

Kinetic Theory of Granular Gases

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talk, papers available: <http://cnls.lanl.gov/~ebn>



Plan

- 1. Basics: collision rules, collision rates**
- 2. The Boltzmann equation**
- 3. Extreme statistics and the linearized Boltzmann equation**
- 4. Forced steady states**
- 5. Freely cooling states**
- 6. Stationary states and energy cascades**
- 7. Hybrid solutions**

Experiments

◆ Friction

D Blair, A Kudrolli 01

◆ Rotation

K Feitosa, N Menon 04

◆ Driving strength

W Losert, J Gollub 98

◆ Dimensionality

J Urbach & Olafsen 98

◆ Boundary

J van Zon, H Swinney 04

◆ Fluid drag

K Kohlstedt, I Aronson, EB 05

◆ Long range interactions

D Blair, A Kudrolli 01; W Losert 02

K Kohlstedt, J Olafsen, EB 05

◆ Substrate

G Baxter, J Olafsen 04

Deviations from equilibrium distribution

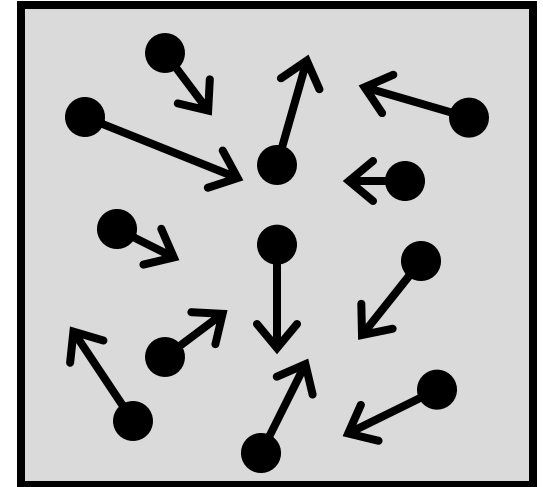
Driven Granular gas

- ◆ Vigorous driving
- ◆ Spatially uniform system
- ◆ Particles undergo binary collisions
- ◆ Velocities change due to
 1. Collisions: lose energy
 2. Forcing: gain energy
- ◆ What is the typical velocity (granular “temperature”)?

$$T = \langle v^2 \rangle$$

- ◆ What is the velocity distribution?

$$f(v)$$



Inelastic Collisions (1D)

- ◆ Relative velocity reduced by $0 < r < 1$

$$v_1 - v_2 = -r(u_1 - u_2)$$

- ◆ Momentum is conserved

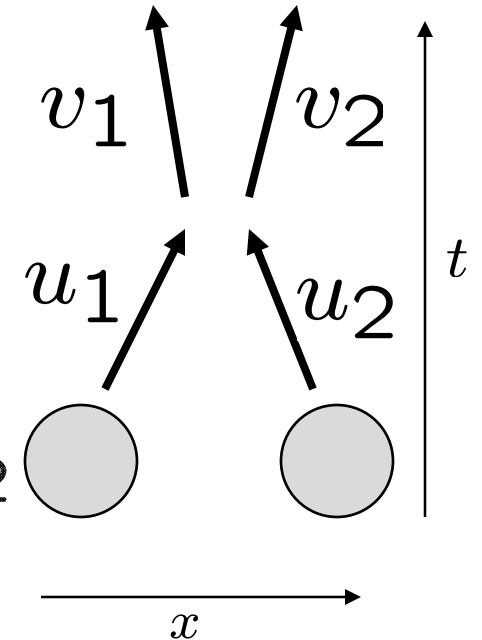
$$v_1 + v_2 = u_1 + u_2$$

- ◆ Energy is dissipated

$$\Delta E = \frac{1 - r^2}{4} (u_1 - u_2)^2$$

- ◆ Limiting cases

$$r = \begin{cases} 0 & \text{completely inelastic } (\Delta E = \max) \\ 1 & \text{elastic } (\Delta E = 0) \end{cases}$$



Inelastic Collisions (any D)

- ◆ Normal relative velocity reduced by $0 < r < 1$

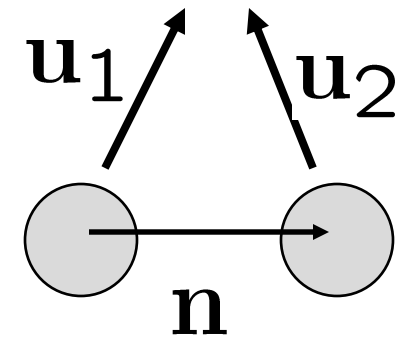
$$(\mathbf{v}_1 - \mathbf{v}_2) \cdot \mathbf{n} = -r(\mathbf{u}_1 - \mathbf{u}_2) \cdot \mathbf{n}$$

- ◆ Momentum conservation

$$\mathbf{v}_1 + \mathbf{v}_2 = \mathbf{u}_1 + \mathbf{u}_2$$

- ◆ Energy loss

$$\Delta E = \frac{1 - r^2}{4} [(\mathbf{u}_1 - \mathbf{u}_2) \cdot \mathbf{n}]^2$$



- ◆ Limiting cases

$$r = \begin{cases} 0 & \text{completely inelastic } (\Delta E = \max) \\ 1 & \text{elastic } (\Delta E = 0) \end{cases}$$

Non-Maxwellian velocity distributions

JC Maxwell, Phil Trans Roy. Soc. 157 49 (1867)

1. Velocity distribution is isotropic

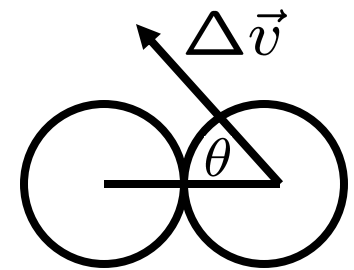
$$f(v_x, v_y, v_z) = f(|v|)$$

2. No correlations between velocity components

$$f(v_x, v_y, v_z) \neq f(v_x)f(v_y)f(v_z)$$

Only possibility is Maxwellian

$$f(v_x, v_y, v_z) \neq C \exp\left(-\frac{v_x^2 + v_y^2 + v_z^2}{2T}\right)$$



Granular gases: collisions create correlations

The Boltzmann equation (1D)

