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# Reciprocity principle for radiative transfer models that use periodic boundary conditions

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#### Abstract

Many numerical models use periodic boundary conditions in solving the radiative transfer through heterogeneous media specified over a fixed domain. A reciprocity principle applicable to solutions from these models is derived for the common situation of a scattering and absorbing heterogeneous medium that is illuminated over the entire domain from a single direction. The derived reciprocity principle states that the domain-averaged bidirectional reflectance distribution function remains invariant when incoming and outgoing directions are interchanged, regardless of the heterogeneity of the medium and the size of the domain. This reciprocity principle provides a simple and useful benchmark test for radiative transfer models that use periodic boundary conditions. © 2002 Elsevier Science Ltd. All rights reserved.

Keywords: Reciprocity; Three-dimensional radiative transfer

## 1. Introduction

Reciprocity principles in radiative transfer theory have been widely used in deriving analytical and numerical solutions of radiative transfer problems [1,2], in testing numerical models of radiative transfer [3], and in remote sensing applications [4,5]. In the most widely studied case, that of a horizontally homogeneous medium completely illuminated at the top boundary by a constant, unidirectional irradiance, the reciprocity principle states that the bidirectional reflectance distribution function (BRDF), R, at the top boundary of the medium is invariant under a change in the incident and outward directions [6]; that is, at the top boundary of the medium,

$$R(-\Omega_1;\Omega_2) = R(-\Omega_2;\Omega_1), \tag{1}$$

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where  $\Omega$  represents the directional unit vector with the outward direction negative. For a unidirectional irradiance, F,

$$R(-\Omega_1;\Omega_2) = \frac{I(-\Omega_1;\Omega_2)}{\Omega_2 \cdot nF(\Omega_2)},\tag{2}$$

where I is the radiance and **n** is a unit vector that is outward normal at the top boundary (i.e.,  $\mathbf{n} \cdot \Omega < 0$  represents a direction incident at the top boundary of the medium).

Eq. (1) has been derived for the idealized case of a horizontally homogeneous medium completely illuminated at the top boundary by a constant irradiance [6]. For this case, the horizontal flux divergence is zero, and the solution of the radiative transfer is one-dimensional (1-D); that is, the radiance field only varies in the vertical dimension. Radiative transfer models for the solution of this idealized case require only the vertical distribution of the optical properties of the medium as input into the model.

In the case of a 3-D heterogeneous medium illuminated everywhere at the top boundary, the radiative transfer solution is much more complicated to handle than the 1-D case. One complicating factor is that the optical properties of the medium need to be specified in all three spatial dimensions. Often, only the optical properties of the medium over a finite horizontal domain are specified, even though the radiative transfer solution for the medium within the domain depends on the optical properties of the medium outside the domain. To handle this problem, periodic boundary conditions (PBC) are often employed. When PBC are employed, the optical properties of the medium within the model domain are assumed to indefinitely repeat themselves outside the model domain, as illustrated in Fig. 1. This type of boundary condition



Fig. 1. An illustration of a medium modeled in a radiative transfer model that uses periodic boundary conditions (PBC). Only the optical properties of the medium (shaded in gray) within the model domain, which is bound at the top by the surface D, are specified in the model. By employing PBC, the radiative transfer model's solution to the radiance field across the surface D effectively solves for the case when the medium indefinitely repeats itself around D. The dashed arrows represent the medium extending out to infinity in all horizontal directions.

is easily handled in model calculations. For example, in Monte Carlo radiative transfer models that employ PBC, a photon leaving the model domain reappears on the opposite side of the domain, traveling in the same direction as when it left the domain.

In general, 3-D radiative transfer solutions obey reciprocity principles that have spatial and directional attributes [7,8]. Note that Eq. (1) is strictly a directional reciprocity principle. The purpose of this article is to provide a formal proof that the domain-averaged BRDF obeys a directional reciprocity principle, regardless of the heterogeneity of the medium and the size of the model domain, for cases when the top boundary of the model domain is illuminated by a constant unidirectional source and the model employs PBC.

