

Mission Technology Forum

Section 25

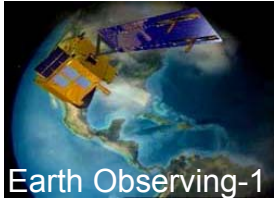
Pulsed Plasma Thruster (PPT)

... Charles Zakrzwski

NASA Goddard Space Flight Center

... Scott Benson

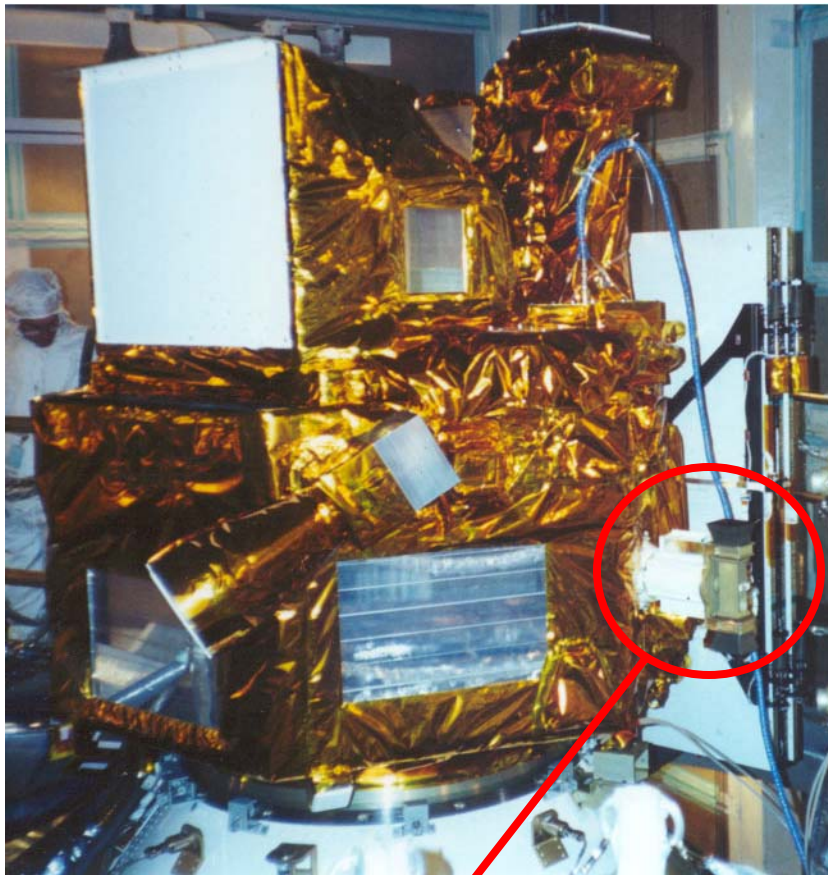
NASA Glenn Research Center



Introduction



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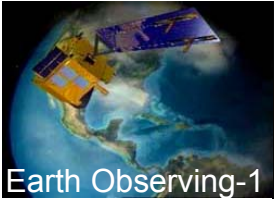
Pulsed Plasma Thruster

◆ Objectives

- **Validate the ability of a new generation of PPT's to provide precision attitude control capability**
 - *PPT replaces pitch wheel/torquer bar*
- **Confirm benign interaction**
 - *Demonstrate imaging capability during PPT operation*
- **Confirm PPT performance parameters**

