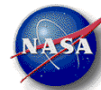
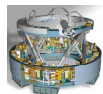


ADVANCED DOCKING/BERTHING SYSTEM

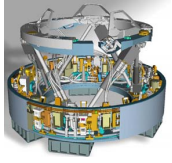
Brandan Robertson
National Aeronautics and Space Administration
Johnson Space Center
Houston, Texas



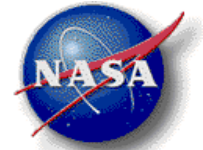
Advanced Docking/Berthing System NASA Seal Workshop GRC

November 9-10, 2004

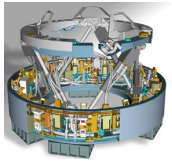
Brandan Robertson, NASA-JSC/ES5 281-483-3732, Houston, TX



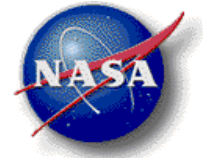
Outline



- Background
- Future Program Needs
- Existing Systems
- Status
- Advanced Docking/Berthing System (ADBS)
Overview
- Key Seal Requirements
- Early Seal Development Work

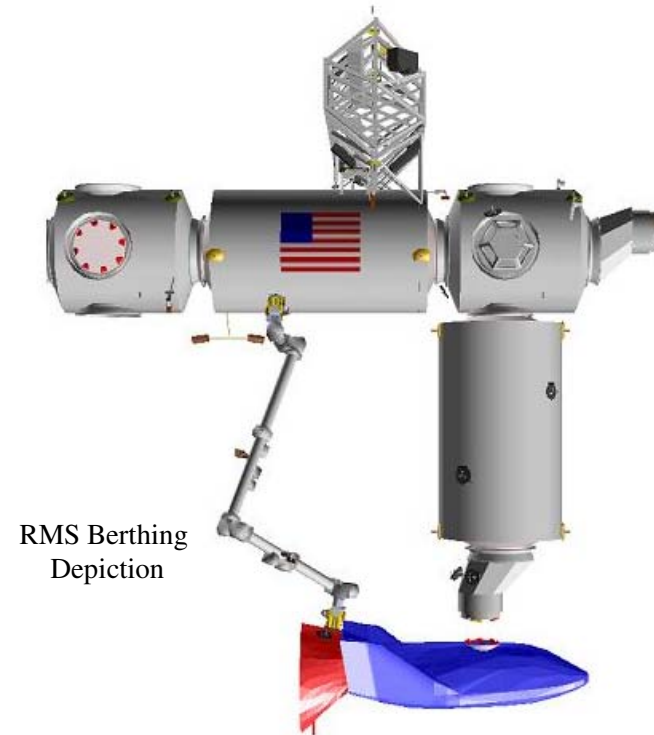


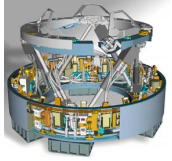
Background



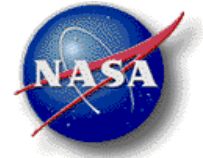
Berthing refers to mating operations where an inactive module/vehicle is placed into the mating interface using a Remote Manipulator System-RMS.

Docking refers to mating operations where an active vehicle flies into the mating interface under its own power.



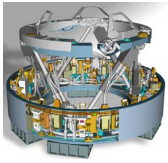


Future Needs

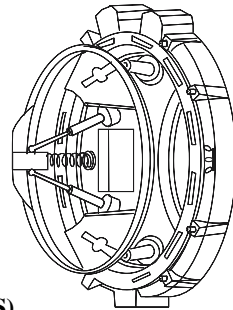


Future Mating System Capability Requirements:

- A system able to support a variety of missions: CTV/CEV/CRV, lunar gateway, Moon, and Mars
- Lightweight, fault tolerant system that blends well into vehicle OML (aero)
- Capable of autonomous rendezvous & docking
- Berthing capable for modular assembly and vehicle swap-out
- Software reconfigurable for a range of vehicles and operations
- Fast separation for rapid release
- Modular for maintenance and servicing
- Constellation safety & reliability goals
- Adaptable to ISS
- Crew and large cargo transfer
- Power, data, and fluid transfer
- Vehicle to vehicle mating (CRV-CTV-others) requires androgynous interface



Existing Systems



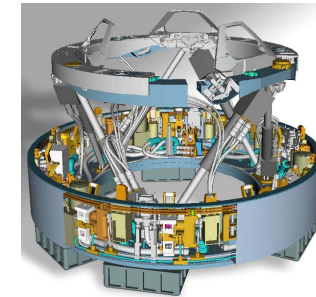
Androgynous Peripheral Docking System (APAS)

Weight: ~950 lbs (660 lbs APDA-6001 + 276 lbs avionics) (hatch not incl.)