- ◆ **Collision rule (linear)** $r = 1 - 2p, \quad p + q = 1$

$$(u_1, u_2) \rightarrow (pu_1 + qu_2, pu_2 + qu_1)$$

- ◆ **Boltzmann equation (nonlinear and nonlocal)**

$$\frac{\partial f(v)}{\partial t} = \iint du_1 du_2 f(u_1) f(u_2) |u_1 - u_2|^\lambda [\delta(v - pu_1 - qu_2) - \delta(v - u_2)]$$

collision rate
gain
loss

- ◆ **Collision rate related to interaction potential**

$$U(r) \sim r^{-\gamma} \quad \lambda = 1 - 2 \frac{d-1}{\gamma} = \begin{cases} 0 & \text{Maxwell molecules} \\ 1 & \text{Hard spheres} \end{cases}$$

Theory: non-linear, non-local, dissipative

The collision rate

◆ Collision rate

$$K(\mathbf{u}_1, \mathbf{u}_2) = |(\mathbf{u}_1 - \mathbf{u}_2) \cdot \mathbf{n}|^\lambda$$

◆ Collision rate related to interaction potential

$$U(r) \sim r^{-\gamma} \quad \lambda = 1 - 2 \frac{d-1}{\gamma} = \begin{cases} 0 & \text{Maxwell molecules} \\ 1 & \text{Hard spheres} \end{cases}$$

◆ Balance kinetic and potential energy

$$v^2 \sim r^{-\gamma} \quad \Rightarrow \quad r \sim v^{-2/\gamma}$$

◆ Collisional cross-section

$$\sigma \sim v r^{d-1} \quad \Rightarrow \quad \sigma \sim v^{1 - \frac{2}{\gamma}(d-1)}$$

Extreme Statistics (1D)

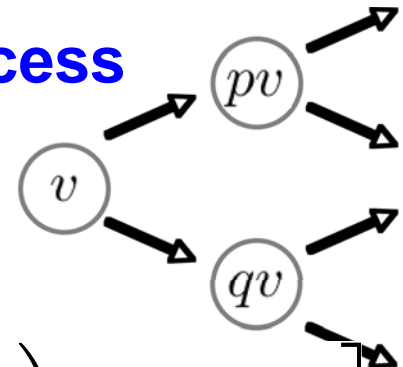
- ◆ Collision rule: arbitrary velocities

$$(u_1, u_2) \rightarrow (pu_1 + qu_2, pu_2 + qu_1)$$



- ◆ Large velocities: linear but nonlocal process

$$v \xrightarrow{v^\lambda} (pv, qv)$$



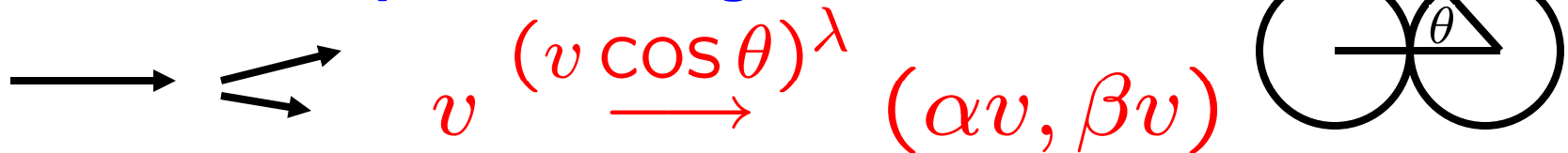
- ◆ High-energies: linear equation

$$\frac{\partial f(v)}{\partial t} = v^\lambda \left[\underbrace{\frac{1}{p^{1+\lambda}} f\left(\frac{v}{p}\right)}_{\text{gain}} + \underbrace{\frac{1}{q^{1+\lambda}} f\left(\frac{v}{q}\right)}_{\text{gain}} - \underbrace{f(v)}_{\text{loss}} \right]$$

Linear, nonlocal evolution equation

Extreme Statistics (any D)

- ◆ Collision process: large velocities



- ◆ Stretching parameters related to impact angle

$$\alpha = (1 - p) \cos \theta \quad \beta = \sqrt{1 - (1 - p^2) \cos^2 \theta}$$

- ◆ Energy decreases, velocity magnitude increases

$$\alpha^2 + \beta^2 \leq 1 \quad \alpha + \beta \geq 1$$

- ◆ Linear equation

$$\frac{\partial f(v)}{\partial t} = \left\langle (v \cos \theta)^\lambda \left[\frac{1}{\alpha^{d+\lambda}} f\left(\frac{v}{\alpha}\right) + \frac{1}{\beta^{d+\lambda}} f\left(\frac{v}{\beta}\right) - f(v) \right] \right\rangle$$

Forced steady states: overpopulated tails

T van Noije, M Ernst 97

- ◆ Energy injection: thermal forcing (at all scales)

$$dv/dt = \eta$$

- ◆ Energy dissipation: inelastic collision

$$v \rightarrow (pv, qv)$$

- ◆ Steady state equation

$$0 = D \frac{d^2 f(v)}{d^2 v} + v^\lambda \left[\frac{1}{p^{1+\lambda}} f\left(\frac{v}{p}\right) + \frac{1}{q^{1+\lambda}} f\left(\frac{v}{q}\right) - f(v) \right]$$