◆ PPT Team

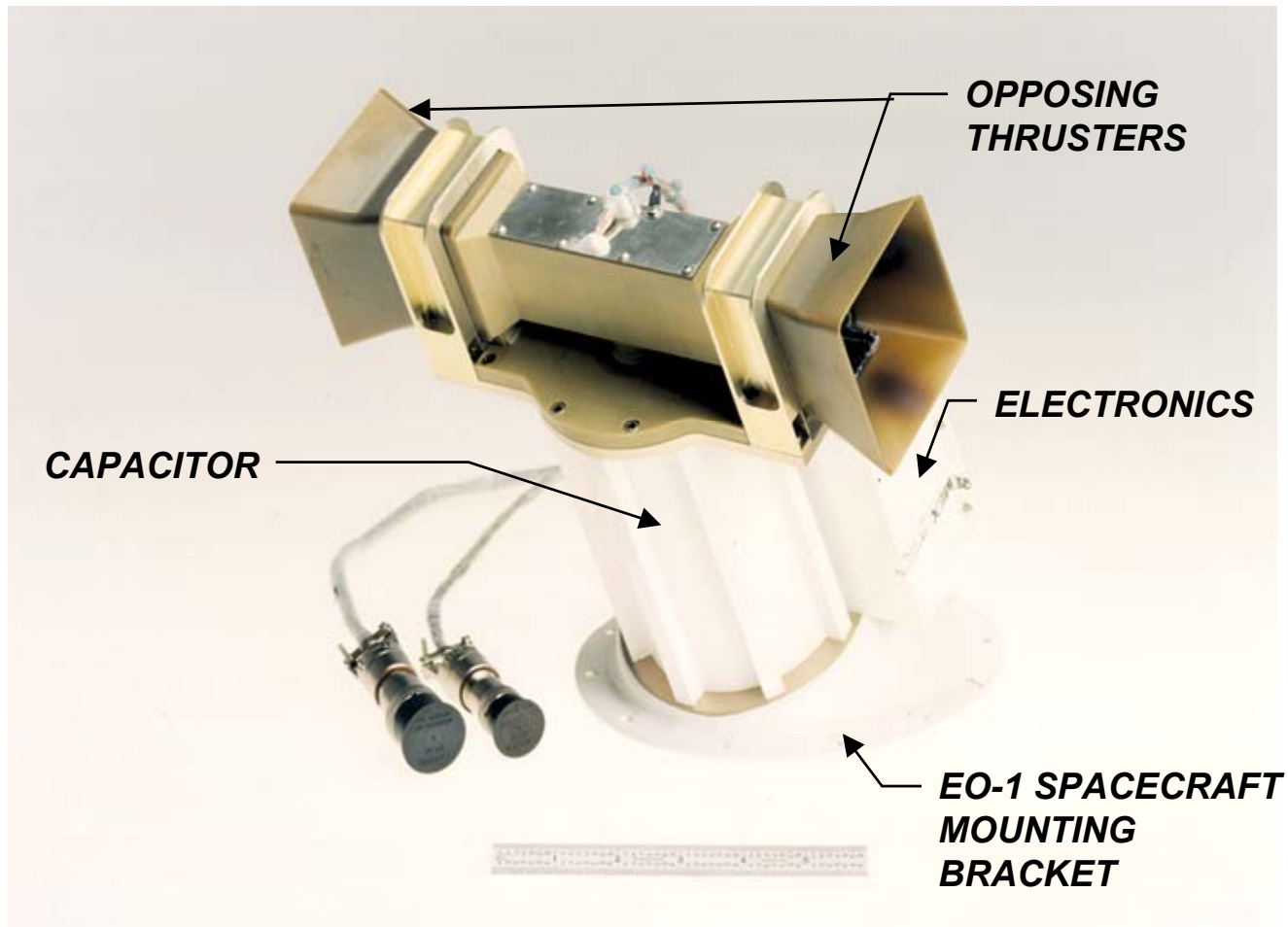
- **NASA/Glenn Research Center**
 - *Scott Benson: (216) 977-7085*
- **General Dynamics Space Propulsion Systems**
 - *Joe Cassady: (703) 271-7576*
- **NASA/Goddard Space Flight Center**
 - *Chuck Zakrzwski: (301) 286-3392*

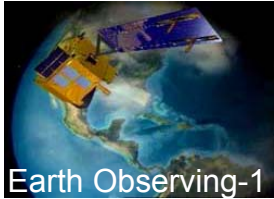


PPT Description (1 of 4)