Max OD: 69" dia

Hatch Pass Through: 31.38" dia

Source: JSC-26938, "Procurement Specification for the Androgynous Peripheral Docking System for the ISS Missions"



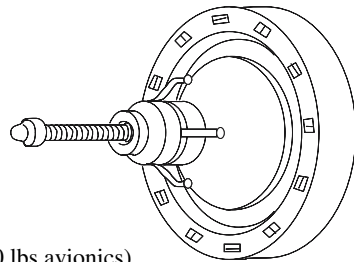
Advanced Docking/Berthing System (ADBS)¹

Weight: est. 750 lbs (includes electronics & hatch)

Max OD: 54" dia

Hatch Pass Through: 31" dia

Source: X-38 Program Group



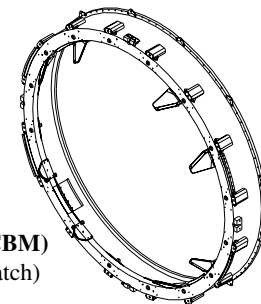
Russian Probe

Weight: 700 lbs (550 lbs cone + 150 lbs avionics)

Max OD: 61" dia

Hatch Pass Through: 31.5" dia (approximate)

Source: Energia



Passive Common Berthing Mechanism (PCBM)

Weight: 680 lbs² (440 lbs PCBM + 240 lbs hatch)

Hatch Pass Through: 50" square

Max OD: 86.3" dia

Source: SSP 41004, Part 1, "Common

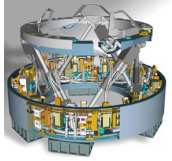
Berthing Mechanism to Pressurized

Elements ICD" & SSP 41015, Part 1, Common

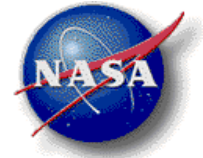
Hatch & Mechanisms To Pressurized Elements ICD

¹ADBS currently under development

²Bulkhead hatch ring structure not included

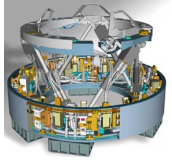


Existing Systems



Limitations of existing systems:

- Do not meet 2-fault tolerant, time-critical release requirement for crewed vehicles
 - APAS for Shuttle relies on 96 bolt EVA to meet 2nd fault tolerance
 - CBM powered bolts in nominal ops are not time critical and are single fault tolerant
- Unique active & passive halves: precludes vehicle-to-vehicle mating
- Do not support autonomous operations
 - No automatic mating of fluid, power (APAS does have a single power/data connector) and forced air umbilicals
 - CBM cannot mate to unmanned vehicles
- Standard ISS racks cannot pass through existing docking ports
- Significant velocities required to provide alignment & capture forces
- Crit-1 operations supported by intensive training & analysis
- High part count / mechanical complexity with single point failures (reliability and failure tolerance problems)
- Berthing mechanisms do not dock and docking mechanisms do not berth
- Russian systems are supplied by a foreign vendor with substantial economic concerns
 - Purchase of additional units banned by Iran Missile Proliferation Sanctions Act of 1997
 - Very limited access to engineering data
- Systems designed and/or certified for very few cycles and short exposure life

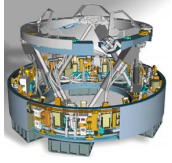


Current Status

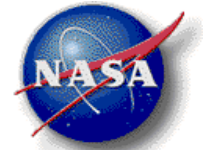


Advanced Mating System Development Activities

- Exploration Systems Technology Maturation Program has selected advanced mating systems for continuation during the recent ICP activity.
- JSC has been developing an advanced mating system (ADBS) since 1996.
 - Originally intended for use on the X-38 project
 - Designed to support both berthing and docking operations and to provide future mission architecture flexibility (cross-cutting technology)
 - The current design baseline is a X-38-sized risk reduction unit (RRU)
 - Fully androgynous interface
 - Uses electromagnets and closed-loop force-feedback for soft-capture
 - Minimally sized for crew transfer
 - Fully integrated ground based system to show TRL 4 maturity
 - Work on Constellation scale system to begin as RRU matures
- Long-duration seal technology (seal-on-seal) has been identified as a current design gap.

