

A Breathless Introduction to Generalized Information Theory

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**Modeling, Algorithms,
and Informatics (CCS-3)**



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ZOO OF AVAILABLE UQ FORMALISMS

Traditional:

- Set Theory
- Logic
- Probability Theory

More Novel:

- **Interval Analysis**
- **Fuzzy Systems**
- **Fuzzy and Monotone Measures**
- **Dempster-Shafer Evidence Theory**
- **Random Sets and Intervals**
- **Possibility Theory**
- **Probability Bounds**
- Rough Sets
- Imprecise Probabilities
- Probabilistic Robustness
- Info-Gap Theory



DEFER OBVIOUS CONTROVERSIES ...

- Why should I care, what's this good for, anyway?
- Isn't that just the same as probability?
- Why isn't probability good enough for you?
- Where do the numbers come from?
- Can you give me an example of where X does better than probability?
- Why do you use all those silly words like "fuzzy" and "belief"? Can you be serious?



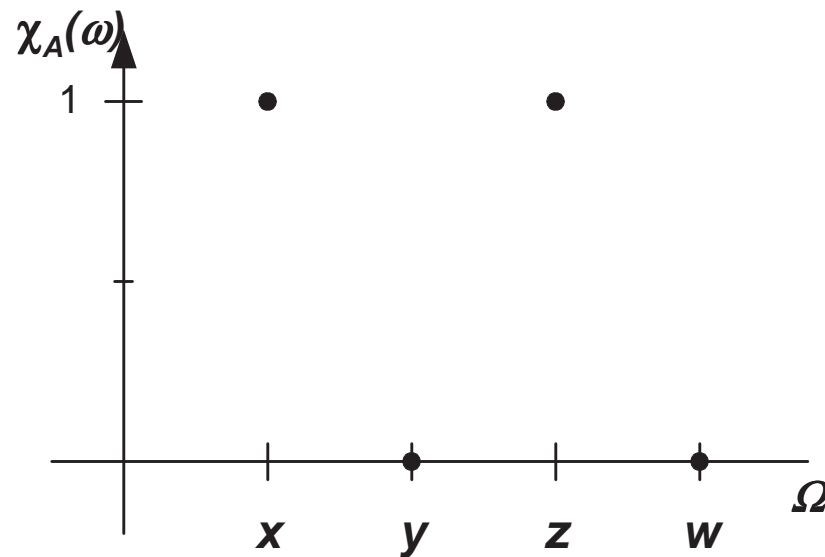
“CLASSICAL” POINT OF DEPARTURE: SETS AND LOGIC

Set Theory: $A \subseteq \Omega, \chi_A: \Omega \mapsto \{0, 1\}, \chi_A(\omega \in \Omega) = \begin{cases} 1 & \omega \in A \\ 0 & \omega \notin A \end{cases}$

Boolean Logic: $T(p) \in \{\text{false}, \text{true}\} = \{0, 1\}$

Isomorphism in Boolean Algebra:

Negation	$\neg p$	\overline{A}
Disjunction	$p \vee q$	$A \cup B$
Conjunction	$p \wedge q$	$A \cap B$
Implication	$p \rightarrow q$	$A \subseteq B$