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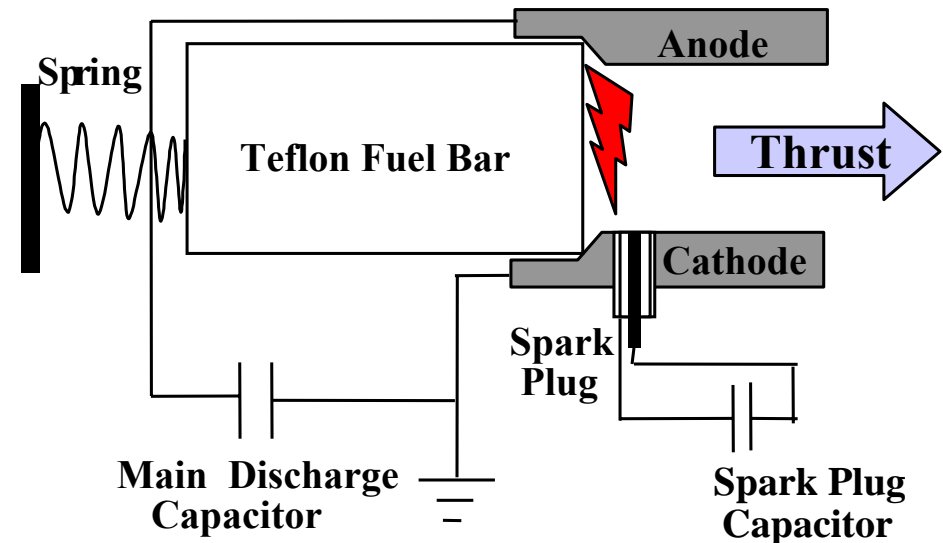


PPT Description (2 of 4)

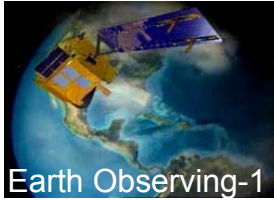


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- ◆ **Small, low power, self-contained electromagnetic propulsion system**
- ◆ **Non-toxic solid propellant: Teflon**
- ◆ **High Isp (650-1350 s), very low I-bit (90-860 $\mu\text{N}\cdot\text{s}$)**
- ◆ **Propellant ablated and ionized by capacitor discharge**
- ◆ **Plasma is accelerated by Lorentz force**
- ◆ **Multiple thrusters can be driven by a common capacitor**



PPT Operation



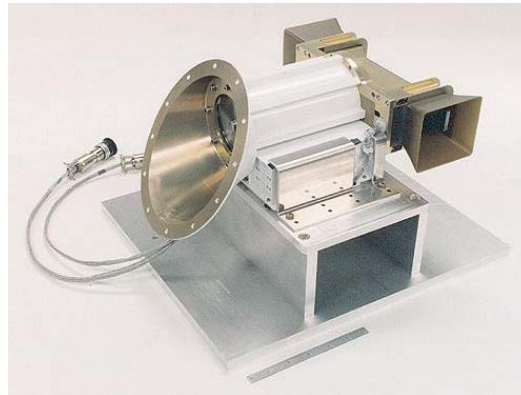
Earth Observing-1

PPT Description (3 of 4)



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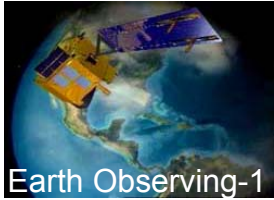
EO-1 PPT (100 W)



Dawgstar PPT (10 W)



Characteristic	EO-1 (Ref. AIAA-99-2276)	Dawgstar (Ref. AIAA-00-3256)
Maximum Input Power	70 Watts (one thruster—EO-1 operations)—100 Watts design	13.1 Watts (two thrusters at once)
Thrusters/System	2	8
Total System Impulse	1850 N-sec (EO-1 propel. load) >15,000 N-sec (system life)	1125 N-sec
Impulse Bit	90-860 μ N-sec, throttleable	56 μ N-sec
Pulse Energy	8.5-56 Joules, throttleable	5 Joules
Maximum Thrust	860 μ N (EO-1); 1.2 mN (design)	112 μ N
Specific Impulse	650-1350 sec	500 sec
Thrust to Power Ratio	12.3 μ N/Watt (System Input)	8.3 μ N/Watt (System)
Total Mass	4.9 kg (2 PPTs, a Power Processing Unit, and fuel)	3.8 kg (8 PPTs, a Power Processing Unit, and fuel)
Propellant	Teflon	Teflon
Propel. Mass (Design)	0.07 kg/thruster (as fueled)	0.030 kg/thruster