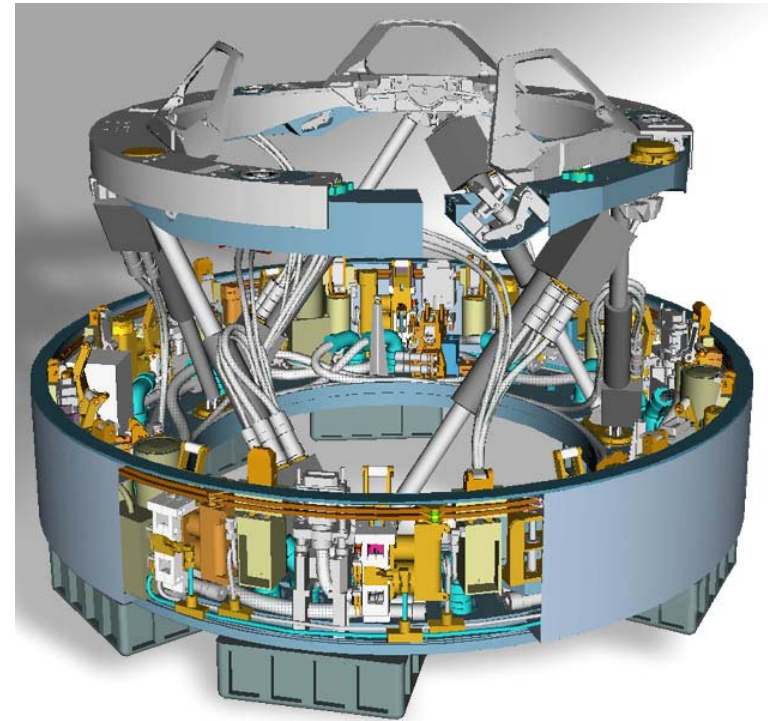


ADBS Overview



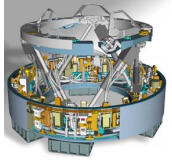
A Next-Generation Mating Mechanism

- Designed specifically to take advantage of modern electromechanical technology
- Incorporates the lessons learned and experiences from previous/current mating mechanism development and use
- Desensitizes mating mechanism operations and performance from other vehicle systems requirements
- Supports both docking and berthing operations
- Supports autonomous rendezvous & mating
- Aligned with NASA Strategic Plan