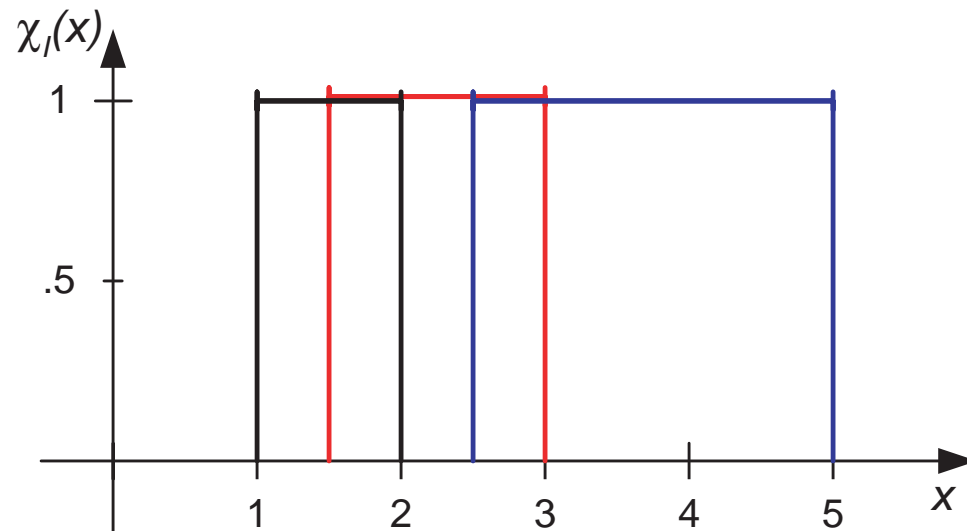
Boolean Logic = Sets

$$A = \{x, z\} \subseteq \Omega$$



INTERVALS

- $I = [I_l, I_u] \subseteq \mathbb{R}$
- $\chi_I(x) = \begin{cases} 1 & I_l \leq x \leq I_u \\ 0 & \text{otherwise} \end{cases}$
- $I_1 * I_2, * \in \{+, -, \times, \div\}$, etc.
- **Extension:** $x + y = [x, x] + [y, y]$



Sets ~ Boolean Logic

Restriction to R

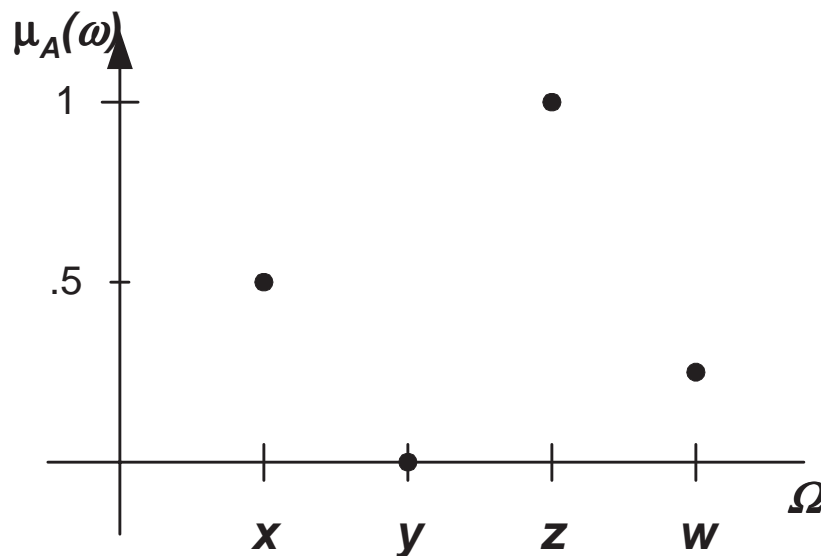
Intervals

$$[1, 2] + [1.5, 3] = [2.5, 5] \subseteq \mathbb{R}$$

FUZZINESS

Fuzzy Sets: $\tilde{A} \subseteq \Omega, \mu_{\tilde{A}}: \Omega \mapsto [0, 1], \mu_{\tilde{A}}(\omega) = \tilde{A}(\omega) \in [0, 1]$ is the “extent” or “degree” to which $\omega \in A$

Fuzzy Logic: $\tilde{T}(p) \in [0, 1]$



$$\tilde{A} = \{ \langle x, .5 \rangle, \langle z, 1 \rangle, \langle w, .25 \rangle \} \subseteq \Omega$$