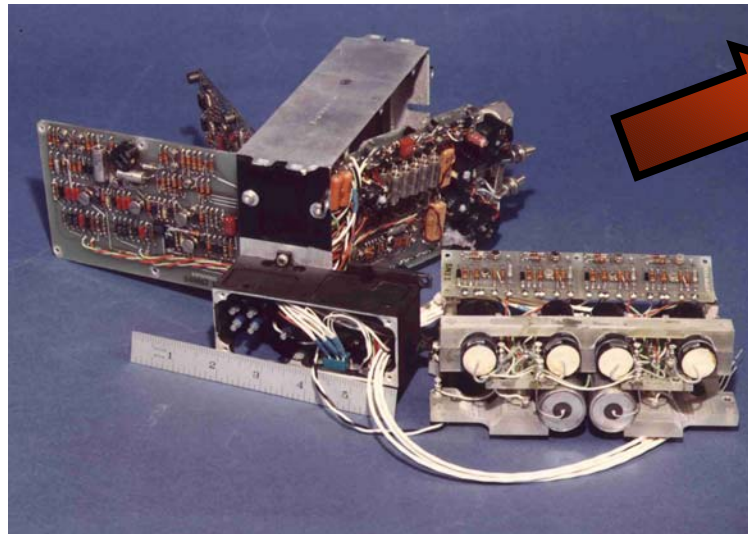
Earth Observing-1

PPT Description (4 of 4)

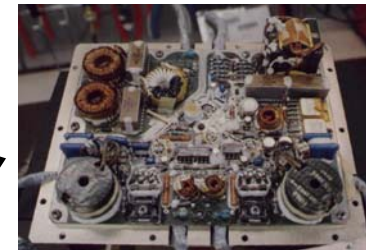


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- ◆ **EO-1 PPT Technology Advancements**
 - **Reduced dry mass from 6.5 to 4.8 kg through cap and electronics reductions [EO-1 PPT mass includes external mounting structure (AIAA 99-2276)]**
 - **EO-1 PPT made significant strides in reducing electronics mass.**

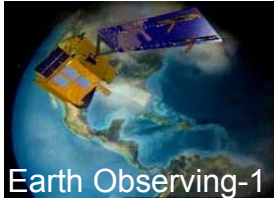


Photos to same scale



**EO-1 Electronics, 750 g
(incl cables and connectors,
but not base plate)**

**LES 8/9 Electronics, 1130 g
(not incl housing shown)**

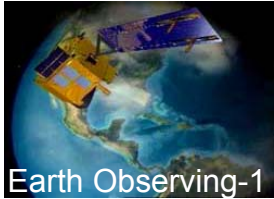


PPT Validation (1 of 5)



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- ◆ **Flight Validation scheduled for October 2001**
- ◆ **PPT Flight unit underwent extensive proto-flight hardware validation/development path**
 - (NASA TM-2000-210340 “Development of a PPT for the EO-1 Spacecraft”)
 - Functionality: Demonstrate range of orbital operations and functionality of test support equipment
 - Performance: Demonstrate performance characteristics
 - Vibration: Acceptance level vibration testing to Delta II levels
 - Thermal Vacuum/Cycle: Demonstrate survival and operations across required temperature range
 - EMI/EMC: Measure characteristic conducted and radiated emissions and evaluate PPT susceptibility to EMI
 - Life/Contamination: Demonstrate thruster life capability through duration of minimum flight experiment. Evaluate plume contamination effects on spacecraft surfaces.
- ◆ **Attitude control capability of PPT confirmed in high fidelity spacecraft simulations**



Earth Observing-1

PPT Validation (2 of 5)



