

# A Non-Hydrostatic Model to Simulate Atmospheric Flows in the Presence of Orography

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# Outline of Presentation

- Introduction
- Mathematical Formulation
- Numerical Algorithm
- Results
- Conclusion



# Introduction

Mathematical Formulation

Numerical Algorithm

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# Motivation of the Research



# Review of Previous Models

	Advection only	Shallow water equations	Compressible or hydrostatic models
No AMR		Qualitative model: <ul style="list-style-type: none"><li>• wave equation</li></ul>	<ul style="list-style-type: none"><li>• time step restricted by sound/gravity waves</li><li>• terrain following coordinates</li><li>• hydrostatic BVP is not well-posed</li></ul>
AMR	<ul style="list-style-type: none"><li>• mass conservation equation only</li><li>• no orography</li></ul>		Current research: <ul style="list-style-type: none"><li>• time step restricted by advection only</li><li>• EB formulation</li><li>• well-posed BVP for AMR</li></ul>

AMR = Adaptive Mesh Refinement

# Time steps

Typical cell:  $\Delta x = 1.5\text{km}$  -  $\Delta z = 200\text{m}$

Time step limitation	Wave speed, $c$	$\Delta t = \frac{\{\Delta x, \Delta z\}}{c}$
Vertical acoustic waves	343 m/s	$\sim 0.6\text{ s}$
Horizontal gravity waves	200 m/s	$\sim 7.5\text{ s}$
Horizontal advection	20 m/s	$\sim 75\text{ s}$

# Research Objective

- Develop a well-posed boundary value problem for gravitationally stratified flows to use in an AMR framework
- Applications
  - Atmospheric modeling
  - Astrophysics



# Algorithmic Requirements

- Use advective time step

=> Implicit treatment of acoustic and gravity waves

- Adaptive Mesh Refinement (AMR)

=> Well-posed boundary-value formulation of the equations

- Orography

=> Cut-cell methods for irregular boundaries





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# Euler Equations for a Compressible Fluid

Mass conservation

$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \vec{u}) = 0$$

Momentum

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \operatorname{grad}(\vec{u}) + \frac{1}{\rho} \operatorname{grad}(p) + g \vec{k} = \vec{0}$$

Pressure

$$\frac{\partial p}{\partial t} + \vec{u} \cdot \operatorname{grad}(p) + \rho c^2 \operatorname{div}(\vec{u}) = 0$$

# Separating Out the Acoustic Waves: Hodge Decomposition

$$\begin{array}{ccccc} \mathbf{u} & = & \mathbf{u}_d & + & \mathbf{u}_p \\ \text{total velocity} & & \text{incompressible} & & \text{compressible} \\ & & \text{vortical motions} & & \text{motions} \\ & & \text{div}(\mathbf{u}_d) = 0 & & \mathbf{u}_p = \text{grad}(\phi) \end{array}$$

# Separating Out the Acoustic Waves: Projection Method

Incom-  
pressible  
flow and  
advective  
transport

$$\frac{\partial \tilde{\rho}}{\partial t} + \text{div}(\rho \vec{u}) = 0$$

$$\frac{\partial \vec{u}_d}{\partial t} + A_d \vec{u} + \frac{1}{\rho} \text{grad}(\pi) + P_o \left( \frac{1}{\rho} \text{grad} \delta + \frac{\tilde{\rho}}{\rho} g \vec{k} \right) = \vec{0}$$

Acoustic  
equations

$$\frac{\partial \vec{u}_p}{\partial t} + \text{grad} \left( \frac{|\vec{u}_p + \vec{u}_h|^2}{2} \right) + Q_o \left( \frac{1}{\rho} \text{grad} \delta + \frac{\tilde{\rho}}{\rho} g \vec{k} \right) = \vec{0}$$

$$\frac{\partial \delta}{\partial t} + \vec{u} \cdot \text{grad}(\pi + \delta) + \rho c^2 \text{div}(\vec{u}_p) + w \frac{\partial \rho_o}{\partial t} \vec{k} + \frac{\partial \pi}{\partial t} = 0$$