- ◆ Stretched exponentials

$$f(v) \sim \exp\left(-v^{1+\lambda/2}\right)$$

Nonequilibrium velocity distributions

A Mechanically vibrated beads

F Rouyer & N Menon 00

B Electrostatically driven powders

I Aronson & J Olafsen 05

◆ Gaussian core

◆ Overpopulated tail

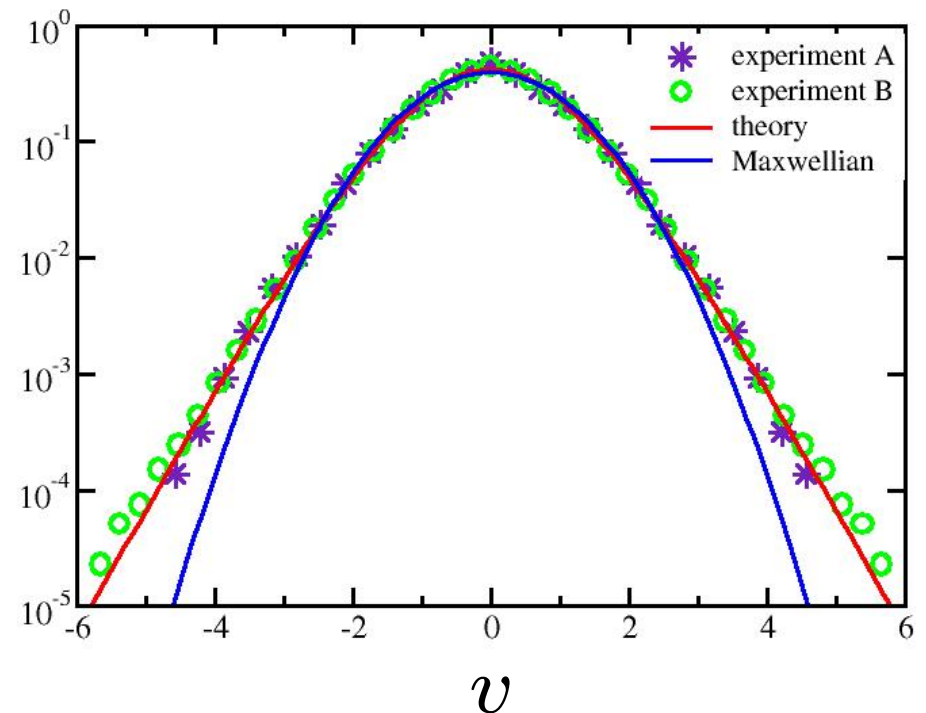
$$f(v) \sim \exp(-|v|^\delta)$$

$$1 \leq \delta \leq 3/2$$

◆ Kurtosis

$$\kappa = \begin{cases} 3.55 & \text{theory} \\ 3.6 & \text{experiment} \end{cases}$$

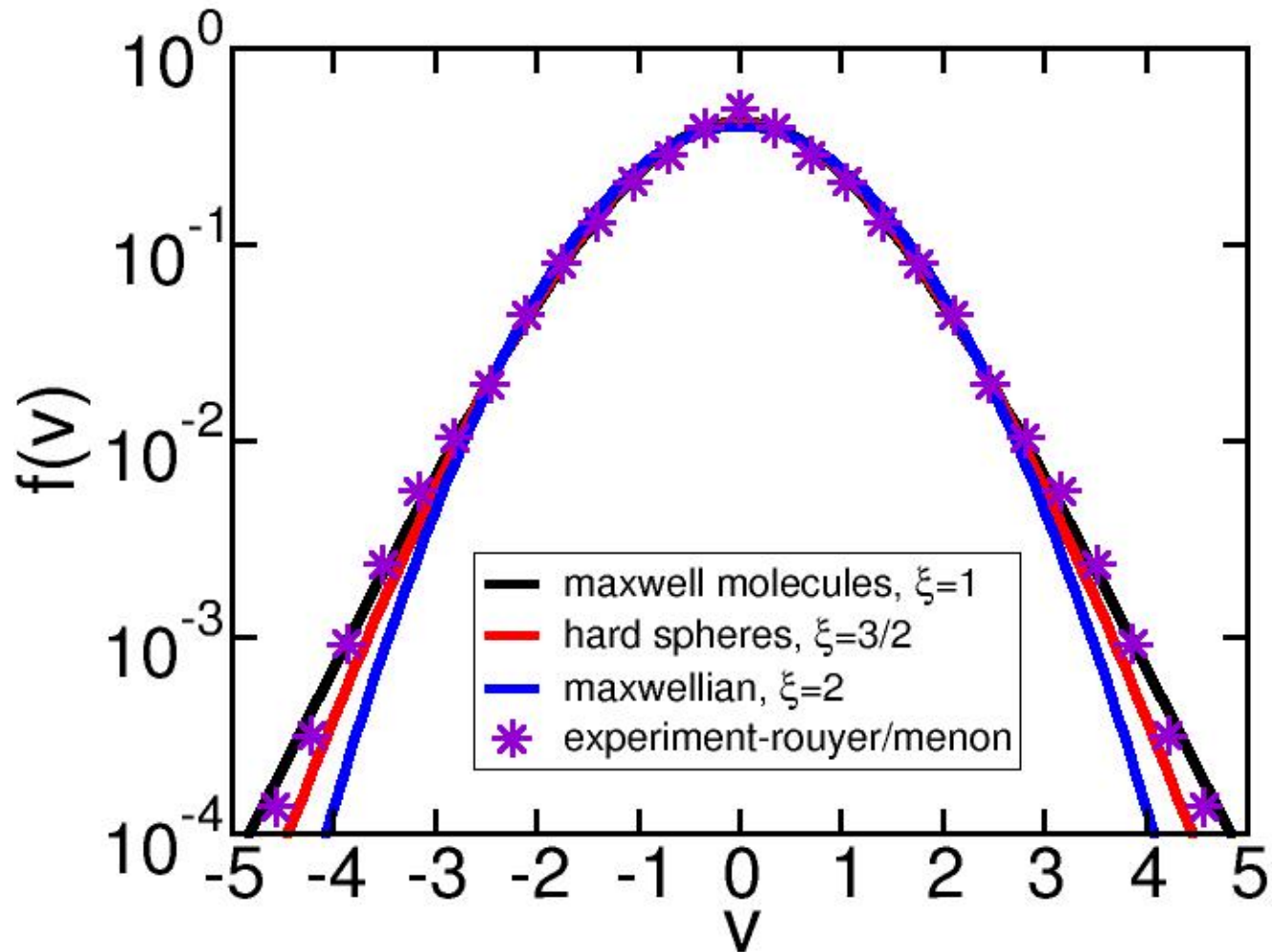
$$f(v)$$



Excellent agreement between theory and experiment

balance between
collisional dissipation,
energy injection from walls

Comparing kinetic theories



Freely cooling states: temperature decay

Haff, JFM 1982

- ◆ Energy loss $\Delta T \sim (\Delta v)^2$
- ◆ Collision rate $\Delta t \sim 1/(\Delta v)^\lambda$
- ◆ Energy balance equation

$$\frac{\Delta T}{\Delta t} \sim -(\Delta v)^{2+\lambda} \quad \Rightarrow \quad \frac{dT}{dt} \sim -T^{1+\lambda/2}$$

