

Recent Progress at NASA in LISA Formulation and Technology Development

Robin Stebbins for the LISA Project at NASA

U.S. LISA Project Scientist

Amaldi 7, Session M7a Sydney, Australia 12 July 2007





Abstract

Over the last year, the NASA portion of the LISA team has been focused its effort on advancing the formulation of the mission and responding to a major National Academy review. This talk will describe advances in, and the current state of: the baseline mission architecture, the performance requirements, the technology development and plans for final integration and test. Interesting results stimulated by the NAS/NRC Beyond Einstein Program Assessment Review will also be described.

BEPAC - Overview and Documents

- The NASA Administrator requested a review of the Beyond Einstein Program (LISA, Constellation X, Black Hole Finder, Joint Dark Energy Mission, CMB Polarization), and a recommendation for which mission would start first.
- The Beyond Einstein Program Assessment Committee (BEPAC) first met in November 2006, and will deliver their report in September 2007.
- The LISA Project, particularly the NASA team, expended ~8 months of effort responding to the BEPAC.
- The response included:
 - 3 BEPAC meetings with two major presentations
 - 4 Town Hall meetings
 - 211 pages answering 71 questions
 - 8 major documents totaling 656 pages

- There is a new "science case" document, available at http://www.lisa-science.org/resources/talksarticles/science/lisa_science_case.pdf
- The science requirements document (ScRD) is the statement of the science that the project intends to perform.
- The LISA International Science Team (LIST) is evolving the ScRD from SNR-based detection to uncertainty in estimation of source parameters from mission data.
- Version 4 of the science requirements document is based on
 - Science Objectives
 - Science Investigations
 - Observational requirements
 - Instrument sensitivity model
 - Validation calculations

Science Requirements

Science Investigation

4.2.1 Determine the relative importance of different black hole growth mechanisms as a function of redshift

Observation Requirement

OR2.1: LISA shall have the capability to detect massive black hole binary mergers, with the larger mass in the range $3x10^4 M_{\odot} < M_1 < 3x10^5 M_{\odot}$, and a smaller mass in the range $10^3 M_{\odot} < M_2 < 10^4 M_{\odot}$, at z = 10, with fractional parameter uncertainties of 25% for luminosity distance, 10% for mass and 10% for spin parameter at maximal spin. LISA shall maintain this detection capability for five years to increase the number of observed events.





[]		Pa	Parameter Uncertainties			
M ₁	M ₂	D _L Uncertainty	Spin Uncertainty	SNR		
1.00E+04	3.00E+02	31.90%	0.012	10.80		
	1.00E+03	34.10%	0.029	18.50		
	3.00E+03	43.20%	0.070	30.90		
	1.00E+04	41.10%	0.115	47.90		
3.00E+04	3.00E+02	28.50%	0.005	14.90		
	1.00E+03	26.80%	0.008	26.40		
	3.00E+03	25.00%	0.016	45.30		
	1.00E+04	24.20%	0.041	79.50		
1.00E+05	3.00E+02	31.70%	0.005	14.60		
	1.00E+03	23.30%	0.006	27.80		
	3.00E+03	20.20%	0.008	46.00		
	1.00E+04	19.30%	0.020	75.00		
3.00E+05	3.00E+03	22.50%	0.016	10.20		

Lang & Hughes

 Lang & Hughes calculation
 Full 2 PN waveform simulation
 Sky and polarization averaged
– 1 and 2 interferometers
– Monte Carlo spins
– Median performance
Parameter Uncertaint

100 Z 50	Distance error distribution 1000 binaries randomly positioned randomly oriented $m_1 = 300 M_{\odot}$ $m_2 = 10000 M_{\odot}$ z = 10	
50		
0	لال محمد میں کر لی ا	3
	$\delta D_{L} / D_{L}$	

