133	By impedance devices in		speed schedules
TJJ	energizing circuit	700	SYNCHRONOUS MOTOR SYSTEMS
134	By circuit making and/or	400.01	.Brushless motor closed-loop
134	braking devices		control
135	LINEAR-MOVEMENT MOTORS	400.02	Vector control (e.g., dq-axis
136	AUXILIARY MEANS FOR PRODUCING		control, 3-2 phase conversion,
100	MECHANICAL STARTING OR	400 00	etc.)
	ACCELERATING TORQUE	400.03	Plural reference comparison
137	.By auxiliary motor		(e.g., reference changes
139	BATTERY-FED MOTOR SYSTEMS		during startup, upper/lower
140	GENERATOR-FED MOTOR SYSTEMS	400.04	reference, etc.)
THO	HAVING GENERATOR CONTROL	400.04	Specific processing of feedback
141	.Automatic generator control and/		signal or circuit therefore (i.e., A-D conversion,
<b>T T T</b>	or with time-delay means		compression, or modification)
142	Responsive to diverse	400.05	With reference signal
142	conditions or with time-delay	400.05	generation (e.g., from
	means		external system, mechanical
143	Plural electrical conditions		oscillator, etc.)
144	Armature or primary current of	400.06	Comparator circuit or method
111	motor	400.07	Plural diverse feedback (e.g.,
145	Terminal voltage or counter	100.07	torque and speed, load and
115	e.m.f. of motor		speed, etc.)
146	Speed of motor or driven device	400.08	With nonmotor parameter or
147	Speed of frequency of generator		remote condition detected
	or its drive means		(e.g., temperature, light,
148	.Alternating-current-motor system		airflow, position of diverse
149	.With plural, diverse or		object, etc.)
147	diversely controlled		-
	generators		

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100 25

400.09	Plural mode control (e.g., open
	and closed loop, starting and
	braking, plural-phase and
	single-phase operation, open
	and closed loop, etc.)

- 400.1 ... With timing or delay
- 400.11 ... With separate starting mode or "ramp-up" mode (e.g., openloop control for startup, startup initialization, etc.)

400.12 ... With table lookup, stored map, or memory table (e.g., speed table, stored current profile, etc.)

- 400.13 ..With timing, delay, or clock pulse counting circuit or generation
- 400.14 ... Phase shifted as function of speed or position
- 400.15 ..With torque or load determination (e.g., by calculation, detection, or estimation, etc.)
- 400.16 .. Control or position information digitally stored on disk (e.g., computer hard drive position detection, etc.)
- 400.17 .. Modification or waveshaping of switching control signal (e.g., switching control input to inverter, etc.)
- 400.18 ..With manual control (e.g., foot switch, surgical tool, etc.)
- 400.19 ...Slew rate control (e.g., slew limiting, etc.)
- 400.2 .. Phase voltage wave-shaping circuit or method (e.g., output from inverter, phase energizing signal, trapezoidal wave, etc.)
- 400.21 .. Having protection means (e.g., switching circuit protection, stall protection, failure to start, "wrong" direction, etc.)
- 400.22 ...Current or voltage limiting (e.g., over-voltage or overcurrent protection, etc.)
- 400.23 .. Torque ripple stabilization or acoustic noise attenuation (e.g., cogging prevention, etc.)
- 400.24 .. Electrical noise attenuation (e.g., EMI, EMR, RFI, etc.)

400.25	Switching noise transient attenuation (e.g., switching error prevention, masking,
	blanking, etc.)
400.26	switching circuit structure or
	component (e.g., inverter,
	bridge circuit, etc.)
400.27	Having both high-side and low- side switching elements for plural-phase motor
400.28	Diverse high side or low side switching
400.29	H-bridge
400.3	Power supply voltage feature (e.g., power supply voltage, Vcc compensation, rectifier circuit, power regulator, auxiliary or secondary power supply, etc.)
400.31	Utilization or dissipation of stored or collapsing field energy (e.g., freewheeling, discharging one winding through another, etc.)
400.32	Sensorless feedback circuit
400.33	Voltage injection detection (e.g., voltage injected at startup to determine position, etc.)
400.34	Electromotive force sensor (e.g., back or counter EMF sensor, etc.)
400.35	<pre>With zero-crossing detection (e.g., polarity reversal,  etc.)</pre>
400.36	With center-tap feedback circuit
400.37	With sensor structure (e.g., tachometer, reed switch, cam- controlled switching, etc.)
400.38	Magnetic field sensor or responsive device (e.g., Hall element, magneto-resistance, etc.)
100 39	Rotating sensor component

- 400.39 ....Rotating sensor component separate from motor structure (e.g., resolver, magnetically sensed rotating disk, etc.)
- 400.4 ... Optical sensor (e.g., encoder, photodetector, etc.)
- 400.41 .. Having specific motor structure (e.g., bifilar windings, airgap dimension, auxiliary winding, phase winding with midtap, etc.)