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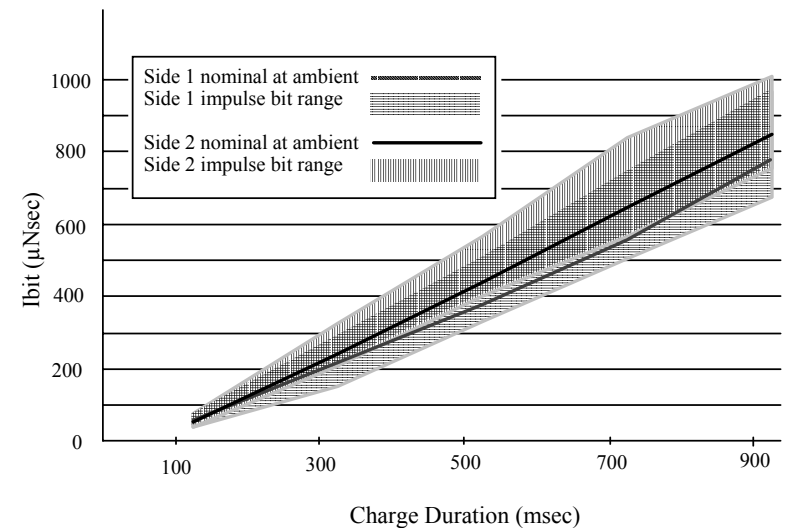
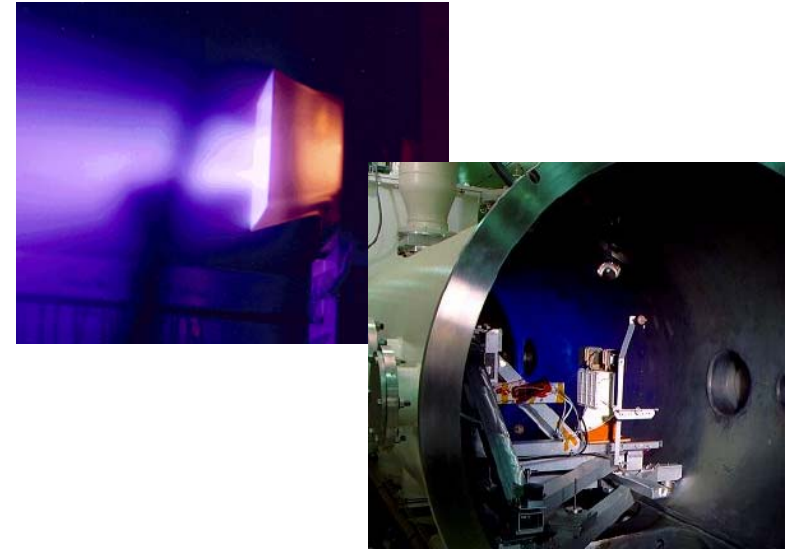
◆ **Functionality**

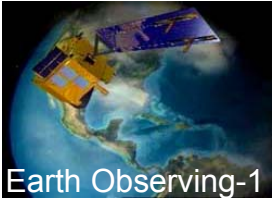
- **Benchmark and vacuum testing**
- **Demonstrate range of planned orbital operations**
 - *Throttling through charge duration control (120 - 920 msec)*

◆ **Performance**

AIAA-99-2290 “Multi-Axis Thrust Measurements of the EO-1 Pulsed Plasma Thruster”

- **Determine thrust and impulse bit across throttle range**
 - *Before and after life testing - no change*
- **Evaluate off-axis impulse bit component**
- **Characterize shot-to-shot repeatability**



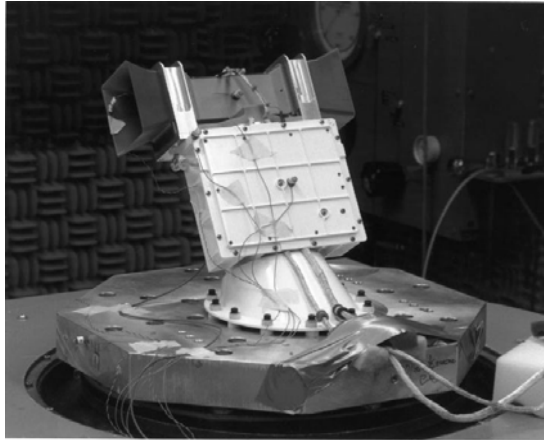


Earth Observing-1

PPT Validation (3 of 5)



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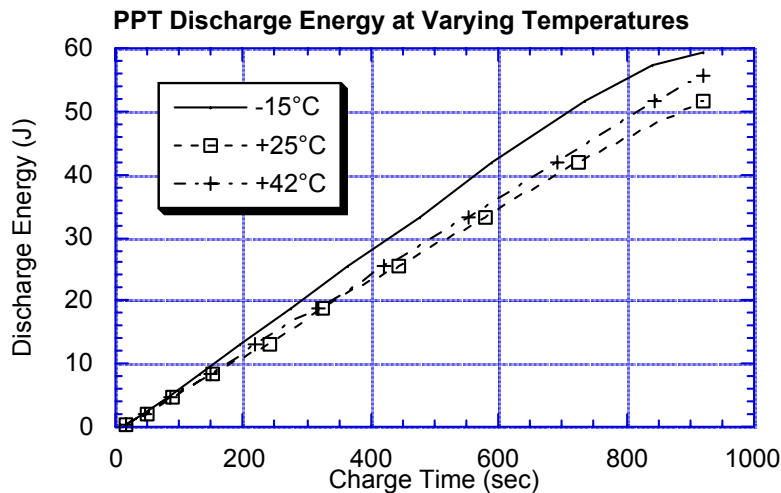


