



**Overview by Ramona Cummings (NASA MSFC)** 

**MSFC** Team:

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Consultant: Lester Cohen (SAO)





### "3" AMSD Concept Designs:



<u>Concept 1</u> Beryllium Mirror; 1<sup>st</sup> Composite Concept(M55J/954-3) 7 actuators (3 tip/tilt/piston actuators +3 simulators on arms, 1 ROC actuator at center)

#### Concept 1 R

Beryllium Mirror; 1<sup>st</sup> Composite Concept(M55J/954-3) 3 bipod actuators (tip/tilt/piston) on strongback, 1 ROC actuator at center tied to bi-pods not RS <u>+ Concept 1 R alternatives</u>



Concept 2 (AC U 2C 19)

ULE Mirror; 2<sup>nd</sup> Composite Concept (M55J/954-3); 16 soft force actuators, 3 bi-pods for displacement



#### Concept 3

Glass (Fused Silica) Mirror; 3<sup>rd</sup> Composite Concept (M55J/954-6); 37 actuators (31 axial force and 6 bi-pod displacements)





Concept	Simulated Items						
	Minor	Reaction Structure	Strong Back	Actuators	Flexures	Vendor Test Fixture	Material Properties at 35 K
1 R (Ball Redesign)	Per Design Dwgs (before acid etch decision)	n/a	Preliminary, sketch info only	Per B/L Design Dwgs so needs insert changes	need updated design	vendor has not released	Extrapolated properties
2 (Kodak)	Per Design Dwgs	Per Design Dwgs	n/a	Per verbal information	Buckling Analysis but no info on varied physical size	vendor has not released	Some extrapolated properties; rest missing
3 (Goodrich)	Per As-Built and Fab'd dwgs and info	Per As-Built and Fab'd dwgs and info	n/a	Per Design Dwgs	Per Design Dwgs	Preliminary Version (Feb 02)	Extrapolated properties
	No suitable information ba	s heen received t	from vendor				
	Only preliminary information has been received from vendor; If design drawing:				, as-built/as-finished data not yet released from vendor		
	All known as-built and as-finished data received from vendor						







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- MSFC, Vendor, and Consultant Teams use a variety of analyzers on AMSD, including
  - Optical Modeling
    - CodeV, ZeMax, IDL
  - Structural Modeling
    - Nastran, Algor, Ansys, Patran
  - Thermal Modeling
    - SINDA, TRASys, Thermal Desktop, TSS, TAK, NEVADA, Nastran
  - Dynamics Modeling
    - Patran





- With the variety of tools used, <u>results</u> rather than models must be compared
- Therefore, specific model verifications and validations with test correlations are required
  - These are as proposed in AMSD Modeling Comparison Plan
    - draft of May 3, 2002 in review with SAO/Lester Cohen
    - final due June 7, 2002
  - Three reviews (schedule TBR) to present and evaluate analytical predictions
    - Late June on all entity and assembly Verifications
    - Late July or early August on all currently identified Validations
    - Late August or Mid-September for added Validations and additional test correlations





- Model Verifications include
  - Conservation of Mass throughout Analyses
  - Structural Analyses
    - Rigid Body Error Check
    - Free Body Error Check
    - Uniform Thermal Soak with Same CTE
  - Thermal Analyses
    - Energy Balance, Temperature Convergence, Unity Form Factor Sums
    - Simple Gradient
    - Uniform Flux
  - Optical
    - RMS, PV, and PSF verifications of idealized model
    - Optical Checkout of idealized model with well defined aberrations
  - Dynamics
    - Modal run for first five out of plane displacements, mirror unconstrained







· Confirmed uniform mirror material properties















1.70+001

1.46+001

1.21+001

9.71+000

7.28+000

4.86+000

2.43+000

8.15-004

NGST

10











#### Validation Use of Models include:

- Static 1g Load on Mirror aligned to Optical Axis
  - Run on the AMSD mirror only, by simply supported edge and by three point support
    - Determine deflection results caused by the self-weight gravity induced sag
    - Should yield symmetrical results for any AMSD mirror
  - Compare FE results to contractor interferograms
- Static 1g Load on Mirror normal to Optical Axis
  - Run analysis of the AMSD mirror only, support by three point mount
    - Look at reasonableness of deflection results caused by the self-weight gravity induced sag
    - Astigmatism and considerable deformation at the mounting points is expected
    - Symmetry of the mirror should preclude need to rotate mirror
  - Compare data collected during mirror fab and polishing to FE results
  - Compare FE results to data collected in the XRCF ambient tests





#### (Validation Use of Models, continued)

- Static 1g Load on Mirror Assembly mounted normal to Optical Axis
  - Run analysis of the AMSD mirror assembly (reaction structure, actuators) in the designed support fixture
    - Determine deflection results caused by the self-weight gravity induced sag
    - Some astigmatism and deformation at the mounting points is expected
    - Symmetry of the mirror should preclude need to rotate mirror
  - Compare FE results to data collected in the XRCF ambient tests and to required contractor FE results
- Backed out static gravity sag on Mirror Assembly mounted normal to OA
  - Run analysis of the AMSD mirror assembly in the designed support fixture with actuator reactions fully backing out effects of gravity on the mirror
    - Compare FE results to test data collected at the XRCF when the actuators are activated for mirror figure correction
    - FE models should yield a residual RMS surface error comparable to the measured residual surface RMS error





#### (Validation Use of Models, continued)

- Actuator Influence Functions
  - Run analysis on the displacement of each actuator attachment point
  - Determine set of actuator influence functions
- Mirror Light-weighting effect on surface figure map, Strehl Ratio, and EE
- Line of Sight Stability at 80 K, 55 K, and 35 K
  - Run analysis of AMSD mirror assembly in the designed support fixture before and after actuator correction for listed stabilized temperatures
    - Compare FE results to test data collected at the XRCF
- Line of Sight Stability at induced thermal gradients
  - Run analysis of AMSD mirror assembly in the designed support fixture before and after actuator correction at TBR induced thermal gradients
    - Compare FE results to test data collected at the XRCF
- Dynamic Analysis of disturbances on AMSD mirror assembly
  - Modal runs for assembly at XRCF ambient then cryo test with chamber and table forcing functions





### **Goodrich Axial Actuators**







### **Goodrich Axial Actuators**

Ti - 0.25mm thick bonded to face sheet (Epoxy not modeled) —

Ti disk 2.5mm thick with zero density (So Actuator CG will not be affected)

Bar element with 7000lbf/in stiffness (Temperature gradient applied will simulate actuator motion)

Ti Actuator Spacers

Point Element at Actuator CG (157grams)



### **Pathfinder Bipod Actuators**







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Ti Actuator Spacers

Point Element at Actuator CG (157grams)





### **Goodrich Bi-Pod Actuators**























- Integration tool in use by the MSFC Team is IODA (Integrated Optical Design and Analysis)
  - Translations
    - ANSYS to Nastran
    - Algor to Nastran
    - ZeMax to CodeV
    - Others
  - Transfer of geometry, displacement, and deformation information to CodeV
    - Accommodates high fidelity Structural Model (100,000's of elements) to same or reduced size Optical Model
  - Macro calls to CodeV
  - Graphical display of predicted and measured results

















NASTRAN generated Surface Deflections extracted and generated in IODA







Code V generated Surface Metrics, extracted and displayed in IODA (PV and RMS)







Code V generated Strehl Ratio, extracted and plotted using IODA macros (mimics Code V plot format)







Code V generated Encircled Energy, extracted and plotted using IODA macros (mimics Code V plot format)







Next speaker:

Larry Craig SBMD Cryo Quilting