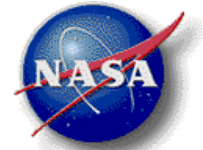


CAD Image

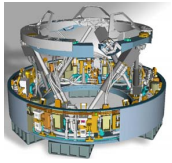
Interactive Overview



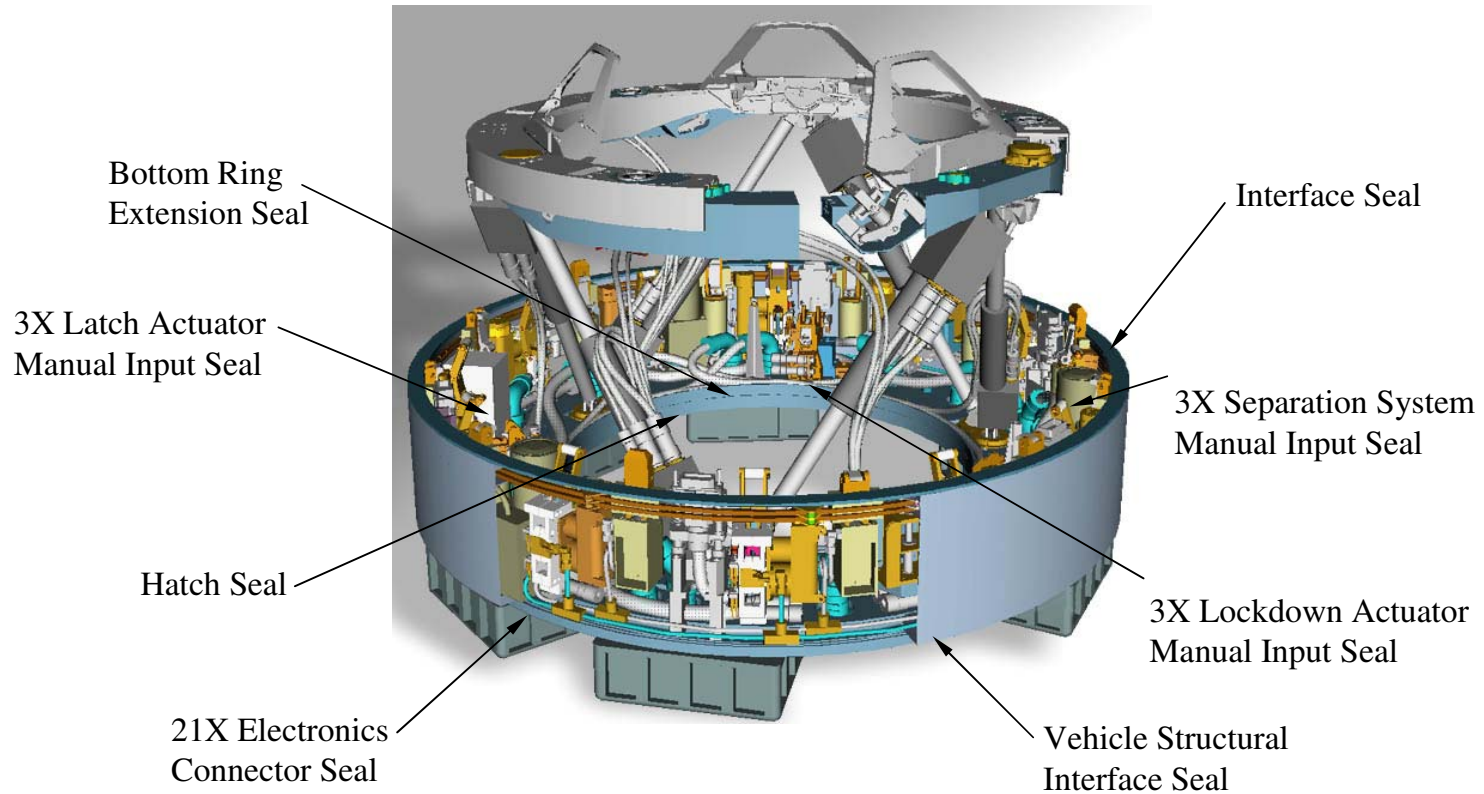
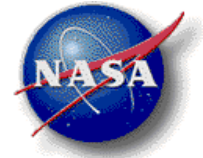
Key Seal Requirements

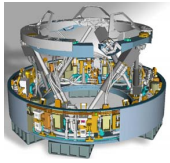


- Seal-on-seal interface
- Very low leak rate
- Long life
 - Long-duration exposed periods
 - Long-duration mated periods
 - Deep-space environments
 - May also be a potential for high mate/demate cycle life
- Redundancy

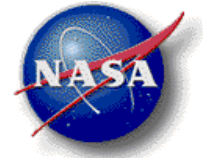


ADBS Seal Locations





Early ADBS Seal Development



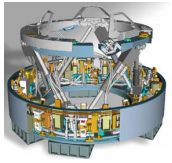
To preserve the fully androgynous design concept the seal design approach baselined was a seal-on-seal implementation similar to the Apollo Soyuz (ASTP) seals.

Subscale seal-on-seal elastomeric development with Parker Inc.