Incompressible flow => semi-implicit formulation

Acoustic waves => implicit formulation

# Separating Out the Acoustic Waves: Projection Method

- Incompressible equations
  - Poisson-like equation for the pressure
  - Explicit treatment of advection
- Acoustic equations
  - Backward-Euler
  - Implicit treatment  $\Rightarrow$  Helmholtz equation for the acoustic pressure

$\Rightarrow$  Well-posed boundary problems for AMR

# Separating Out Fast Gravity Waves

- Isolate incompressible flow and gravity terms

$$\frac{\partial u_d}{\partial x} + \frac{\partial w_d}{\partial z} = 0$$

$$L_z \frac{\partial \pi_H}{\partial t} + \frac{\partial u_d}{\partial x} = f_\rho$$

$$\frac{\partial u_d}{\partial t} + \frac{1}{\rho_o} \frac{\partial \pi_H}{\partial x} = f_u$$

$$\frac{\partial \pi_H}{\partial z} = -\tilde{\rho} g$$

$\rho_o(z)$ : background stratification

$$L_z = \frac{\partial}{\partial z} \frac{1}{g \frac{d\rho_o}{dz}} \frac{\partial}{\partial z}: \text{second order self-adjoint operator}$$

- This set of equations is equivalent to the set of incompressible equations in  $(u_d, \rho)$

# Separating Out Fast Gravity Waves

- Decomposition on eigenvectors

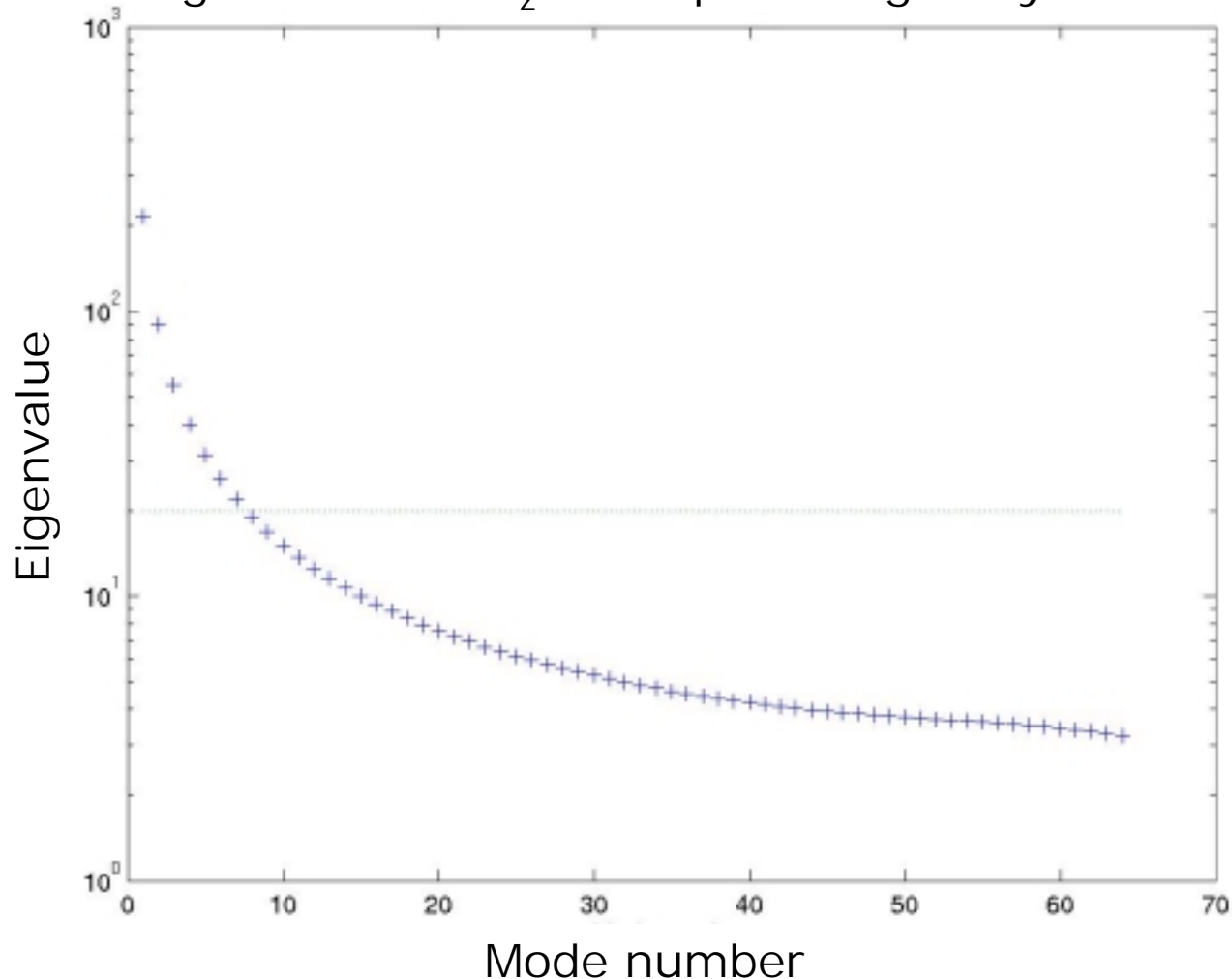
$$\begin{pmatrix} u_d \\ \pi_H \end{pmatrix} = \sum_k \begin{pmatrix} u_d^k(x, t) \\ \pi_H^k(x, t) \end{pmatrix} r^k(z)$$