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400.42	.Brushless motor open-loop control	733	Commutator connected to secondary winding
701	.Hysteresis or reluctance motor	734	Slip rings connected to
	systems		secondary winding
702	.Antihunting or damping	735	Rotor shaft coupled to
703	.Braking		dynamoelectric machine
704	.Pole changing motor winding	736	Slip rings connected to
	circuits		dynamoelectric machine winding
705	.Synchronization systems	737	.Self-cascaded motor windings
706	With armature power removal	738	.With commutated winding
	upon failure to synchronize or	739	.Reversing
	loss of synchronism	740	With diverse motor operation
707	Upon failure to resynchronize	741	With braking
708	Responsive to thermal	742	Electromagnetic brakes
	electrical element in system	743	Generator action
709	Having different armature	744	Plugging
	voltage prior to synchronism	745	
710	With d.c. field removal		reactor in primary circuit
711	With electronic control	746	Two phase motor
	element in system	747	Two phase motor
712	With field excitation	748	With plural primary windings
	application	740	or winding portions having
713	Responsive to slip voltage		common connection
710	frequency in d.c. field	749	Operating from a single phase
	winding	740	source
714	Responsive to armature current	750	Shaded pole motor
715	Responsive to rotor speed or	751	Split phase motor with
710	rotor driven member	751	capacitor interchangeably
716	.Field winding circuits		connected in series with
717	Responsive to a motor condition		either primary winding
718	Induced voltage in field	752	With controlled electronic
110	winding	752	device to provide the series
719	Speed responsive field power		connection
110	sources	753	With de-energizable start
720	.Armature winding circuits	135	winding
720	Responsive to rotor shaft	754	With separate winding or
121	position or speed	734	winding portion energized for
722	Having electronic power		each direction of rotation
122	conversion circuit	755	Automatic current reversal on
702		155	start winding
723	Having variable frequency	756	With controlled electronic
704	supply	750	switch for phase reversal
724	Having a plurality of windings	757	.Braking
705	or winding portions		
725	REPULSION MOTOR SYSTEMS	758	With diverse operation
726	.With added motor winding or	759	Dynamic braking
	convertible to series motor	760	Direct current primary winding
727	INDUCTION MOTOR SYSTEMS	$\nabla C 1$	braking circuit
728	.Repulsion start	761	Rotating rotor controls
729	.Power-factor control		braking current in primary
730	.With plural separately movable	760	winding
504	rotors	762	With a.c. to d.c. conversion
731	.With voltage source connected to	762	circuit
	motor secondary	763	Reversal of power to primary
732	Electronic device controls		winding
	current in secondary circuit	764	Three phase power reversal

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765	Eddy current braking circuits	795	With plural capacitors
766	.Primary and secondary circuits	796	Saturable winding in
767	.Primary circuit control		capacitor run motor circuit
768	Three phase motor operated from	797	Phase splitting using stator
	single phase source		winding mutual inductance or
769	With dynamoelectric converter		saturable winding
770	Dual voltage motors	798	Responsive to motor condition
771	Delta-wye, plural wye, or	799	Responsive to speed or
	plural delta connected primary		rotation phase angle
	windings	800	With controlled power
772	Plural speed		conversion
773	Pole changing	801	Including inverter
774	Single phase motor	802	Responsive to an additional
775	Separate primary running		condition
	winding for each pole number,	803	With controlled a.c. to
	alternately energized		d.c. circuit in inverter
776	Entire primary running		supply
	winding energized for each	804	With controlled magnetic
	running speed		reactance
777	Separate primary running	805	Responsive to motor voltage
	winding for each pole number,	806	Condition responsive
	alternately energized	807	Frequency control
778	Starting control	808	With voltage magnitude control
779	With speed control	809	With voltage phase angle
780	Three phase motor with	005	control
	variable transformer to	810	With voltage pulse time
	initially adjust voltage to	010	control
	motor windings	811	Pluse width modulation or
781	Operating from a single phase	011	chopping
	source	812	Voltage control
782	With protective features	813	With transformer
783	Thermal starting and thermal	814	With impedance control
	overload protection	815	Saturable reactor
784	Impedance for reducing	816	Single phase, split phase
	current during starting	010	motors
	operation	817	With capacitor
785	Start winding removed during	818	.Secondary circuit control
	running operation	819	Open secondary member or
786	By electronic switch	010	portion thereof with means to
787	With transformer for		open or close the circuit
	sensing the run winding		thereto
	current	820	Closed secondary member or
788	With variable temperature	020	member portion with means to
	coefficient resistor in switch		change electrical
	control circuit		characteristics thereof
789	By electromagnetic switch	821	Impedance control of secondary
790	With relay coil in series		circuit
	with main winding	822	Responsive to motor condition
791	By thermal switch	823	Rotor speed or position
792	With variable temperature	020	responsive
	coefficient impedance element	824	Centrifugal force of rotor
793	By centrifugal switch	221	controls secondary circuit
794	Capacitor run motor with		impedance
	different capacitance at	825	Induction motor current
	starting	826	Primary motor current
		-	_ · · · · · · · · · · · · · · · · · · ·