- ◆ Temperature decays, system comes to rest

$$T \sim t^{-2/\lambda} \quad \Rightarrow \quad f(v) \rightarrow \delta(v)$$

System comes to rest

Temperature decay: dimensional analysis

◆ Collision rate

$$K \sim (\Delta v)^\lambda \sim v^\lambda$$

◆ Collision rate inversely proportional to time

$$K \sim t^{-1} \quad \Rightarrow \quad v \sim t^{-1/\lambda}$$

Freely cooling states: similarity solutions

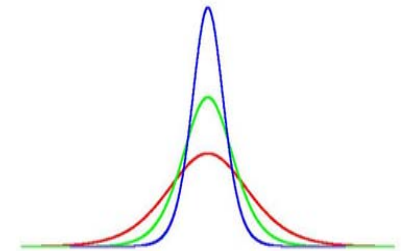
Esipov, Poeschel 97

◆ Linearized equation

$$\frac{\partial f(v)}{\partial t} = v^\lambda \left[\frac{1}{p^{1+\lambda}} f\left(\frac{v}{p}\right) + \frac{1}{q^{1+\lambda}} f\left(\frac{v}{q}\right) - f(v) \right]$$

◆ Similarity solution

$$f(v) \rightarrow t^{1/\lambda} \Phi(vt^{1/\lambda})$$



◆ Steady state equation

$$\frac{1}{\lambda} \left[\Phi(z) + z \frac{d}{dz} \Phi(z) \right] = z^\lambda \left[\frac{1}{p^{1+\lambda}} \Phi\left(\frac{z}{p}\right) + \frac{1}{q^{1+\lambda}} \Phi\left(\frac{z}{q}\right) - \Phi(z) \right]$$

◆ Stretched exponentials (overpopulation)

$$\Phi(z) \sim \exp(-z^\lambda)$$

An exact solution

- ◆ One-dimensional Maxwell molecules

- ◆ Fourier transform obeys a closed equation $F(k) = \int dv e^{ikv} f(v)$

$$F(k) = F(pk)F(qk)$$

- ◆ Exponential solution

$$F(k) = \exp(-v_0|k|)$$

- ◆ Lorentzian velocity distribution

$$f(v) = \frac{1}{\pi v_0} \frac{1}{1 + (v/v_0)^2}$$

Nontrivial stationary states do exist!

Are there nontrivial steady states?

◆ Stationary Boltzmann equation

$$0 = \iint du_1 du_2 f(u_1) f(u_2) |u_1 - u_2|^\lambda [\delta(v - pu_1 - qu_2) - \delta(v - u_2)]$$

collision rate gain loss

Naive answer: NO!

◆ According to the energy balance equation

$$\frac{dT}{dt} = -\Gamma$$

◆ Dissipation rate is positive

$$\Gamma > 0$$

Cascade Dynamics (1D)

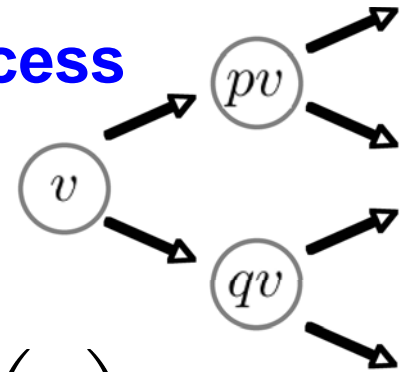
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$$(u_1, u_2) \rightarrow (pu_1 + qu_2, pu_2 + qu_1)$$



- ◆ Large velocities: linear but nonlocal process

$$v \rightarrow (pv, qv)$$



- ◆ High-energies: linear equation

$$f(v) = \frac{1}{p^{1+\lambda}} f\left(\frac{v}{p}\right) + \frac{1}{q^{1+\lambda}} f\left(\frac{v}{q}\right)$$

loss

gain

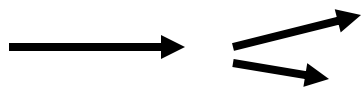
gain

- ◆ Power-law tail

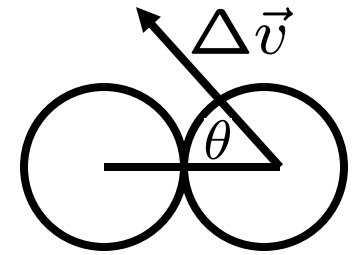
$$f(v) \sim v^{-2-\lambda}$$

Cascade Dynamics (any D)

- ◆ Collision process: large velocities



$$v \rightarrow (\alpha v, \beta v)$$



- ◆ Stretching parameters related to impact angle

$$\alpha = (1 - p) \cos \theta \quad \beta = \sqrt{1 - (1 - p^2) \cos^2 \theta}$$

- ◆ Energy decreases, velocity magnitude increases

$$\alpha^2 + \beta^2 \leq 1 \quad \alpha + \beta \geq 1$$

- ◆ Steady state equation

$$f(v) = \left\langle \frac{1}{\alpha^{d+\lambda}} f\left(\frac{v}{\alpha}\right) + \frac{1}{\beta^{d+\lambda}} f\left(\frac{v}{\beta}\right) \right\rangle$$

