Dislocation Modelling Atomic-scale to the Continuum

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The University of Liverpool US DoE, Washington, March 2004



<u>Issues</u>:

- how to model strengthening effects, yield phenomena, obstacle absorption, defect motion, etc.?
- models able to give quantitative information?
- models able to describe candidate materials?
- periodic boundary conditions?
- dislocation density?
- statics or dynamics?
- are results for dislocation shape and critical stress comparable with elasticity theory?
- is high strain rate unavoidable? is it realistic?
- how good is simulation based on elasticity theory?
- what shape should be taken from MD or experiment for DD?
- incorporation of atomic-scale information from statics and/or dynamics into models based on elasticity theory?
- <u>other areas</u>: solutes, cracks

Irradiation microstructure - effect on mechanical properties

dislocations under stress move through field of irradiation-induced obstacles
 dislocation loops, SFTs, point defect clusters, voids, precipitates, etc.



<u>Issue</u>: how to model strengthening effects, yield phenomena, defect absorption, defect motion, etc.?

- · <u>Multiscale modelling</u> approach is necessary
 - <u>continuum</u> scale for strength, stress-strain characteristics, obstacle statistics effects, etc.
 - <u>atomic</u> scale for dislocation-obstacle interaction mechanisms, strength parameters, etc. (not obvious *a priori*)
 - nano- \rightarrow micro- \rightarrow meso-mechanics

<u>continuum</u> scale for strength, stress-strain characteristics, obstacle statistics effects, etc.



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and SIDNEY YIPT

 <u>atomic</u> scale for dislocation-obstacle interaction mechanisms, strength parameters, etc. (not obvious *a priori*)



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Atomic-scale

- Requirements
 - long-distance motion of dislocation
 - extraction of stress/strain and stress/strain-rate characteristics
 - T = OK and T > OK
 - atomic structure of obstacle and dislocation after interaction

<u>Tssue</u>: models able to give quantitative information?

- ~1-10M arrows
- simple, short-range potentials

<u>Issue</u>: models able to describe candidate materials?



Model - edge dislocation:



translation vector of two half crystals = translation vector of MD cell



MD cell (periodic boundaries along line <u>and</u> glide direction)

$\sigma_{\text{appl}} = F_{\text{ext}} / (L_b L)$





<u>Tssue</u>: dislocation density? e.g. $L_{b} = 120b$ H = 30bL = 120b $\rho_{b} = 1/(L_{b} + H)$ $\sim 1/(10^{4}b^{2})$ $\sim 1.6 \times 10^{15} m^{-2}$

Issue: statics or dynamics?

- T=OK (statics) simulations apply shear strain
- T>OK (dynamics) simulations apply shear stress or strain rate

<u>Issue</u>: periodic boundary conditions?





'true' region → good match to infinitebody stress field

Static simulation (T = 0K) Ex. <u>edge</u> dislocation \Rightarrow row of voids in α -Fe at T = 0K



void spacing L



void size D



<u>Issue</u>: are results for dislocation shape and critical stress comparable with elasticity theory?



 ϕ_e (line tension) should <u>not</u> to be equated to ϕ_e (atomic modelling)

<u>Issue</u>: what shape should be taken from MD or experiment for DD?



Angle?



 $\tau = T/bR$ in line tension, but what is T? (ln(R/r₀) and r₀ unknown) <u>Issue</u>: how good is simulation based on elasticity theory?

- · Bacon, Scattergood, Kocks (1973-)
 - the effect of self-interaction on the critical stress $\tau_c(L,D,\underline{b})$



data fits
 τ = (μb/2πL)[ln(D*) + B]
 where D* = (1/D+1/L)⁻¹ ≈ D





the atomic simulation stress
values are similar
so are the line shapes

<u>Issue</u>: incorporation of atomic-scale mechanisms into models based on elasticity theory?

Ex 1 - Dislocation climb due to vacancy absorption from voids



Ex 2 - Dislocation-induced transformation of Cu precipitates in Fe



Dynamics simulation (T > OK)

- dislocation dynamics at the atomic scale
- motion under constant applied strain-rate (10⁶-10⁸s⁻¹)

<u>Issue</u>: is high strain rate unavoidable? - is it realistic?

Ex 1. 2nm voids in Fe - strain rate 5×10⁶s⁻¹

Ó

T, K



- mechanisms of T-dependence?

T, K

Ex 2. Interaction of dislocation with row of glissile interstitial loops - constant applied stress



drag coefficient tb = (B_{disl}+B_{loop})v:
 drag due to moveable pinning points spacing L, mobility m:

$$B_{loop} = \frac{1}{mL} \text{ where } m = \frac{D}{kT}$$

and for loops:
$$D = f \frac{1}{2} b^2 v$$





<u>Issue</u>: incorporation of atomic-scale mechanisms from dynamics into models based on elasticity theory?

<u>General Issue</u>: incorporation of information from atomic-scale simulations into models based on elasticity theory?

- obstacle forces
- dislocation dynamics
- obstacle dynamics
- <u>Other areas</u>:
 - effects of solutes
 - dislocations near cracks

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