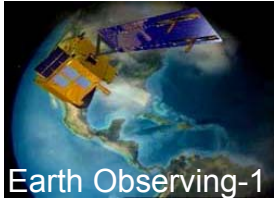
◆ **Vibration**

- **Acceptance level vibration testing to Delta II levels**
 - Random vibration to 14.1 grms on 3 axes

◆ **Thermal Vacuum**

- **Demonstrate survival and operations across required temperature range**
 - -32 to +42°C survival range
 - -15 to +42°C operating range
 - Characterized sensitivity in main capacitor charge rate to temperature
 - Factored into performance results
 - Function of charge duration throttling approach





PPT Validation (4 of 5)



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◆ Life/Contamination

- **Demonstrate thruster life**
 - Minimum experiment life (100,000 pulses/side)
- **Evaluate plume contamination effects on spacecraft surfaces.**
 - Spacecraft surface samples (X-band antenna surface, radiator, MLI)

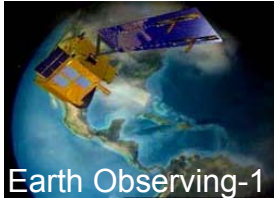
◆ EMI/EMC:

- **Characterised conducted and radiated emissions**
 - Consistent with previous electric propulsion devices
 - RE01, CE01 and CE07 results within spec
 - CE03 limits (conducted emissions) exceed by up to 12 dB below 4 MHz – waiver accepted

- **RE02 broadband radiated emissions exceed levels below 100 MHz**

AIAA 2001-3641 "Addressing EO-1 Spacecraft PPT EMI Concerns"

- **Continuing PPT EMI evaluation at GRC**

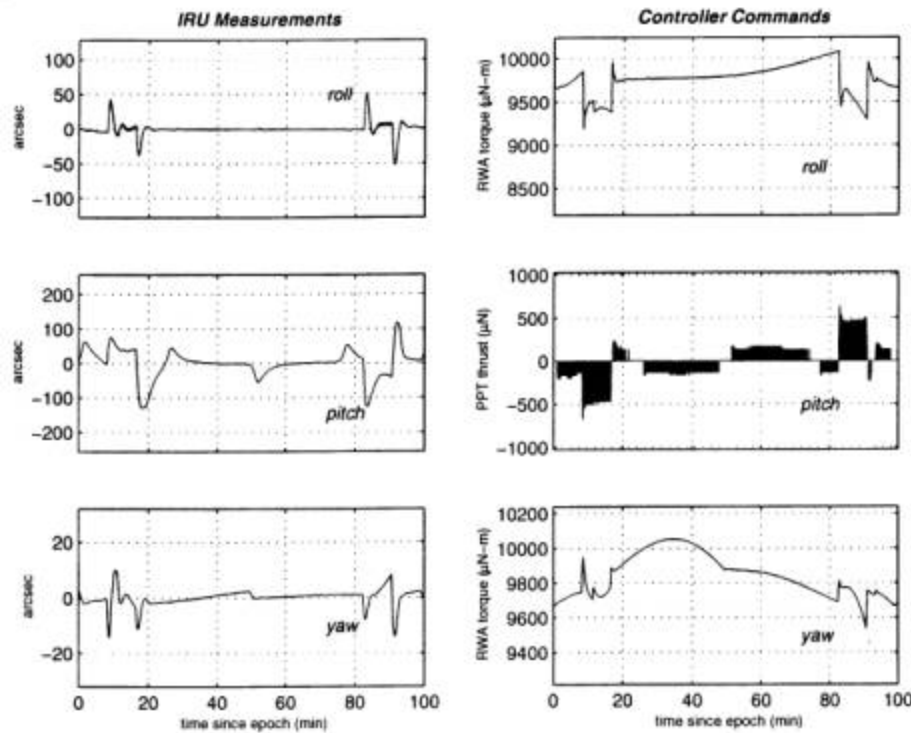


Earth Observing-1

PPT Validation (5 of 5)