- $\begin{pmatrix} u_d^k \\ \pi_H^k \end{pmatrix}$  satisfy the wave equation in  $x$  with wave speed  $\lambda_k = \text{eigenvalues of } L_z^{-1/2}$



# Separating Out Fast Gravity Waves

Eigenvalues of  $L_z^{-1/2}$  = speed of gravity waves





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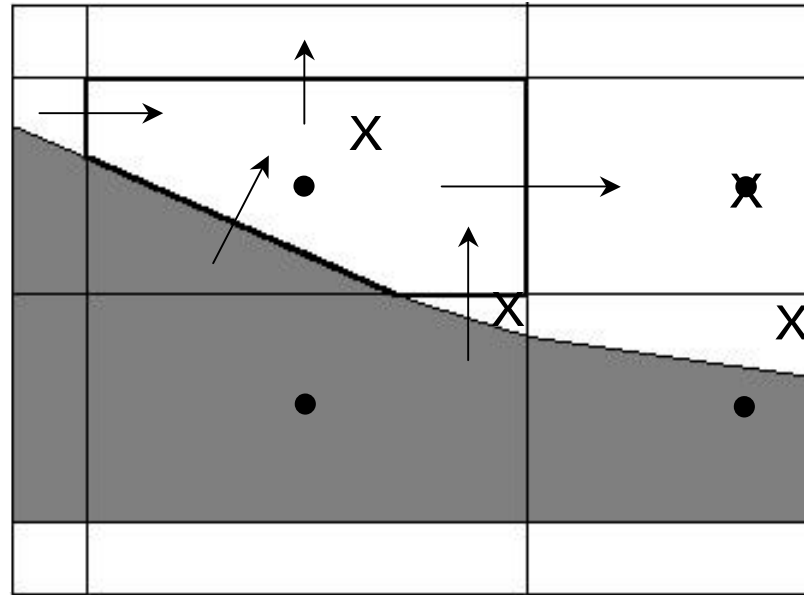
Conclusion

# Overview of the Algorithm

$$\frac{\partial \vec{V}}{\partial t} + \vec{A} \left( \vec{V}, \frac{\partial \vec{V}}{\partial x}, \frac{\partial \vec{V}}{\partial z} \right) = \vec{0}$$

- Implicit treatment of acoustic waves using splitting
- Semi-implicit (explicit for advection)  
for incompressible advection
- Splitting of fast horizontal gravity waves  
from dynamics
- Use embedded boundaries for orography

# Cartesian Grid Embedded Boundary methods



- PDEs written in conservation form

$$\frac{\partial U}{\partial t} + \nabla \cdot \vec{F}(u) = 0 \quad \nabla \cdot \vec{F} \approx \frac{1}{V} \int_V \nabla \cdot \vec{F} dV = \frac{1}{V} \oint_S \vec{F} \cdot \vec{n} dS$$