F			Parameter Uncertainties			
M1	M ₂	D _L Uncertainty		Spin Uncertainty	SNR	
1.00E+04	3.00E+02	31.9	90%	0.012	10.80	
	1.00E+03	34. ⁻	10%	0.029	18.50	
	3.00E+03	43.2	20%	0.070	30.90	
	1.00E+04	41.1	10%	0.115	47.90	
3.00E+04	3.00E+02	28.	50%	0.005	14.90	
	1.00E+03	26.8	30%	0.008	26.40	
	3.00E+03	25.00%		0.016	45.30	
	1.00E+04	24.2	20%	0.041	79.50	
1.00E+05	3.00E+02	31.1	70%	0.005	14.60	
	1.00E+03	23.	30%	0.006	27.80	
	3.00E+03	20.3	20%	0.008	46.00	
	1.00E+04	19.3	30%	0.020	75.00	
3.00E+05	3.00E+03	22.	50%	0.016	10.20	

Mission Elements and Integration



Mission Design



Bus – "Designed around the Science Complement"



٠

-X







537 r ¥	Propulsion	■µN thrusters				
	ACS	■Star Trackers ■Sun Sensors ■Gyros				
	Comm.	■2 Ka-Band HGAs ■4 X-Band Omni LGAs				
	C&DH	 Flight Proven CPU Standard Serial Bus 				
	Thermal	 Passive Design 				
	Power	 Triple junction GaAs fixed SA Li-Ion Battery 				
	Structures and Mechanisms	 Aluminum Honeycomb Composite 2 mechanisms 				





1			1		
	-	-			

Sciencecraft



Propulsion Module (P/M) / Spacecraft (S/C)



Technologies – µN Thrusters

Prototype thruster emitter testing continuing successfully

- Emitter current stability improvement has been demonstrated, reducing thrust noise and overspray
- Emitter design is compatible with ST7 thruster head to maximize heritage
- We continue to prepare for our long duration test of emitter clogging (Starts in July-August)

Completed testing of first LISA Colloid Micro-Newton Thruster

- Thruster purchased from Busek in Fall of 2005; testing was completed last month
- Evidence for low-energy ion population in exhaust beam verified by independent measurements of beam energy
- Results are critical to understanding accelerator overspray and beam / neutralizer / spacecraft interactions
- Results will be presented at the 2006 Joint Propulsion Conference in July

Completed initial model of bubble formation and collapse in propellant feed system

- Understanding bubble formation and collapse is critical to thruster performance and lifetime



Trade Studies

- Propulsion Module And Launch Stack Configuration: External Structure (Options 1 or 2), Central Structure
- $\sqrt{}$ Getting to orbit: LV options and SEP vs. chemical
- ✓ Propulsion Module As Communication Relay: versus No Communication Relay
- Micro-Propulsion Subsystem: Accommodation to Generate Force-free Moments, Accommodation Using Solar Dynamic Pressure
- ✓ Star Tracker Re-use: Additional STR on Propulsion module, Use Science Spacecraft STR
- ✓ Separation Strategy From Propulsion Module: Separation with spinning SC/Propulsion Module, Non spinning separation
- ✓ Telescope design: Dall-Kirkham (FTR design modified to 40 cm aperture), Ritchey-Chretien, Symmetrized Korsch (Schiefspiegler), Cassegrain
- √ Vacuum Enclosure: Vacuum enclosure, getters, or vent to space
- ✓ Instrument Pointing: Optical assembly pointing, Telescope pointing, In-FOV pointing
- Point-ahead Angle Correction: PAA correction by PM actuation, PAA correction with actuator on Optical Bench, Optical Element(s) in the Science Beam, Optical Element(s) in the Local Oscillator Beam, Rotating the Main Beam Splitter,
- ✓ Point Ahead Actuator Trade-Off
- ✓ Optical Bench Layout: Number and location of optics, height of beam, "Frequency Swap" versus heterodyne with outgoing laser
- 2 Mkm arm option with negation of Earth perturbation and in-field pointing, single optical bench