## 2. Proof

For an external unidirectional illumination, Di Girolamo [8] derived the following reciprocity principle:

$$\Omega_2 \cdot \boldsymbol{n} \int_D F_2(\boldsymbol{r}, \Omega_2) I(\boldsymbol{r}, -\Omega_2; C, \Omega_1) \, \mathrm{d}\boldsymbol{r} = \Omega_1 \cdot \boldsymbol{n} \int_C F_1(\boldsymbol{r}, \Omega_1) I(\boldsymbol{r}, -\Omega_1; D, \Omega_2) \, \mathrm{d}\boldsymbol{r}, \tag{3}$$

where  $I(\mathbf{r}, -\Omega_2; C, \Omega_1)$  is the radiance at position  $\mathbf{r}$  in direction  $-\Omega_2$  caused by illuminating the surface C with a unidirectional irradiance  $F_1(\mathbf{r}, \Omega_1)$  from direction  $\Omega_1, I(\mathbf{r}, -\Omega_1; D, \Omega_2)$  is the radiance at position  $\mathbf{r}$  in direction  $-\Omega_1$  caused by illuminating the surface D with a unidirectional irradiance  $F_2(\mathbf{r}, \Omega_2)$  from direction  $\Omega_2$ , and surface integration is taken over surfaces C and D. Eq. (3) is quite general and applies to any absorbing and scattering medium, regardless of its heterogeneity. The only assumption used in its derivation is that the scattering phase function of the scatterers that form the medium have time-reversal symmetry.

Surfaces C and D may represent any surface in space. However, for this proof, let C be the horizontal surface that extends out to infinity in all horizontal directions, located at the top boundary of the model domain, and illuminated everywhere with a constant unidirectional irradiance. In practice, the model domain is finite and is bound at the top by a horizontal surface, D. Thus, D is a subset of C. As shown in Fig. 1, the domain can be considered periodic out to infinity in all horizontal directions when PBC are used. Thus,

$$C = \sum_{i=1}^{N} D_i, \quad N \to \infty, \tag{4}$$

where  $D_i$  represents the top surface of an individual domain as shown in Fig. 1. Summing both sides of Eq. (3) over all  $D_i$  and dividing by N yields

$$\frac{\Omega_2 \cdot \boldsymbol{n}}{N} \sum_{i=1}^N \int_{D_i} F_2(\boldsymbol{r}, \Omega_2) I(\boldsymbol{r}, -\Omega_2; \boldsymbol{C}, \Omega_1) \, \mathrm{d}\boldsymbol{r} = \frac{\Omega_1 \cdot \boldsymbol{n}}{N} \sum_{i=1}^N \int_{\boldsymbol{C}} F_1(\boldsymbol{r}, \Omega_1) I(\boldsymbol{r}, -\Omega_1; D_i, \Omega_2) \, \mathrm{d}\boldsymbol{r}.$$
 (5)

For the case of PBC, the integral on the left-hand side of Eq. (5) is the same for all  $D_i$ ; that is

$$\int_{D_i} F_2(\mathbf{r}, \Omega_2) I(\mathbf{r}, -\Omega_2; C, \Omega_1) \, \mathrm{d}\mathbf{r} = \int_D F_2(\mathbf{r}, \Omega_2) I(\mathbf{r}, -\Omega_2; C, \Omega_1) \, \mathrm{d}\mathbf{r} \quad \forall \ D_i,$$
(6)

where D is any one realization of  $D_i$ , which is simply the surface of the top boundary of the model domain. With Eq. (6), Eq. (5) becomes

$$\Omega_2 \cdot \boldsymbol{n} \int_D F_2(\boldsymbol{r}, \Omega_2) I(\boldsymbol{r}, -\Omega_2; \boldsymbol{C}, \Omega_1) \, \mathrm{d}\boldsymbol{r} = \frac{\Omega_1 \cdot \boldsymbol{n}}{N} \sum_{i=1}^N \int_C F_1(\boldsymbol{r}, \Omega_1) I(\boldsymbol{r}, -\Omega_1; D_i, \Omega_2) \, \mathrm{d}\boldsymbol{r}.$$
(7)

Note, with reference to Eq. (4), the integral on the right-hand side of Eq. (7) can be written as

$$\int_{C} F_1(\mathbf{r}, \Omega_1) I(\mathbf{r}, -\Omega_1; D_i, \Omega_2) \, \mathrm{d}\mathbf{r} = \sum_{j=1}^{N} \int_{D_j} F_1(\mathbf{r}, \Omega_1) I(\mathbf{r}, -\Omega_1; D_i, \Omega_2) \, \mathrm{d}\mathbf{r}.$$
(8)