Power-laws are generic

- ◆ Velocity distributions always has power-law tail

$$f(v) \sim v^{-\sigma}$$

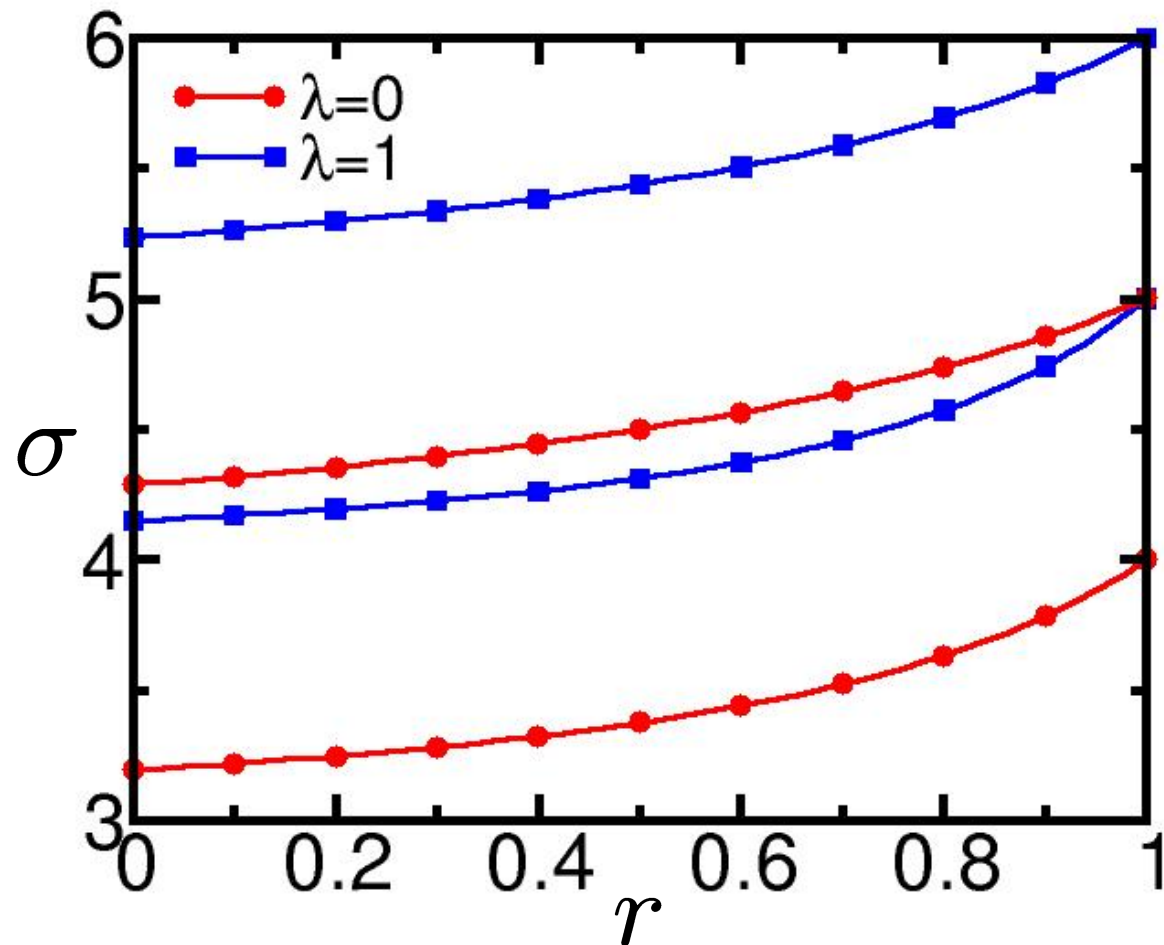
- ◆ Exponent varies with parameters

$$\frac{{}_1F_2\left(\frac{d+\lambda-\sigma}{2}, \frac{\lambda+1}{2}, \frac{d+\lambda}{2}, 1-p^2\right)}{(1-p)^{\sigma-d-\lambda}} = \frac{\Gamma\left(\frac{\sigma-d+1}{2}\right)\Gamma\left(\frac{d+\lambda}{2}\right)}{\Gamma\left(\frac{\sigma}{2}\right)\Gamma\left(\frac{\lambda+1}{2}\right)}$$

- ◆ Tight bounds $1 \leq \sigma - d - \lambda \leq 2$
- ◆ Elastic limit is singular $\sigma \rightarrow d + 2 + \lambda$