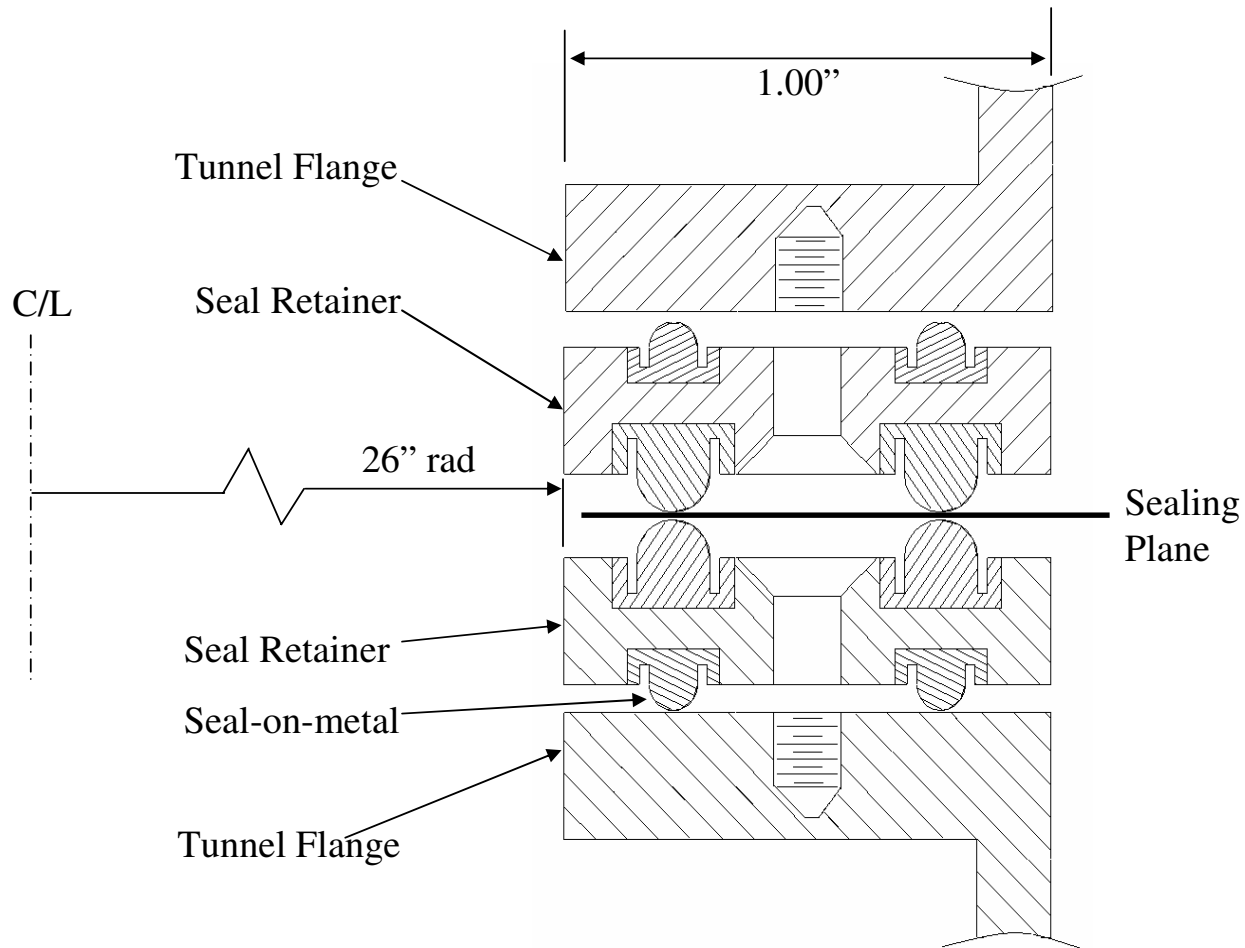
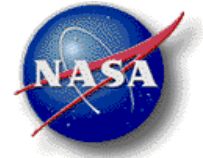
- Quick development and testing to evaluate seal-on-seal potential
- 2 cross-sections (flat top and elliptical) and 2 different durometer silicon materials
- Helium leak testing and seal load force testing completed in July 2001
- Adhesion testing is ongoing

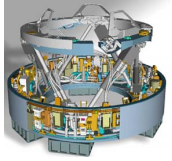
Test results

- Leak rates comparable to ISS CBM seals with offset of 0.050 inches and no gapping (~20 configurations tested)
- Compression force testing showed that “flat top” slightly higher than “elliptical” for the 70 durometer at (96 & 87 lb/in) and for the 50 durometer at (46 & 42 lb/in). Results indicated that seal-on-seal in the “acceptable” range for use.
- Adhesion test results pending; series of “buttons” molded from each material are currently mated and compressed for eventual separation and inspection at TBD regular intervals of time.