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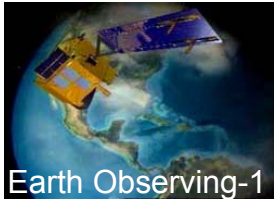
High Fidelity Simulation Results for nominal imaging orbit

◆ Attitude Control Experiment

- **PPT Replaces pitch momentum wheel**
- **Minimum impact to existing ACS architecture**
- **Same PID controller used**
 - Computed pitch torque commands processed for PPT control
 - PID control gains adjusted
- **Pitch wheel speed brought to zero**
 - Pitch magnetic torquer turned off

◆ Simulation Results

- **During imaging mode pointing errors within 5 arcsec requirement**
- **Worst case roll, pitch, and yaw errors: 52.1, 129.3, 14.2 arcsec**
 - Caused by solar array wind/rewind
- **Orbital average power 12.6 W**



Earth Observing-1

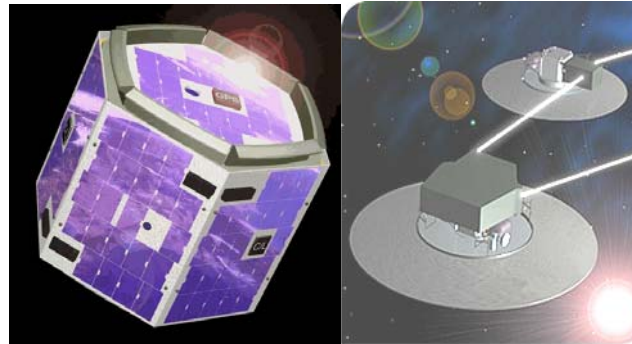
PPT Technology Transfer & Infusion



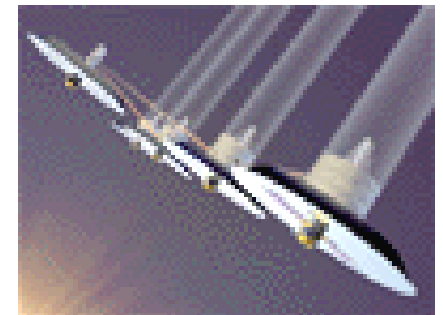
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**Current
(EO-1)**



**Near Term
(DawgStar, StarLight)**

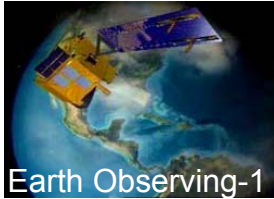


**Far Term
(TPF, MAXIM)**



**Multi-Thruster System Architecture,
Long Life, Low Mass/Volume,
Integration Ease, Specific Impulse, Efficiency,
Thrust-to-Power, Impulse Bit Accuracy**

Continued PPT Technology Development and Improvement



Technology Transfer & Infusion (Mission Applications)



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Formation Flying

◆ Interferometry Missions (Starlight, TPF, Planet Imager)

- Require 1 cm separation control between spacecraft
- PPTs have been leading candidates for these missions due to high precision thrust pulses, high Isp

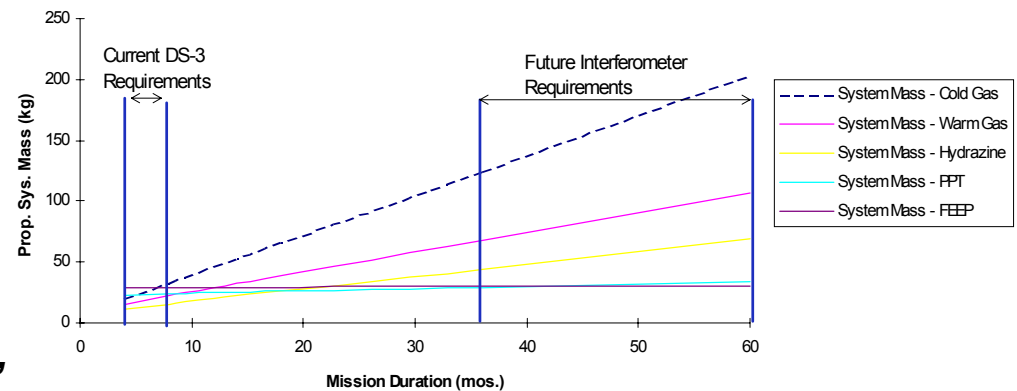
◆ Earth Observing Mission (Techsat 21, Leonardo)