- Away from boundaries: standard finite-difference discretization

# Cartesian Grid Embedded Boundary methods

Advantages of underlying rectangular grid

- Grid generation is tractable (T. Deschamps' talk)
- Well-understood
- Straightforward coupling to structured AMR

Large aspect ratio (1/10) introduces new issues

- Line solver for multigrid method



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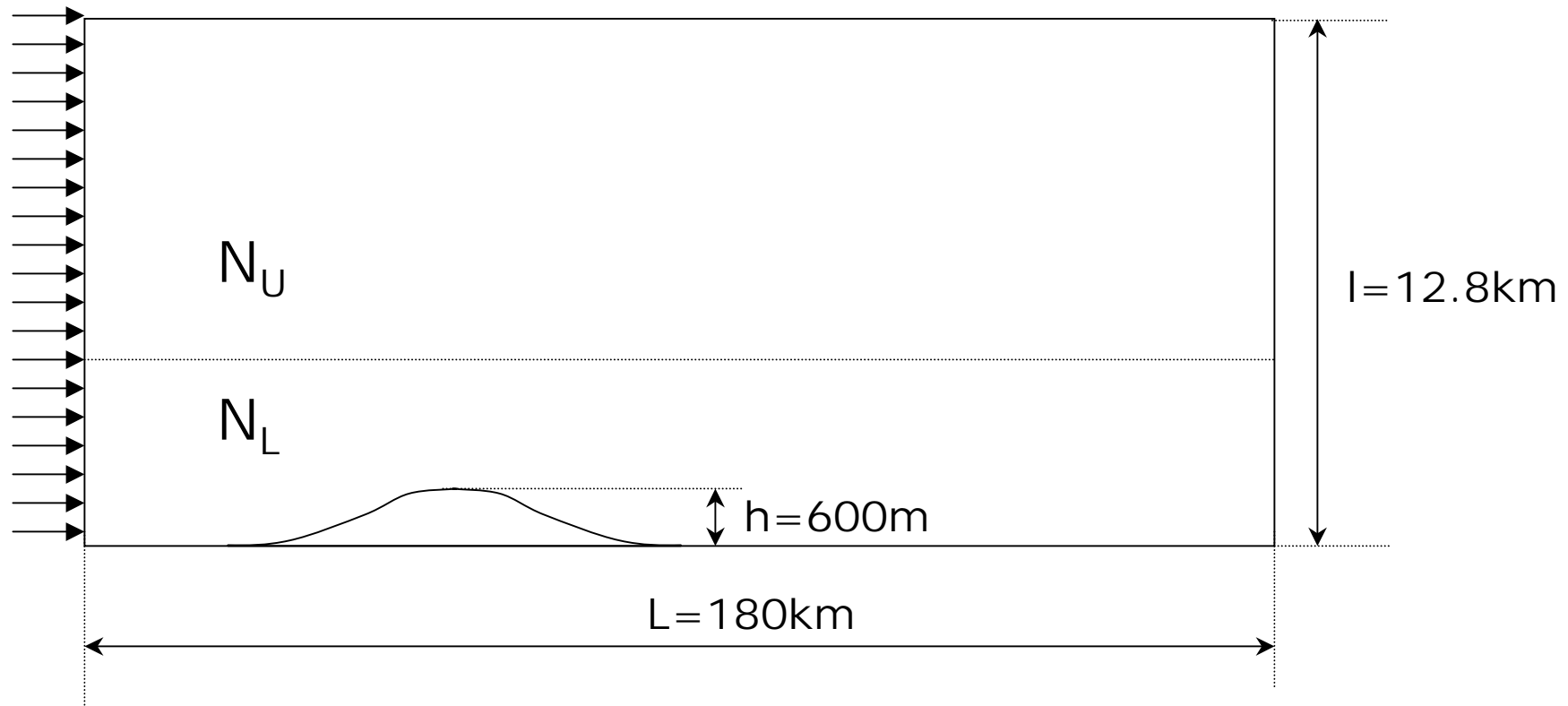
# Results for a 2-Layered Atmosphere

$\Delta x = 1406.25\text{m}$   
 $\Delta z = 200\text{m}$   
 $\Delta t = 5\text{s}$