Fuzzy Sets ~ Fuzzy Logic

To $[0, 1]$

Sets ~ Boolean Logic



FUZZY OPERATIONS

(canonical example)

$$\begin{array}{lll}
 \bar{A} & \mu_{\bar{A}}(\omega) = c(\tilde{A}(\omega)) & \mu_{\bar{A}}(\omega) = 1 - \tilde{A}(\omega) \\
 \tilde{A} \cup \tilde{B} & \mu_{\tilde{A} \cup \tilde{B}}(\omega) = \tilde{A}(\omega) \sqcup \tilde{B}(\omega) & \mu_{\tilde{A} \cup \tilde{B}}(\omega) = \tilde{A}(\omega) \vee \tilde{B}(\omega) \\
 \tilde{A} \cap \tilde{B} & \mu_{\tilde{A} \cap \tilde{B}}(\omega) = \tilde{A}(\omega) \sqcap \tilde{B}(\omega) & \mu_{\tilde{A} \cap \tilde{B}}(\omega) = \tilde{A}(\omega) \wedge \tilde{B}(\omega) \\
 \tilde{A} \subseteq \tilde{B} & \mu_{\tilde{A} \subseteq \tilde{B}}(\omega) = \tilde{A}(\omega) \rightarrow \tilde{B}(\omega) & \mu_{\tilde{A} \subseteq \tilde{B}}(\omega) = (1 - \tilde{A}(\omega)) \vee \tilde{B}(\omega)
 \end{array}$$

- \vee, \wedge are max and min
- $c: [0, 1] \mapsto [0, 1]$ is a complement function

$$c(0) = 1, c(1) = 0, x \leq y \rightarrow c(x) \geq c(y)$$
- \sqcap (\sqcup) is a triangular norm (conorm) (associative copulas/co-copula): $\sqcap, \sqcup: [0, 1]^2 \mapsto [0, 1]$, associative, monotonic,

$$\begin{array}{ll}
 0 \sqcup x = x \sqcup 0 = x, & 1 \sqcap x = x \sqcap 1 = x \\
 x \sqcap y \quad x \wedge y \geq x \times y & \geq 0 \vee (x + y - 1) \geq \lfloor x \rfloor \lfloor y \rfloor \\
 x \sqcup y \quad x \vee y \leq x + y - xy & \leq 1 \wedge (x + y) \leq \lceil x \rceil \lceil y \rceil
 \end{array}$$
- **Extension:** When $\tilde{A}, \tilde{B}: \Omega \mapsto \{0, 1\}$, then “crisp” set operations recovered