**Dissipation rate always divergent
Energy finite or infinite**

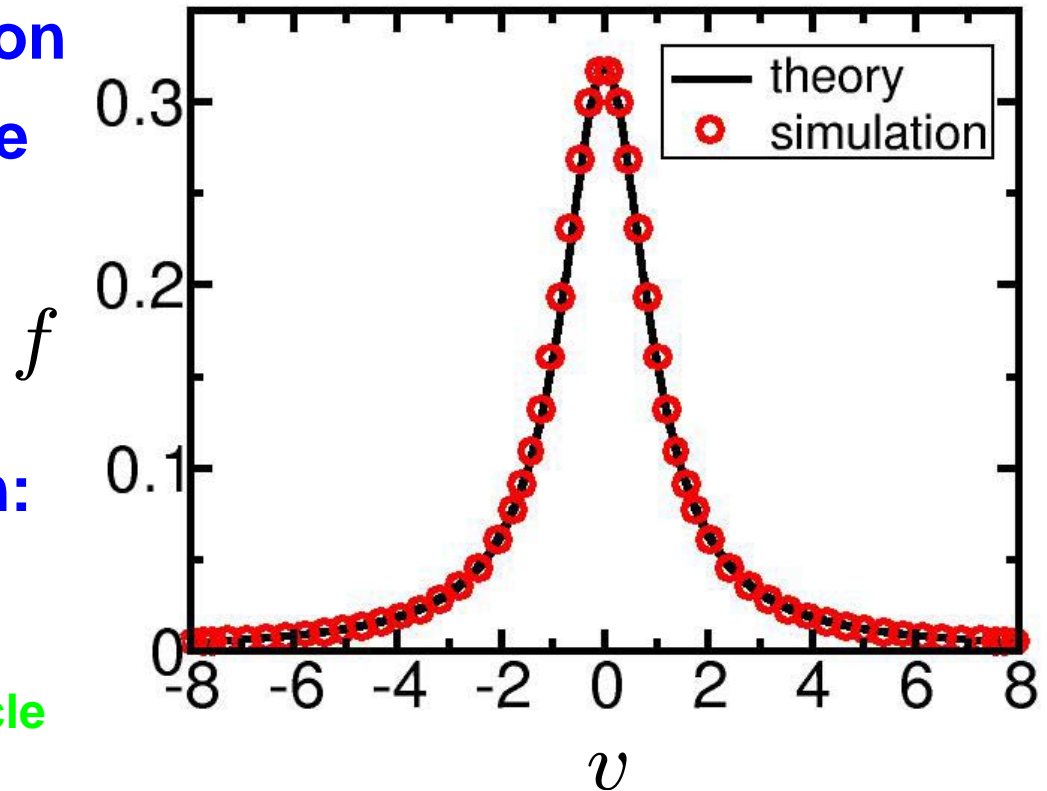
The characteristic exponent σ



σ varies with spatial dimension, collision rules

Monte Carlo Simulations

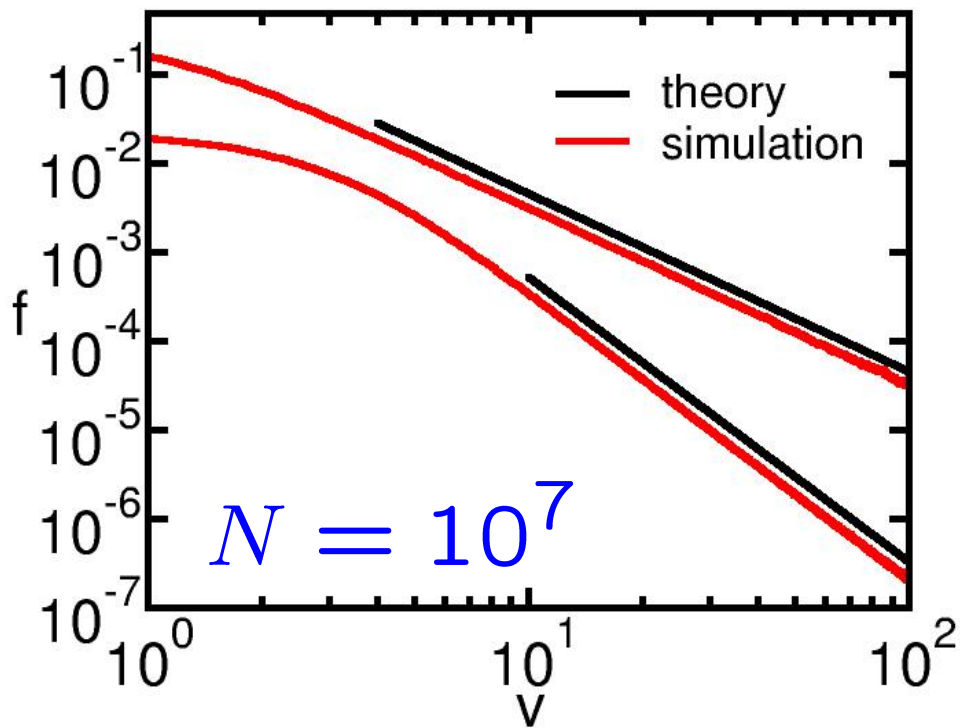
- ◆ Compact initial distribution
- ◆ Inject energy at very large velocity scales only
- ◆ Maintain constant total energy
- ◆ “Lottery” implementation:
 - Keep track of total energy dissipated, E_T
 - With small rate, boost a particle by E_T



Excellent agreement between theory and simulation

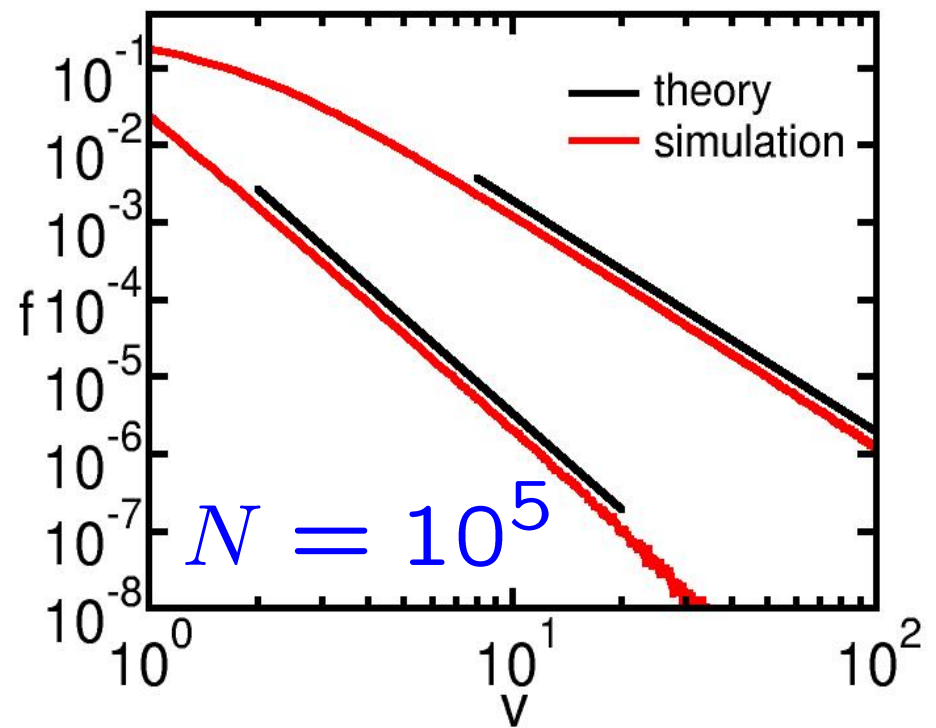
Further confirmation

Maxwell molecules (1D, 2D)



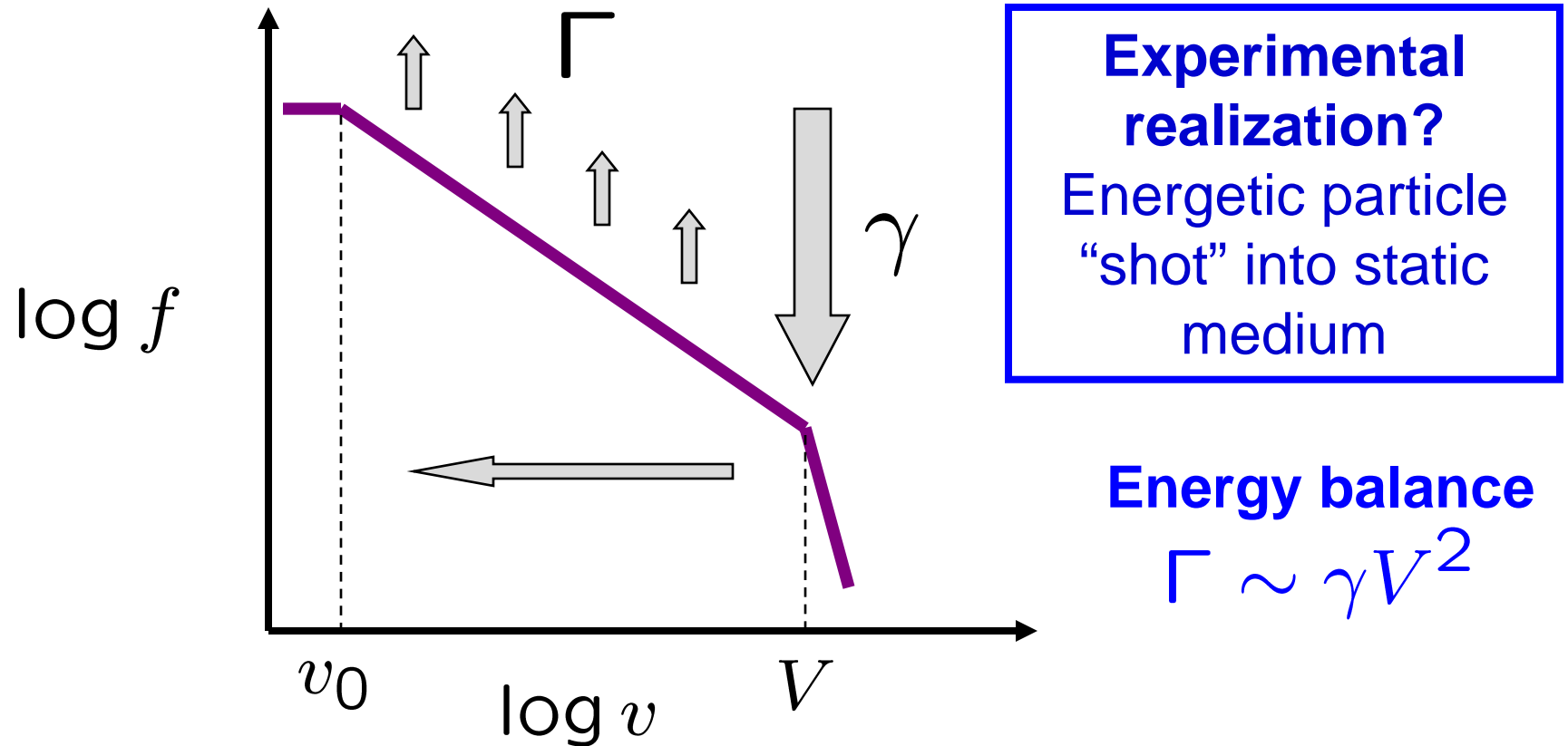
d	theory	simulation
1	2	1.995
2	3.19520	3.19