827	Frequency of secondary current	272	With automatic starting and/or stopping
828	Secondary voltage	273	.Motor braking
829	By manual operation	274	With acceleration control
830	.With relatively movable	275	With automatic starting and/or
	cooperating motor parts to		stopping
	control energized motor	276	Acceleration control
831	Axially movable cooperating	270	With automatic starting and/or
031	parts	211	stopping
832	Dual stators, one or both	278	In response to an electrical
012	-	270	
244	angularly movable	070	condition
244	ALTERNATING CURRENT COMMUTATING	279	Automatic stopping means less
0.45	MOTORS		responsive during acceleration
245	.Universal or A.CD.C. motors	280	MOTOR-REVERSING
246	SERIES MOTORS	281	.Periodic- or intermittent-
247	.Convertible for nonseries motor		reversing
	operation	282	In response to movement or
248	.With plural, diverse or		position (e.g., limit of
	diversely connected or		travel) of motor or driven
	controlled sources of e.m.f.		device
249	.Control by motor circuit	283	.Automatic and/or with time-delay
	impedance		means
250	Impedance in series with field	284	With means to delay reversing
	windings and in parallel to		until motor substantially
	armature winding		stops
251	.Field circuit control	285	Instant of, or passage or
252	Plural, diverse or diversely		predetermined time or having
	connected or controlled field		time-delay means
	coils	286	Movement or position of motor
253	HOMOPOLAR OR UNIFORM FIELD MOTORS		or driven device
254.1	SWITCHED RELUCTANCE MOTOR	287	.Armature or primary circuit
	COMMUTATION CONTROL		control
254.2	.Having asymmetric half-bridge	288	Plural, diverse or diversely
255	PLURAL DIVERSE MOTOR CONTROLS	200	controlled armature windings
255	.Motor-reversing	289	Phase-reversal
250	5	290	Selectively energized windings
-	With running-speed control		
258	And braking	291	Armature or primary current
259	And acceleration control	000	reversal
260	And acceleration control	292	By shifting motor brushes or
261	With braking		selecting appropriate set of
262	And acceleration control		brushes
263	With acceleration control	293	Reversing polarity of current
264	With automatic starting and/or		supplied to armature circuit
	stopping	294	Wheatstone bridge type
265	Stopping upon predetermined	295	Potentiometer-controlled
	movement of or position of	296	.Field circuit control
	motor or driven device	297	Plural, diverse or diversely
266	At limit-of-travel of motor		controlled field windings
	or driven device	298	Simultaneous energization
267	Dual control circuits	299	With means for short-
	alternately energized		circuiting a winding
268	.Running-speed control	300	Field-circuit current reversed
269	With braking		
270	And acceleration control		
270 271			
∠ / ⊥	With acceleration control		

### 318 - 10 CLASS 318 ELECTRICITY: MOTIVE POWER SYSTEMS

Class 388 subclasses 800-841 are an integral part of this Class (Class 318), as shown by the position of this box, and follows the schedule hierarchy of this Class, retaining all pertinent definitions and Class lines of this class. Class 388 subclasses 842-860 are an integral part of this Class (Class 318), as shown by the position of this box, and follows the schedule hierarchy of this Class, retaining all pertinent definitions and Class lines of this class.