- ✓ Strap-down System Vs. Direct Proof Mass Reflection*: Proof Mass to Proof Mass measurement, Proof Mass versus Optical bench measurement
- ✓ Electrostatic Readout Vs. Optical Read-out (ORO)*: Optical readout only in sensitive axis, Optical readout also in non-sensitive axis
- Laser Frequency Stabilization: Free-running laser with cavity stabilization, Arm Locking, Higher order/extended arm locking
- ✓ Laser Beam Acquisition: Scanning, Defocusing, Super CCD star tracking
- ✓ Data Transmitted To Ground*: Classical approach, Sending one guadrant and difference to other guadrants
- Perform End-to-End Data Architecture Trade: Ka vs. X, contact time and frequency, power amp, antenna size,steerable dish vs. phased array and interSC comm,
- ✓ Define Strategy for Flat Spot Finding and Calibration at Far Spacecraft
- √ Develop First Cut Avionics and FSW Architectures
- Define Thermal Stability Requirements and Architecture, define interface requirements
- √ *Perform Self-Gravity Zone Definition*
- Magnetic Analysis Zone Definition
- √ Define detailed Arm-Locking requirements
- √ Document 40 cm Telescope Decision: ...to go to 40cm from 30cm
- J Define Top-Level On-Orbit Alignment Concept
- ✓ Define Pointing Mechanism Requirements and Concept (Constellation "Breathing Angle")

Mass and Power Budgets

Element			Mass	; (kg)	
S/C Bus			314		
Payload Mass			259		
Prop Module Mass	· ·		259		
Dry Flight System M	lass		832		
30% Contingency			250		
Dry Mass Total			1082	· · · · · · · · · · · · · · · · · · ·	
Spacecraft Propellan	t Mass and contingency		474		
Wet Mass			1556)	
3 S/C Wet Mass			4668		
LV Adaptor			200		
Total Launch Mass			4868	• • • • • • • • • • • • • • • • • • •	
Atlas 531 Launch ca 0.5 km ² /s ²	apability to the required (C3 =	5165		
Excess lift capability	7		2 9 7	· · ·	
Spacecraft Bus	· · · · · · · · · · · · · · · · · · ·	33	6.2		
	Power	5	0.0		
Со	mmand & Data Handling	4	5.0		
	Comm	6	1.0	-	
	Attitude Control		8.0		
	Micro-Newton Thruston	1 17	7 2		
	Thermal	3	5.0	1	
Pavload		252.7		1	
LOCS		17	3.0]	
LIMAS).7	ר היי היי היי היי היי היי היי היי היי הי	
Sciencecraft Total (W)			8.9		
Total (W)		50	8.9	4	
Total with 30% Marc	ain (W)	76	5.6	4	

Electrical Block Diagram

.



Integration, Verification and Test Plan

- Every requirement must be shown to be met either by measurement, analysis, or "similarity."
- Jeff Livas has developed an extensive plan for the integration and test of the LISA flight system
- Goal: to assess the effects of architecture changes on one of the most challenging phases of the mission
- Main components
 - List of tests
 - Environmental tests
 - Science payload tests
 - Constellation tests
 - Cost database

Step # IV&T flow step

1 Optical Bench Integration 1 Optical Bench Initial Testing

2a GRS Integration 2a GRS Testing

2b GRS and OB Integration 2b GRS and OB Testing

3a Laser System Integration 3b Laser and OB Testing

4 Telescope Integration 4 Telescope Testing

5 LOCS Integration 5 LOCS Testing 5 LOCS acceptance testing

6a LIMAS Integration 6a LIMAS Testing

6b LOCS and LIMAS Integration 6b LOCS and LIMAS Testing 6b LOCS/LIMAS acceptance testing

7a Spacecraft Bus Integration

7b Sciencecraft Integration 7b Sciencecraft Testing

8 Constellation Testing

9a Propulsion Module (PM) Integation 9a PM Testing 9a PM acceptance testing

9b Cruise Module Integration 9b Cruise Module Testing

10 Launch Stack Integration 10 Launch Stack Testing

11 KSC acceptance testing 11 KSC Integration 11 KSC testing

Recent Work Reported in Other Talks

- Phase measurement see presentation by Daniel Shaddock
- Laser sideband locking see poster by Ira Thorpe an Jeff Livas
- Mock LISA Data Challenge see presentation by Matt Benaquista
- Numerical Relativity see presentation by Bernard Kelly

Summary

- The LISA Project has expended a substantial effort supporting the NRC's Beyond Einstein Program Assessment.
- Technology development on micronewton thrusters, phase measurement system, laser stabilization, etc. continues.
- The formulation effort has focused on trade studies and alternate payload architectures.