Hard spheres (1D, 2D)



d	theory	simulation
1	3	2.994
2	4.14922	4.15

Injection, cascade, dissipation



- ❖ Energy is injected at large velocity scales
- ❖ Energy cascades from large velocities to small velocities
- ❖ Energy dissipated at small velocity scales

Energy balance

- ◆ Energy injection rate γ
- ◆ Energy injection scale V
- ◆ Typical velocity scale v_0
- ◆ Balance between energy injection and dissipation

$$\gamma \sim V^\lambda (V/v_0)^{d-\sigma}$$

- ◆ For “lottery” injection: injection scale diverges with injection rate

$$V \sim \begin{cases} \gamma^{-1/(2-\lambda)} & \sigma < d + 2 \\ \gamma^{-1/(\sigma-d-\lambda)} & \sigma > d + 2 \end{cases}$$

Self-similar collapse

◆ **Self-similar distribution**

$$f(v, t) \simeq v^{-\sigma} \Phi \left(\frac{v}{V(t)} \right)$$

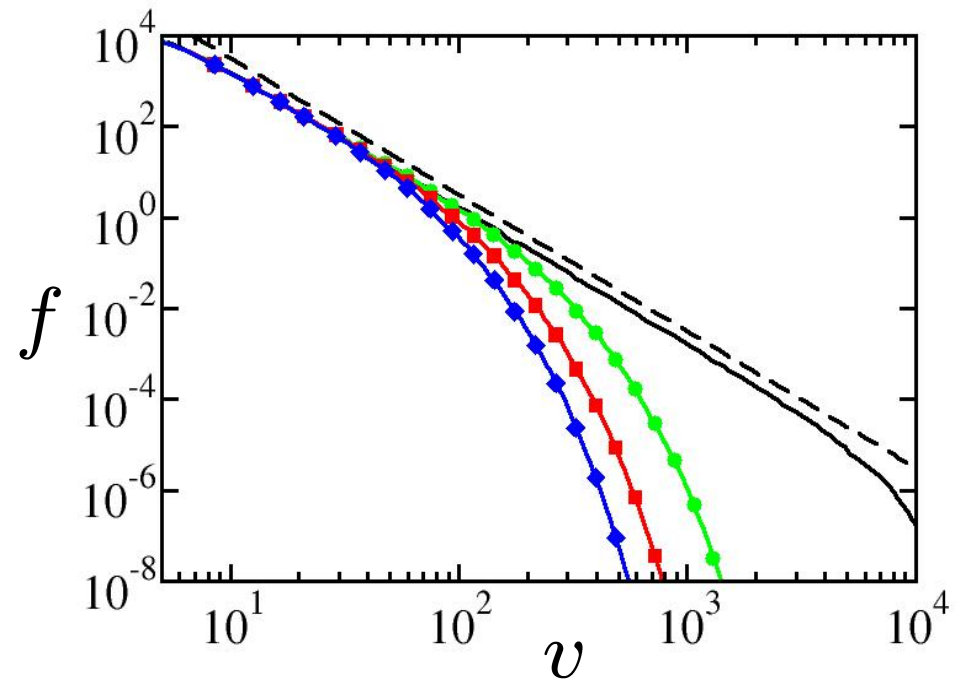
◆ **Cutoff velocity decays**

$$V(t) \sim t^{-1/\lambda}$$

◆ **Scaling function**

$$\Phi(x) = \sum_{n=1}^{\infty} A_n \exp \left[-(2^n x)^\lambda \right]$$

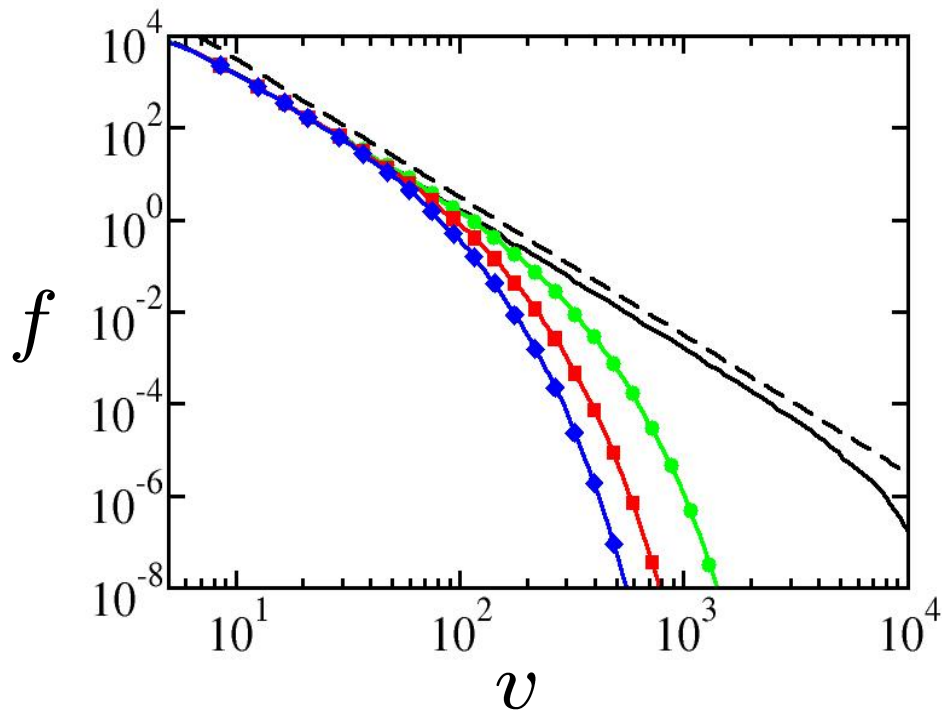
$$A_n = \prod_{\substack{k=1 \\ k \neq n}}^{\infty} \frac{1}{1 - 2^{\lambda(n-k)}}$$