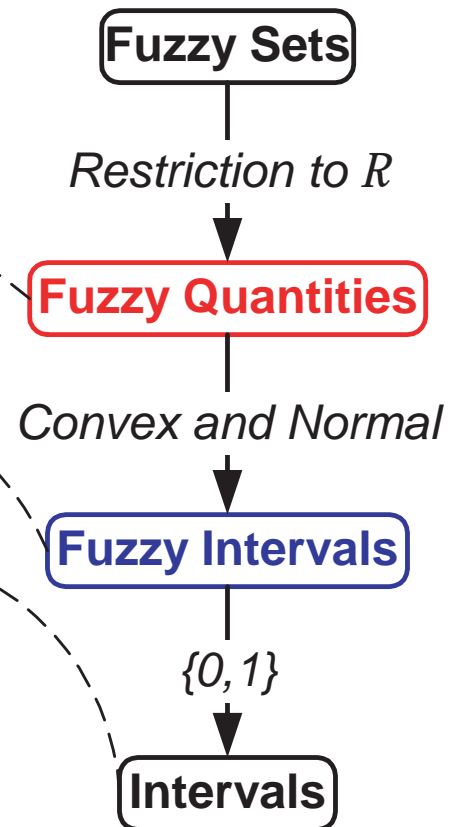
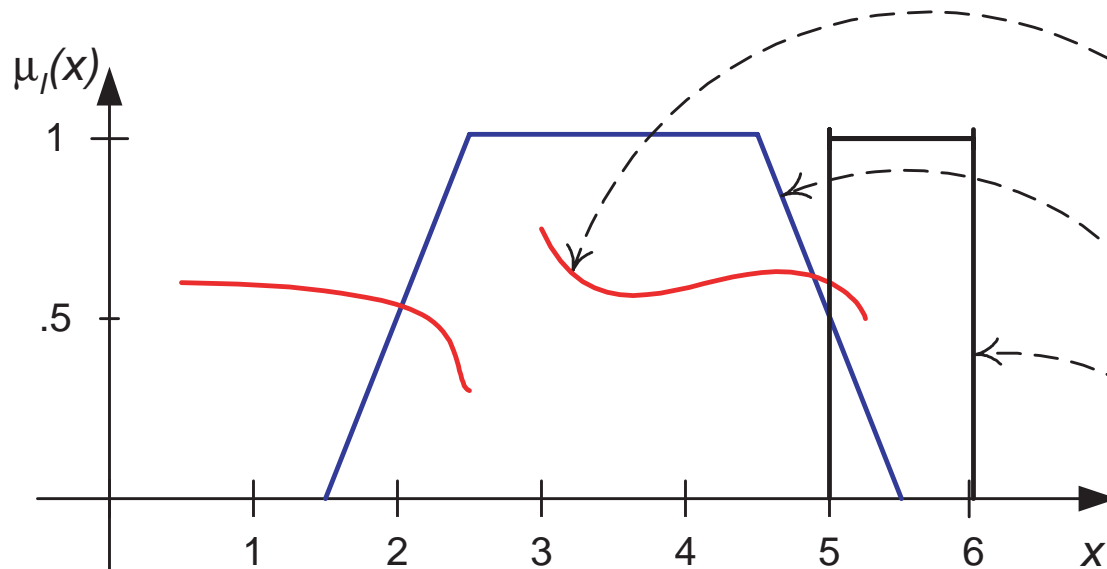
FUZZY QUANTITIES, NUMBERS AND INTERVALS

Fuzzy Quantity: Fuzzy subset of the line $\tilde{I} \subseteq \mathbb{R}$

Fuzzy Interval: Also convex and normal

Fuzzy Number: Single-peaked

Fuzzy Interval Operations: $\tilde{I} * \tilde{J}$, etc.



FUZZY SETS AS GENERALIZED “DENSITIES” OR “DISTRIBUTIONS”

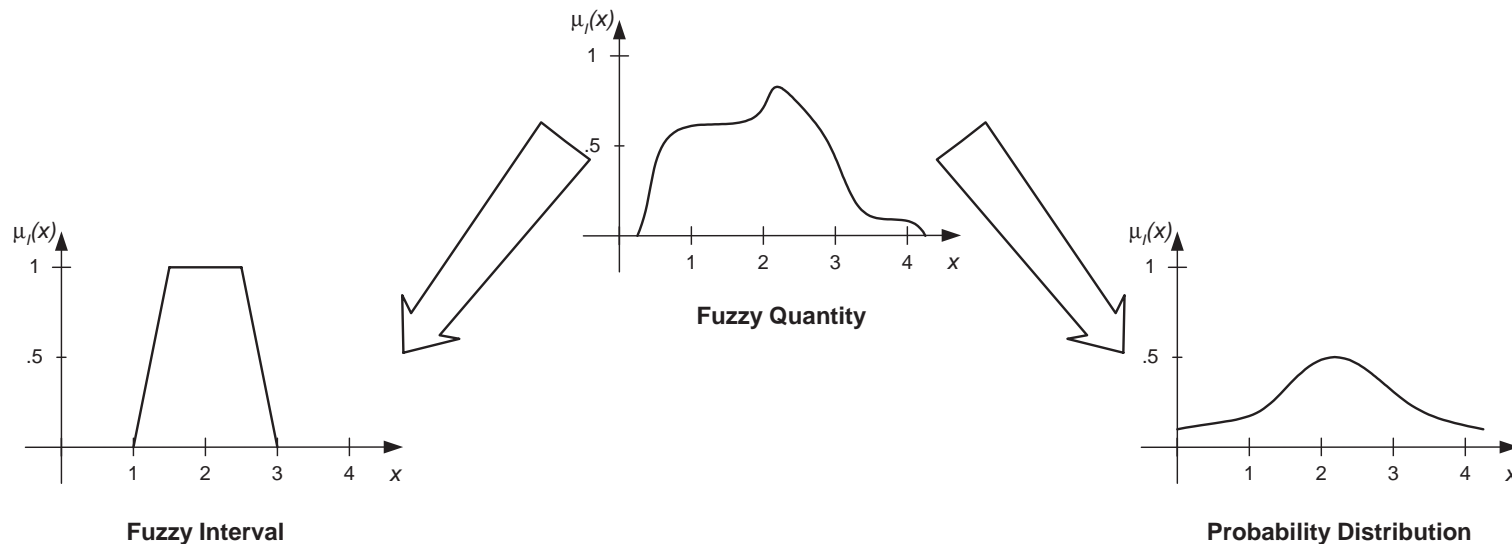
Fuzzy Quantity: $\tilde{I} \subseteq \mathbb{R}$

