Biologically Inspired Intelligent Robots

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Kenneth Meijer, U. of Maastricht, Netherlands; Y. Bar-Cohen, JPL; and Robert Full, UC Berkeley

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Bruce Blumberg, MIT

Chapter 4: Haptic and Telepresence Robotics

Allen Fisch, Rutger U.; Dinos Mavroidis, Rutgers U.; Yoseph Bar-Cohen, JPL; and Juan Melli-Huber Rutger University

Chapter 5: Cyborg Technology - Biomimetic Orthotic and Prosthetic Technology

Hugh Herr, MIT; University Graham Paul Whiteley, U. of Bath, England; and Dudley Childress, Northwester University

Chapter 6: Character Creation - Structural Elements of Biomimetic Robots

Richard Landon, Stan Winston Studios

Chapter 7: Biologically Inspired Components of Robots - Sensors, Actuators and Power Supplies

Gil Pratt, MIT

Chapter 8: Control of Biomimentic Robots

Dan Paluska, MIT; Maja Mataric, USC; and Jerry Pratt, MIT

Chapter 9: Cognitive Modeling for Biomimetic Robots

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Chapter 10: Bio-Robotic Applications

David Hanson, UTD; Daniela Rus, Dartmouth University; Steven Canvin, Lego; and Gernot Schmierer, Schmalz GmbH, German;

Chapter 11: Outlook for the Technology of Intelligent Biomimetic Robots

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