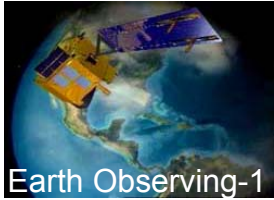
- Air Force and NASA are studying ways to deploy constellations of small satellites in co-orbiting formations
- Typically requires 1 mN - 100 mN of thrust, with capability to generate 0.5 mN - 2 mN-s impulse bit
- PPTs trade well because of small impulse bit, high Isp, and small volume

Precision Pointing (Maxium)

- Fine attitude control for pointing optical instruments

System Mass Comparison





Technology Transfer & Infusion (Mission Applications)



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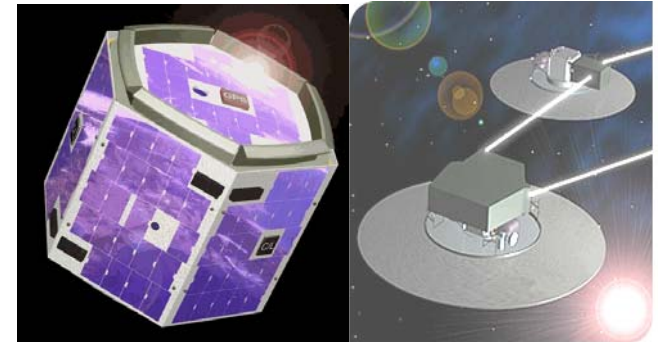
◆ Continuous disturbance reduction

- **Drag free control (GRACE and GPS follow-ons)**
 - Repeatably low thrust range of PPT use to cancel atmospheric drag forces
 - Maintains orbit, improves prediction accuracy
- **Other (TDRSS type GEO missions)**
 - PPTs can cancel disturbance forces to reduce size of attitude control system



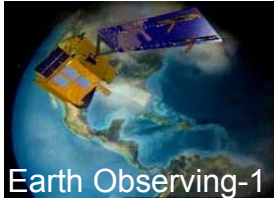
◆ Micro/Nanosats (Dawgstar, MMS)

- **Low mass/volume/power ideally suited for microsats**
- **Simple to integrate, No chemical/pressure hazard**
 - Well suited multiple S/C on a deploer ship and university project



◆ Large Space Structures

- **Used as active control actuators**

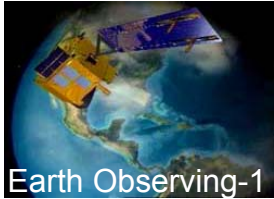


Lessons Learned



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- ◆ ***PPTs can be implemented as attitude control actuators with minimal impact to existing attitude control subsystem architectures***
- ◆ ***Increasing range of PPT thrust would expand the use of PPT as ACS actuators***
 - *On going PPT development efforts are addressing concern by looking at changes to components and changes in operation methods*
- ◆ ***Radiated emission concerns must be addressed earlier in project timeline***
 - *Special test with PPT in bell jar while electrically mated to S/C to confirmed benign effect on S/C bus (without instruments).*
 - *Successful ambient testing with GSE performed with ALI integrated*
 - *Effort to conclusively quantify risk to instruments unit beyond program constraints at time issue was identified*
 - *Most desirable solution for EO-1 would be to test with high fidelity ALI engineering unit*
- ◆ ***Continuing research into PPT EMI reduction leveraging EO-1 experience***
 - *Addressing: lower discharge energies, improved component characteristics, geometry effects, sparkplug characteristics*



Summary / Conclusion



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◆ **Benefits of PPT Technology**

- *Micro impulse capability for precision pointing/positioning*
- *Unique high Isp, low power attributes well suited to small spacecraft*
- *Eliminates distributed, toxic propellant systems*
- *Low mass / power / volume alternative for mission in which both conventional ACS and delta-V systems can be replaced.*

◆ **Applications**

- *Formation flying/precision pointing (Starlight, SAR, TPF, Maxium)*
- *Propulsive attitude and drag free control (Future GRACE/GPS missions, GEO solar disturbances)*
- *Micro/small satellite propulsion (Dawgstar, Techsat 21)*

◆ **EO-1 Flight Validation**

- *EO-1 PPT experiment will validate the capability of a new generation of PPTs to perform spacecraft attitude control*
- *Ground validation tests indicate adequate PPT performance*