Probability Distribution: Fuzzy quantity where

$$\int_{x \in \mathbb{R}} \mu_{\tilde{I}}(x) = 1$$

Fuzzy Interval = Possibility Distribution: Fuzzy quantity where

$$\sup_{x \in \mathbb{R}} \mu_{\tilde{I}}(x) = 1$$



GENERALIZED MEASURES

- From point functions to set functions
- Generalizes relation between probability density and probability measure
- **Fuzzy Measure:** $\nu: 2^\Omega \mapsto [0, 1]$, where
$$\nu(\emptyset) = 0, \quad \nu(\Omega) = 1, \quad A \subseteq B \rightarrow \nu(A) \leq \nu(B).$$
- **Trace** as concept of density $\rho_\nu: \Omega \mapsto [0, 1], \rho_\nu(\omega) := \nu(\{\omega\})$.
- **Distributional** or **decomposable** if $\exists \sqcup, \nu(A) = \sqcup_{\omega \in A} \rho_\nu(\omega)$.
- **Normalization:** $\sqcup_{\omega \in \Omega} \rho_\nu(\omega) = 1$.
- A probability measure is a fuzzy measure ($A \subseteq B \rightarrow \Pr(A) \leq \Pr(B)$) with an additional additive constraint:
$$\Pr(A \cup B) - \Pr(A \cap B) = \Pr(A) + \Pr(B)$$
$$\rho_{\Pr}(\omega) = p(\omega)$$

Pr is distributional for $\sqcup = \dagger_b$



DEMPSTER-SHAFER EVIDENCE THEORY

- **Belief** and **plausibility** as dual fuzzy measures:

$$\text{Bel}(A \cup B) \geq \text{Bel}(A) + \text{Bel}(B) - \text{Bel}(A \cap B)$$

$$\text{Pl}(A \cap B) \leq \text{Bel}(A) + \text{Bel}(B) - \text{Bel}(A \cup B)$$

$$\text{Bel}(A) + \text{Bel}(\bar{A}) \leq 1, \quad \text{Pl}(A) + \text{Pl}(\bar{A}) \geq 1$$

$$\text{Bel}(A) = 1 - \text{Pl}(\bar{A}), \quad \text{Pl}(A) = 1 - \text{Bel}(\bar{A})$$

$$\text{Bel}(A) \leq \text{Pl}(A)$$

- Codetermined by a **basic probability assignment** $m: 2^\Omega \mapsto [0, 1]$ where $\sum_{A \subseteq \Omega} m(A) = 1$:

$$\text{Bel}(A) = \sum_{B \subseteq A} m(B), \quad \text{Pl}(A) = \sum_{B \cap A \neq \emptyset} m(B)$$

$$m(A) = \sum_{B \subseteq A} (-1)^{|A-B|} \text{Bel}(B) = \sum_{B \subseteq A} (-1)^{|A-B|} (1 - \text{Pl}(\bar{B}))$$