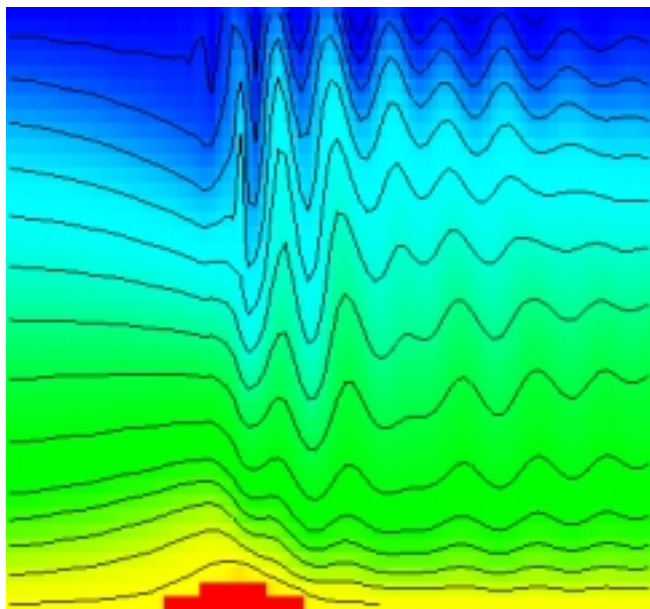
N: Brunt-Väisälä frequency

- $N_U > N_L$ : stable
- $N_L > N_U$ : instable

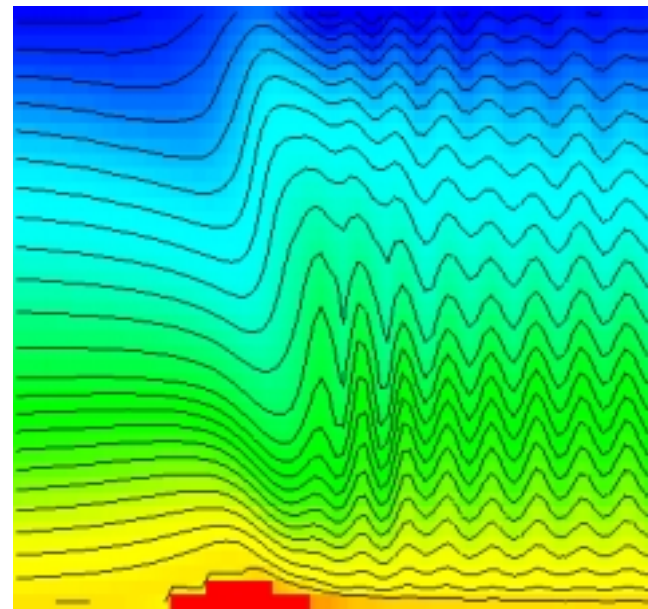
$u_o = 20\text{m/s}$





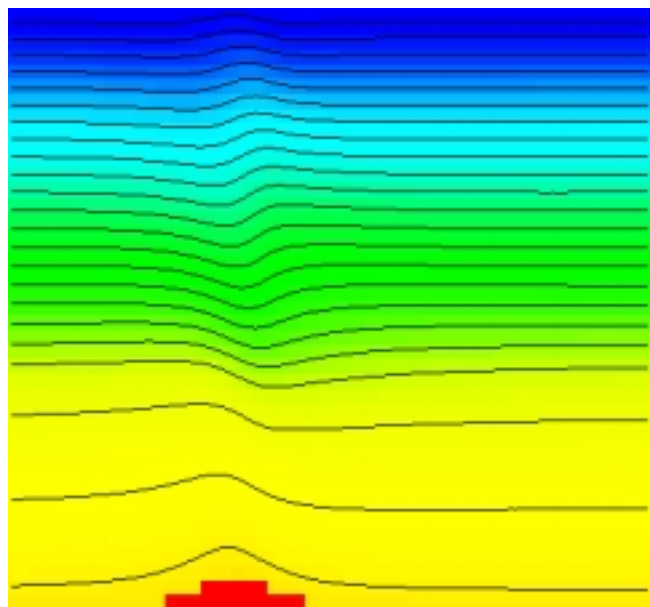


$$N_L > N_U$$

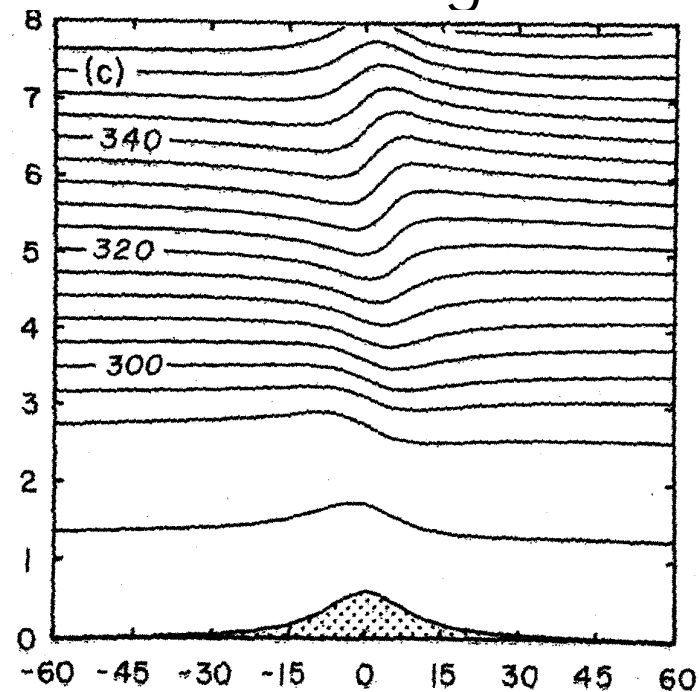


$\frac{1}{4}$  wavelength

$\frac{1}{2}$  wavelength



$$N_U > N_L$$





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# Status and Summary

- Formulation of well-posed initial-boundary problem
  - ✓ Stiff acoustic waves
  - ❑ Still working on implicit treatment of gravity waves
  - ❑ How does 2D implicit gravity waves couple with 3D AMR slow dynamics?
- EB treatment of orography
  - ✓ Good results on mountain lee-waves
- AMR
  - ❑ Not yet, but substantial progress on well-posed boundary-value problem