Substituting Eq. (8) into Eq. (7) yields

$$\Omega_{2} \cdot \boldsymbol{n} \int_{D} F_{2}(\boldsymbol{r}, \Omega_{2}) I(\boldsymbol{r}, -\Omega_{2}; \boldsymbol{C}, \Omega_{1}) \, d\boldsymbol{r} = \frac{\Omega_{1} \cdot \boldsymbol{n}}{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \int_{D_{j}} F_{1}(\boldsymbol{r}, \Omega_{1}) I(\boldsymbol{r}, -\Omega_{1}; D_{i}, \Omega_{2}) \, d\boldsymbol{r}$$

$$= \frac{\Omega_{1} \cdot \boldsymbol{n}}{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \int_{D_{j}} F_{1}(\boldsymbol{r}, \Omega_{1}) I(\boldsymbol{r}, -\Omega_{1}; D_{i}, \Omega_{2}) \, d\boldsymbol{r}$$

$$= \frac{\Omega_{1} \cdot \boldsymbol{n}}{N} \sum_{j=1}^{N} \int_{D_{j}} F_{1}(\boldsymbol{r}, \Omega_{1}) I(\boldsymbol{r}, -\Omega_{1}; \boldsymbol{C}, \Omega_{2}) \, d\boldsymbol{r}. \tag{9}$$

For the case of PBC, the integral on the right-hand side of Eq. (9) is the same for all  $D_j$ ; that is

$$\int_{D_j} F_1(\mathbf{r}, \Omega_1) I(\mathbf{r}, -\Omega_1; C, \Omega_2) \, \mathrm{d}\mathbf{r} = \int_D F_1(\mathbf{r}, \Omega_1) I(\mathbf{r}, -\Omega_1; C, \Omega_2) \, \mathrm{d}\mathbf{r} \quad \forall \ D_j,$$
(10)

where D is any one realization of  $D_j$ , which is simply the surface of the top boundary of the model domain. Substituting Eq. (10) into Eq. (9) yields

$$\Omega_2 \cdot \boldsymbol{n} \int_D F_2(\boldsymbol{r}, \Omega_2) I(\boldsymbol{r}, -\Omega_2; \boldsymbol{C}, \Omega_1) \, \mathrm{d}\boldsymbol{r} = \Omega_1 \cdot \boldsymbol{n} \int_D F_1(\boldsymbol{r}, \Omega_1) I(\boldsymbol{r}, -\Omega_1; \boldsymbol{C}, \Omega_2) \, \mathrm{d}\boldsymbol{r}.$$
(11)

In the case when  $F_1$  and  $F_2$  are independent of r (i.e., constant illumination), Eq. (11) can be written as

$$\frac{\int_D I(\mathbf{r}, -\Omega_2; C, \Omega_1) \,\mathrm{d}\mathbf{r}}{\Omega_1 \cdot \mathbf{n} F_1(\Omega_1)} = \frac{\int_D I(\mathbf{r}, -\Omega_1; C, \Omega_2) \,\mathrm{d}\mathbf{r}}{\Omega_2 \cdot \mathbf{n} F_2(\Omega_2)}.$$
(12)

When divided through by the area of D, Eq. (12) states that the average BRDF over the domain D obeys directional reciprocity.

#### 3. Discussion

It was shown in this article that the domain-averaged BRDF remains invariant when incoming and outgoing directions are interchanged, regardless of the heterogeneity of the medium and the size of the model domain, for cases when the top boundary of the model domain is illuminated

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by a constant unidirectional source and the model employs PBC. This statement is also true when vacuum boundary conditions (VBC) are employed; that is, photons exiting the domain never return. The proof is straightforward: for VBC, C = D = top boundary of model domain in Eq. (3). Setting  $F_1$  and  $F_2$  independent of r leads directly to Eq. (12).

Eq. (12) provides a useful benchmark test for 3-D radiative transfer codes. These codes traditionally have had very few benchmark tests upon which to draw. Eq. (12) is currently being used as a benchmark test in the NASA/DOE Intercomparison of 3-D Radiation Codes project [9].

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