DEMPSTER-SHAFER EVIDENCE THEORY

Focal Set: $\mathcal{F} = \{A_j \subseteq \Omega : m(A_j) > 0\}$

Body of Evidence: $\langle \mathcal{F}, m \rangle = \langle \{A_j\}, \{m(A_j)\} \rangle$

Example:

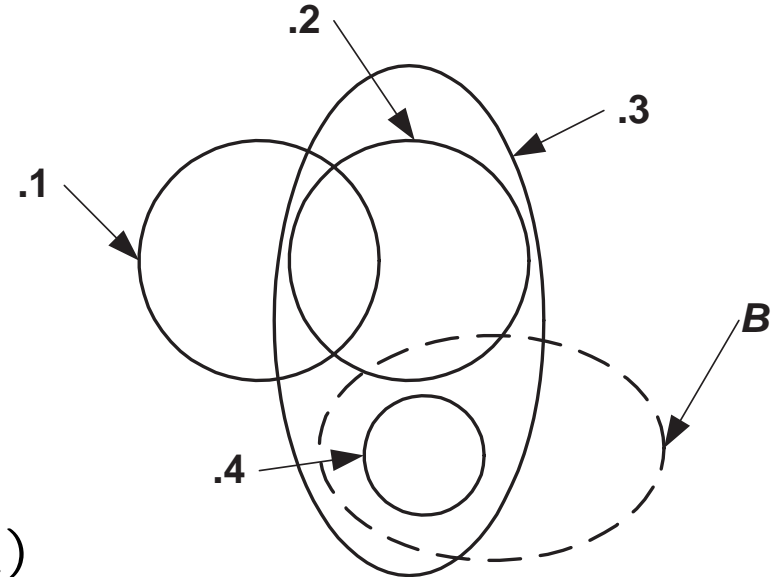
$$\mathcal{F} = \{A_1, A_2, A_3, A_4\}$$

$$m(A_1) = .1, m(A_2) = .2$$

$$m(A_3) = .3, m(A_4) = .4$$

$$\begin{aligned} \text{Bel}(B) &= \sum_{A_j \subseteq B} m(A_j) \\ &= m(A_4) = .4 \end{aligned}$$

$$\begin{aligned} \text{Pl}(B) &= \sum_{A_j \cap B \neq \emptyset} m(A_j) \\ &= m(A_2) + m(A_3) + m(A_4) \\ &= .2 + .3 + .4 = .9 \end{aligned}$$



RANDOM VARIABLES, RANDOM SETS, AND BODIES OF EVIDENCE

- Transform a body of evidence: $\langle \{A_j\}, \{m(A_j)\} \rangle = \{ \langle A_j, m(A_j) \rangle \}$
- Recalling that $\sum_{A_j} m(A_j) = 1$, then $m(A_j)$ sure looks like a density $p(A_j)$
- **Random Variable:** Given a probability space $\langle X, \Sigma, \text{Pr} \rangle$, then $S: X \mapsto \Omega$ is a random variable if S is Pr -measurable: $\forall \omega \in \Omega, S^{-1}(\omega) \in \Sigma$.
- **General Random Set:** $S: X \mapsto 2^\Omega - \{\emptyset\}$ is a random subset of Ω if S is Pr -measurable: $\forall \emptyset \neq A \subseteq \Omega, S^{-1}(A) \in \Sigma$. m acts as density of S .
- **Finite Random Set:** $S = \{ \langle A_j, m(A_j) \rangle \}$.
 $\text{Pr}(S = A) = m(A)$
 $\text{Pr}(S \subseteq A) = \text{Bel}(A), \quad \text{Pr}(S \cap A \neq \emptyset) = \text{Pl}(A)$