RRU Interface Seal Concept





Early ADBS Seal Development

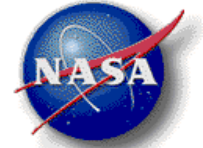
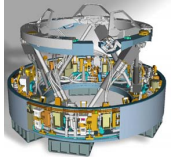


Conclusions

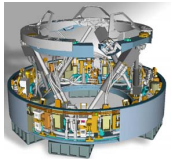
- No elastomeric seal-on-seal show stoppers yet

Forward work

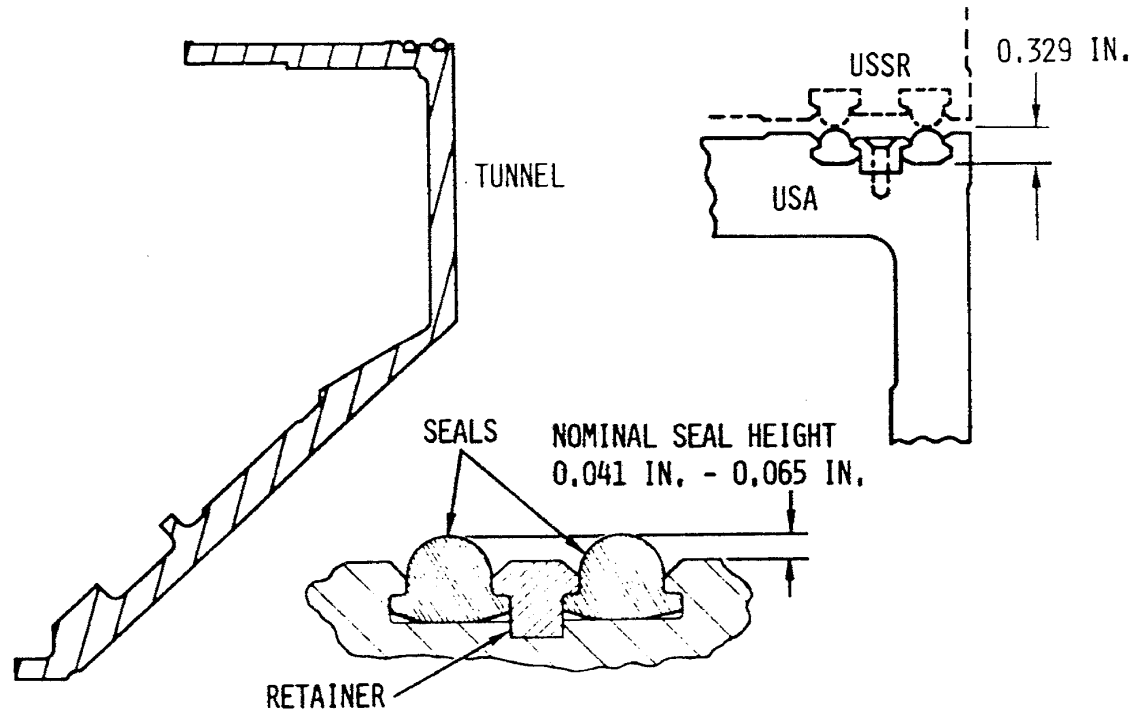
- As soon as funding picture clears up, move forward with a full development seal purchase for the RRU
- Need to establish “the” baseline seal cross-section
 - Optimize seal to guarantee optimal sealing: percent of fill, squeeze, crown profile and height, if elastomeric
 - Establish total potential seal mismatch: misalignment, thermal expansion, flange deflection
 - Establish acceptable seal force and leak rate
- Determine if a single piece ~54” seal/retainer construction possible. Parker has indicated they do this now in a newly acquired facility.
- Evaluate concepts and results for full-scale Constellation implementation
 - Evaluate RRU design upward scaling
 - Are metallic seals a better solution?



Backup Slides



Existing System Seals



Apollo Soyuz Test Program Docking System Interface Seal Diagram