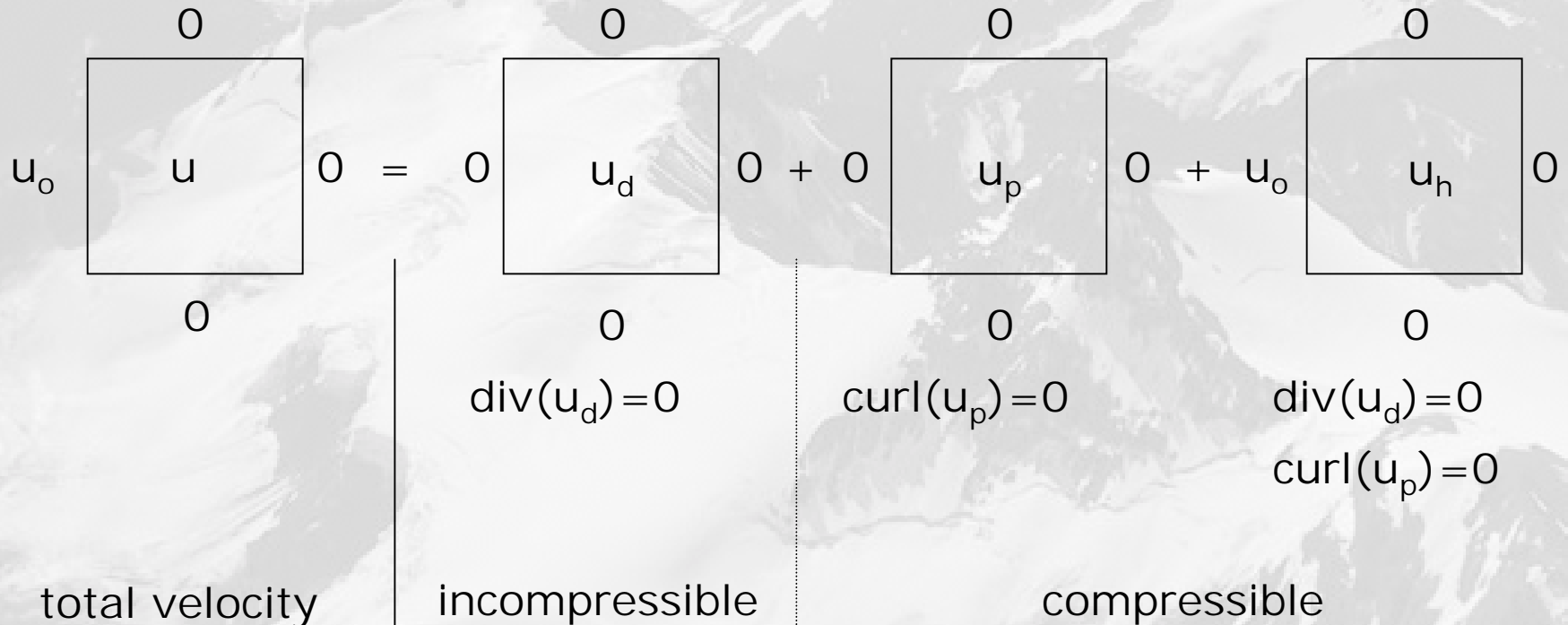
# Future Work

- Split the gravity waves
- Go to 3D
- Use an AMR framework
- Parallelize the code



# First-Aid Kit

# Separating Out the Acoustic Waves: Hodge Decomposition



# Definitions of Projections

$$\vec{u}_d = P_o(\vec{u})$$

$$\vec{u}_\rho = Q_o(\vec{u})$$

$$Q_\rho = \frac{1}{\rho} \text{grad}(L_\rho)^{-1} \text{div}$$

$$P_\rho = I - Q_\rho$$

$$Q_o = \text{grad}(L_o)^{-1} \text{div}$$

$$P_o = I - Q_o$$

$$L_\rho = \text{div} \left( \frac{1}{\rho} \text{grad} \right)$$

$$L_o = \text{div}(\text{grad})$$



# Definitions of Other Terms

$$A_d u = \vec{u} \cdot \text{grad}(\vec{u}) - \text{grad} \left( \frac{|u_p + u_h|^2}{2} \right)$$

$$\frac{1}{\rho} \text{grad}(\pi) = -Q_\rho(A_d u)$$

$$\delta = \rho - \rho_o(z) - \pi$$

# Separating Out Fast Gravity Waves

$$\frac{\partial \pi_H}{\partial z} = -\tilde{\rho}g$$

$$L_z \frac{\partial \pi_H}{\partial t} + \frac{\partial u_d}{\partial x} = f_\rho$$

$$\frac{\partial u_d}{\partial t} + \frac{1}{\rho_o} \frac{\partial \pi_H}{\partial x} = f_u$$

Wave equation

Project on fast  
eigenmodes

$$\lambda_k \frac{\partial \pi_H^k}{\partial t} + \frac{\partial \hat{u}_d^k}{\partial x} = \hat{f}_\rho$$

$$\frac{\partial \hat{u}_d^k}{\partial t} + \frac{\partial \pi_H^k}{\partial x} = \hat{f}_u$$

recompose

$$\pi_H^{Fast} = \sum_{k=1}^K \pi_H^k r_k$$

$$\hat{u}_d^{Fast} = \sum_{k=1}^K \hat{u}_d^k r_k$$

Back to original  
variables

$$u_d^{Fast}, \pi_H^{Fast}$$

# Outline of Algorithm

Recall: unknowns are  $u_d$ ,  $u_p$ ,  $\rho$ ,  $\pi$ ,  $\delta$

Find the eigenvalues and eigenvectors of  $L_z$

1. Advance  $\mathbf{u}_d$  to half time step and to face centers
2. Advance  $\rho$  to half time step and to face centers
3. Partially advance  $\mathbf{u}_d$  using only the advective terms
4. Solve for  $\pi_H^{Fast}$ ,  $u_d^{Fast}$
5. Project out unstable (fast) modes
6. Solve for auxiliary pressure  $\pi$
7. Advance acoustic pressure  $\delta$  implicitly
8. Advance curl-free velocity  $\mathbf{u}_p$
9. Update  $\rho$
10. Add missing terms in update for  $\mathbf{u}_d$