362	BRAKING
363	."Spotting" or adjustment of
	braking controller during
	coasting
364	.Automatic and/or with time-delay
	means
365	Plural diverse conditions or
	with time delay
366	Condition of motor or driven
000	device
367	Armature or primary current
368	Armature or primary circuit
500	voltage or terminal or counter
	e.m.f. voltage
369	Speed, acceleration, movement
505	or position of motor or driven
	device
370	.Plural, diverse or diversely
570	controlled braking means
371	Including both friction braking
571	"plugging" and/or dynamic
	braking
372	.Friction braking
373	
515	."Plugging" or application of
374	reverse power to motor
574	Energy flow interrupted when motor stops
375	_
376	.Dynamic braking
	Regenerative
377	With additional source of e.m.f.
378	
5/0	In series with armature or
379	primary circuit
	Locally closed armature circuit
380	Closed through impedance or
2.04	the like
381	With field or secondary
	circuit control
382	.By auxiliary electric generator
	or by magnetic attraction or
2.02	repulsion devices
383	"ANTI-BRAKING" OR BRAKING-
	PREVENTION MEANS

430	MOTOR LOAD, ARMATURE CURRENT OR		
	FORCE CONTROL DURING STARTING		
	AND/OR STOPPING		
431	.Initial, "cracking" or "starting		
	from rest" torque control		
432	CONSTANT MOTOR CURRENT, LOAD AND/		
	OR TORQUE CONTROL		
433	.Control of motor load or device		
	driven		
434	LIMITATION OF MOTOR LOAD,		
	CURRENT, TORQUE OR FORCE		
	(E.G., PREVENTING OVERLOAD)		
436	NONRUNNING, ENERGIZED MOTOR		
437	PHASING OR ANGULAR OR LINEAR		
	POSITIONAL CONTROL OF MOVABLE		
	ELEMENT OF THE MOTOR		
438	POWER FACTOR CONTROL OF ARMATURE		
	OR LINE CIRCUIT		
440	HAVING PLURAL, DIVERSE OR		
	DIVERSELY CONTROLLED SOURCES		
441	.A.C. and D.C.		
442	.Different voltages		
443	PERIODIC, REPETITIOUS OR		
	SUCCESSIVE OPERATIONS CONTROL		
	OF MOTOR, INCLUDING "JOG" AND "INCH" CONTROL		
444			
444	.Variable periods or intervals		
445	between controlling operations AUTOMATIC AND/OR WITH TIME-DELAY		
44)	MEANS (E.G., AUTOMATIC		
	STARTING AND/OR STOPPING)		
446	.With nonautomatic control means		
110	(e.g., manual)		
447	.Nonresponsive or less responsive		
	for limited periods		
448	.Anti-hunting		
449	.With respect to a fixed		
	standard, master or reference		
	device		
450	Electrical detector		
451	Mechanically vibrating device		
	as reference device (e.g.,		
	tuning fork)		
452	.Plural, diverse conditions or		