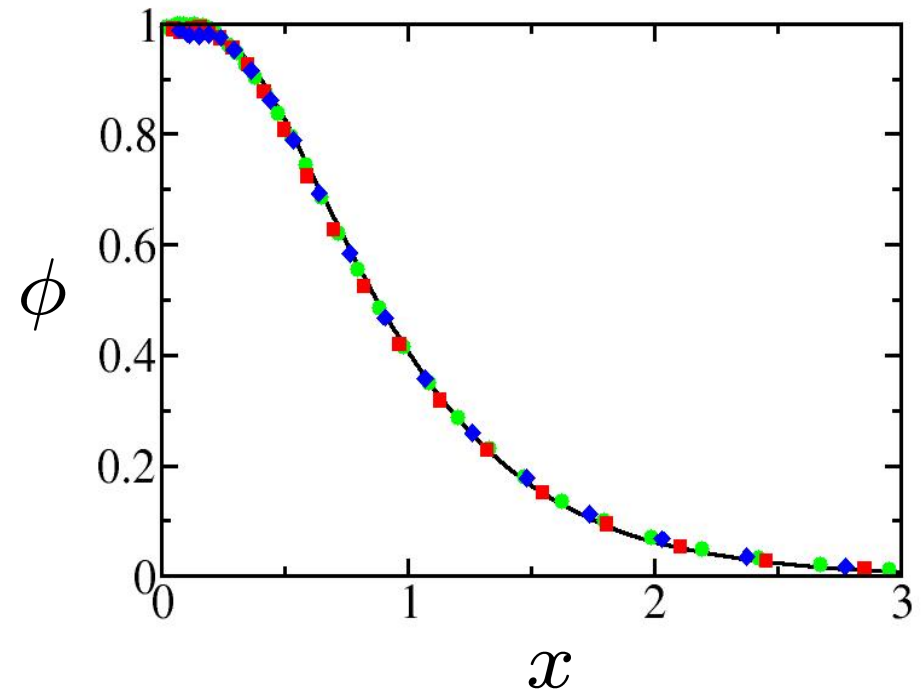
Hybrid between steady-state and time dependent state

Numerical confirmation

Velocity distribution



Scaling function



A third family of solutions exists

Conclusions

- ◆ **New class of nonequilibrium stationary states**
- ◆ **Energy cascades from large to small velocities**
- ◆ **Power-law high-energy tail**
- ◆ **Energy input at large scales balances dissipation**
- ◆ **Associated similarity solutions exist as well**
- ◆ **Temperature insufficient to characterize velocities**
- ◆ **Experimental realization: requires a different driving mechanism**

Outlook

- ◆ Spatially extended systems
- ◆ Spatial structures
- ◆ Polydispersed granular media
- ◆ Experimental realization

E. Ben-Naim and J. Machta, Phys. Rev. Lett. **94**, 138001 (2005)

E. Ben-Naim, B. Machta, and J. Machta, cond-mat/0504187

Deviation from Maxwell-Boltzmann

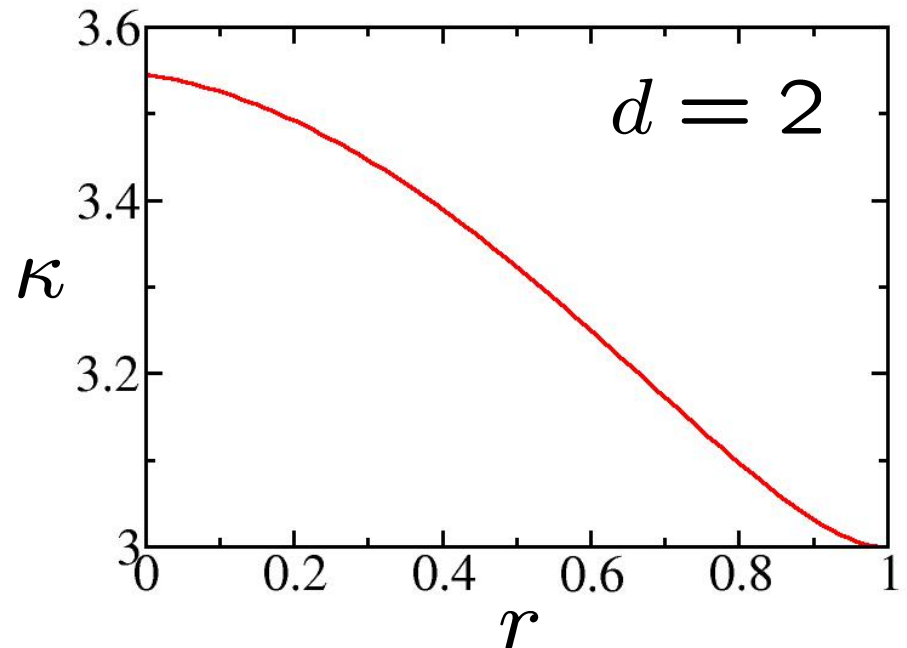
◆ Kurtosis κ

$$\kappa = \langle v^4 \rangle / \langle v^2 \rangle^2$$

$$\kappa = 3 + \frac{18(1-r)^2(1+r)}{33 - 25r + 3r^2 - 3r^3}$$

◆ Restitution coefficient r

$$\Delta E \propto (1 - r^2) (\Delta v)^2$$



1. Velocity distribution independent of driving strength
2. Stronger dissipation yields stronger deviation

Exact solution of Maxwell's kinetic theory: thermal forcing balances dissipation

EB, Krapivsky 02