with time-delay means

.. Electrical condition

453

454	Plural, diverse electrical conditions	488	.Responsive to stress in body or material
455	Voltage and current (e.g.,	489	.Responsive to direction,
400	watts)	407	inclination or angular
156			position of bodies
456	.Rate-of-change of a condition	490	-
457	Interia-type detector	490	WITH SIGNALS, METERS, RECORDERS
458	Electrical condition	401	OR TESTING DEVICES
459	.Terminal voltage or counter-	491	CONTROL OF BOTH MOTOR CIRCUIT AND
	electromotive force of		MOTOR STRUCTURE
	controlled motor	492	MOTOR MAGNETIC ENERGY DISSIPATION
460	.Sound, supersonic vibration or	493	CONTROL OF BOTH ARMATURE (OR
	mechanical vibration		PRIMARY) CIRCUIT AND FIELD (OR
461	.Speed or rate-of-movement		SECONDARY) CIRCUIT
462	Centrifugal-type detector	494	ARMATURE (OR PRIMARY) CIRCUIT
463	Tachometer-type detector		CONTROL
464	Electric generator tachometer	495	.Plural, diverse or diversely
465	In excess of a predetermined		controlled, armature or
	valve		primary windings
466	.Movement, position, or limit-of-	496	Polyphase windings
	travel	497	Series-parallel
467	Plural sensing means for	498	Energized or controlled in
207	determining plural positions		predetermined sequence
	or plural limits-of travel	499	Wound or energized in magnetic
468	Limit-of-travel control means		opposition
469	Overloading limit-of-travel-	500	.Plural sources of voltage
±05	type control means		(including counter e.m.f.
470	Magnitude of movement or		cells)
470	revolutions	501	.By shunting armature or primary
1 - 1		301	winding
471	.Responsive to thermal conditions	502	.Variable length or tapped
472	Of motor control means	502	armature winding
473	In or about the motor being	503	.Frequency or pulsation control
4 17 4	controlled	504	.Voltage control
474	.Motor load, armature or primary	504	-
	or secondary circuit current	505	.By means to space-discharge
475	Mechanical-type detector (e.g.,	FOC	devices
	by yielding spring devices)	506	Plural, diverse or diversely
476	In excess of a predetermined		connected or controlled space-
	magnitude		discharge devices
477	Intentionally increased load	507	Having discharge-control means
478	.Electrical conditions in circuit		(e.g., grids)
	other than controlled motor	508	.Impedance-controlled
	circuit	509	Plural, diverse or diversely
479	Voltage		controlled impedances
480	.Radiant energy	510	Including both reactor and
481	.Pressure in a fluid or granular		condenser
	material	511	Inherently or self-variable
482	.Level of fluid or granular		impedance
	material	512	Inductive reactor controlled
483	.Moisture content or wetness	513	Having auxiliary means for
484	.Time or with time-delay means		saturating reactor core
485	Dash-pot or other mechanical	514	Resistor-controlled
	delay means	515	Having short-circuiting means
486	Pilot- or servo-motors	516	Short-circuited step-by-step
487	Electromagnetic or inductive	519	.By armature or primary circuit-
107	time-delay means		making and/or breaking
	STHE GETGY HEGHTD		

## 318 - 12 CLASS 318 ELECTRICITY: MOTIVE POWER SYSTEMS

520	Electromagnetically actuated		
521	FIELD OR SECONDARY CIRCUIT		
	CONTROL		
523	.Plural, diverse or diversely		
	connected or controlled field windings		
524	Convertible number-of-poles		
524	type (e.g., 4-pole or 6-pole)		
525	Differentially wound or		
525	energized windings		
526	Series-parallel		
527	Series field winding		
528	With means to short circuit a		
	field winding		
529	Selectively energized		
530	.Plural, diverse or diversely		
	connected or controlled		
	sources of field circuit		
	voltage		
531	.Variable length or tapped field winding		
532	.By means of space-discharge		
	device in field circuit		
533	.Impedance-controlled		
534	Plural, diverse or diversely		
	connected or controlled field		
	circuit impedances		
535	Wheatstone bridge		
536	.By field circuit making and/or		
	breaking		
537	Intermittently operated		
538	MOTOR STRUCTURE ADJUSTMENT OR		
500	CONTROL		
539	.Both armature and field		
	structures rotatable or		
E40	adjustable		
540 541	.Rotor element movable axially		
541	.Brush or other current-collector control		
542	Having movement toward or from		
J42	cooperating part (e.g., brush		
	lifted from commutator)		
543	THREE-OR-MORE-POSITIONS MOTOR		
515	CONTROLLER SYSTEMS		
544	.With other motor control device		
545	Main line switch		
546	.Plural, diverse or diversely		
	controlled controllers		
547	Plural control stations		
548	.Plural control stations		
549	.Return to "off", "starting" or		
	"neutral" positions		
550	Power-operated controllers		
551	.Knee- or foot-operated		
	controllers		

552	.Power-actuated controllers
553	Separately actuated controller
	contacts
554	Electromagnetic actuated
555	Electromagnetic actuated
556	Reciprocating or oscillating
	electromagnetic means
557	Intermittent or step-by-step
	operation
558	MISCELLANEOUS

# FOREIGN ART COLLECTIONS

#### FOR 000 CLASS-RELATED FOREIGN DOCUMENTS

Any foreign patents or nonpatent literature from subclasses that have been reclassified have been transferred directly to the FOR Collections listed below. These Collections contain ONLY foreign patents or nonpatent literature. The parenthetical references in the Collection titles refer to the abolished subclasses from which these Collections were derived.

FOR 100 SPACE-DISCHARGE-DEVI	SPACE-DISCHARGE-DEVICE COMMUTATED		
MOTOR (318/138)			
FOR 101 SELF-COMMUTATED IMPU	LSE OR		
RELUCTANCE MOTORS	(318/254)		
FOR 102 MOTOR COMMUTATION CON	NTROL SYSTEMS		
(318/439)			

#### DIGESTS

#### DIG 2 WINDSHIELD WIPER CONTROLS