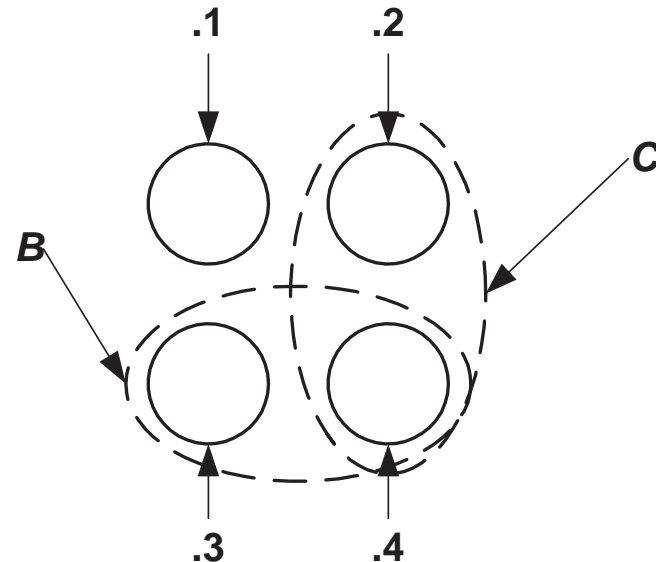


DECOMPOSABLE CASE: PROBABILITY MEASURES

- Assume \mathcal{F} is a disjoint class: $\forall A_1, A_2 \in \mathcal{F}, A_1 \cap A_2 = \emptyset$.
- More particularly, $\mathcal{F} = \{\{\omega\}\}$.
- $\text{Bel}(B) = \text{Pl}(B) = \text{Pr}(B)$
- Probability distribution $p(\omega) = \text{Pr}(\{\omega\}), \sqcup = +_b$:

$$\text{Pr}(A) = \sum_{\omega \in A} p(\omega), \quad \text{Pr}(\Omega) = \sum_{\omega \in \Omega} p(\omega) = 1$$

- $\text{Bel}(B) = \text{Pl}(B) = \text{Pr}(B) = .3 + .4 = .7$
- $\text{Pr}(B \cup C) = \text{Pr}(B) + \text{Pr}(C) - \text{Pr}(B \cap C) = .9$



DECOMPOSABLE CASE: POSSIBILITY MEASURES

- Assume \mathcal{F} is a nested class: $\forall A_1, A_2 \in \mathcal{F}, A_1 \subseteq A_2$ or $A_2 \subseteq A_1$
- PI becomes a **possibility measure** Π distributional for $\sqcup = \vee$:

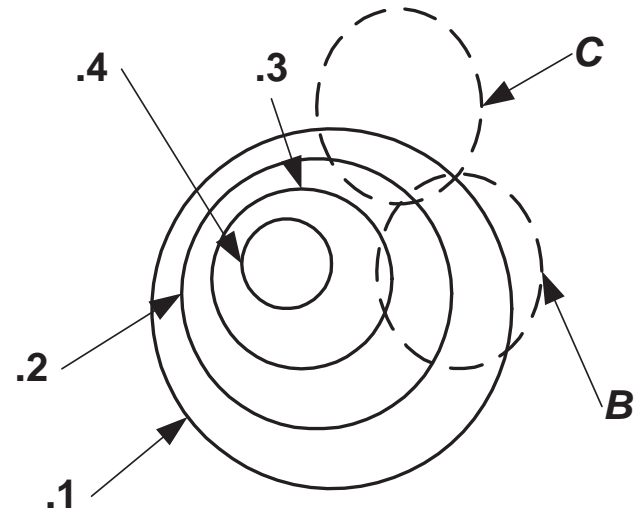
$$\Pi(B \cup C) = \Pi(B) \vee \Pi(C)$$

- Dual **necessity measure** $\text{Bel} = \eta$

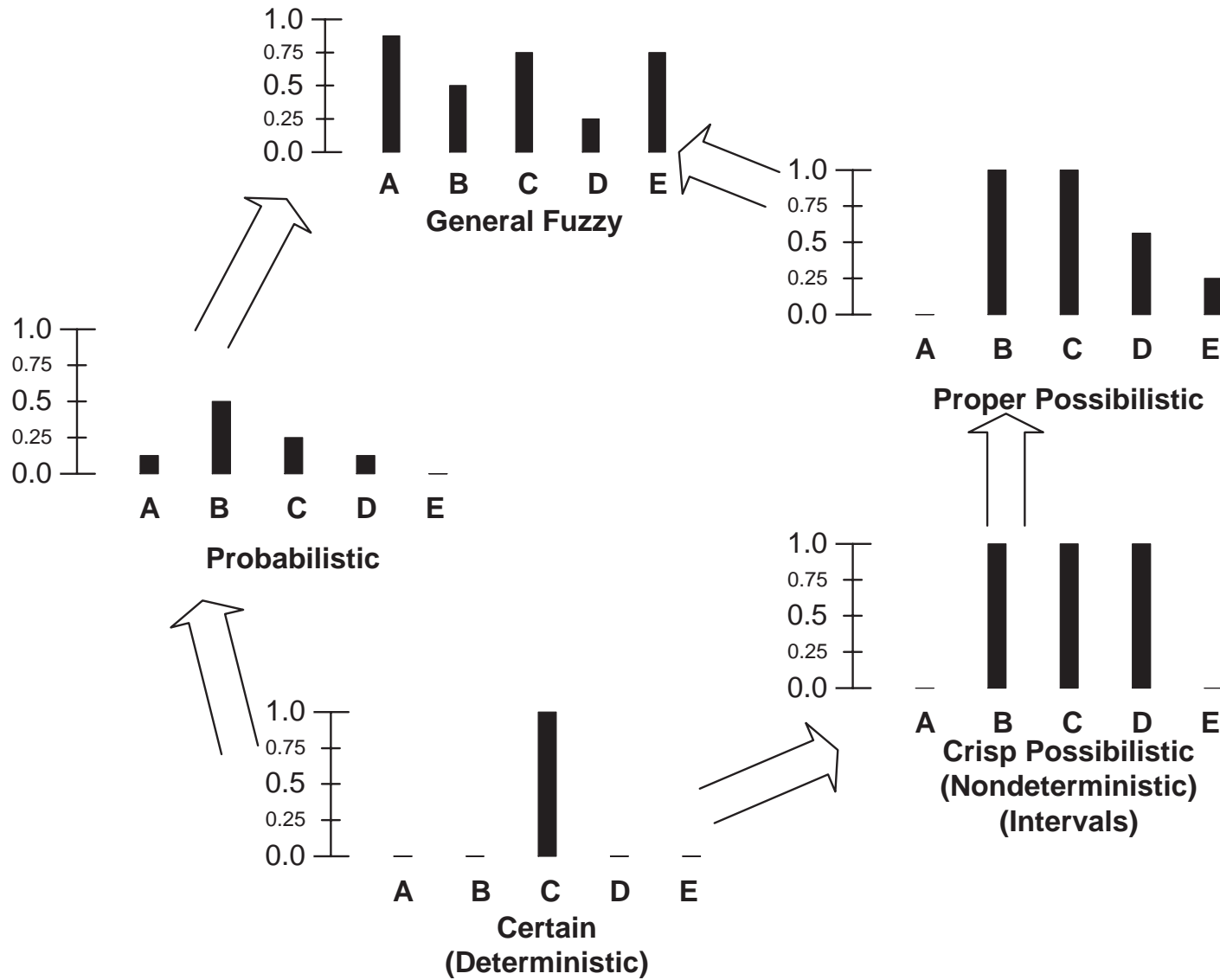
- Possibility distribution $\pi(\omega) = \Pi(\{\omega\}), \sqcup = \vee$:

$$\Pi(A) = \vee_{\omega \in A} \pi(\omega), \quad \Pi(\Omega) = \vee_{\omega \in \Omega} \pi(\omega) = 1$$

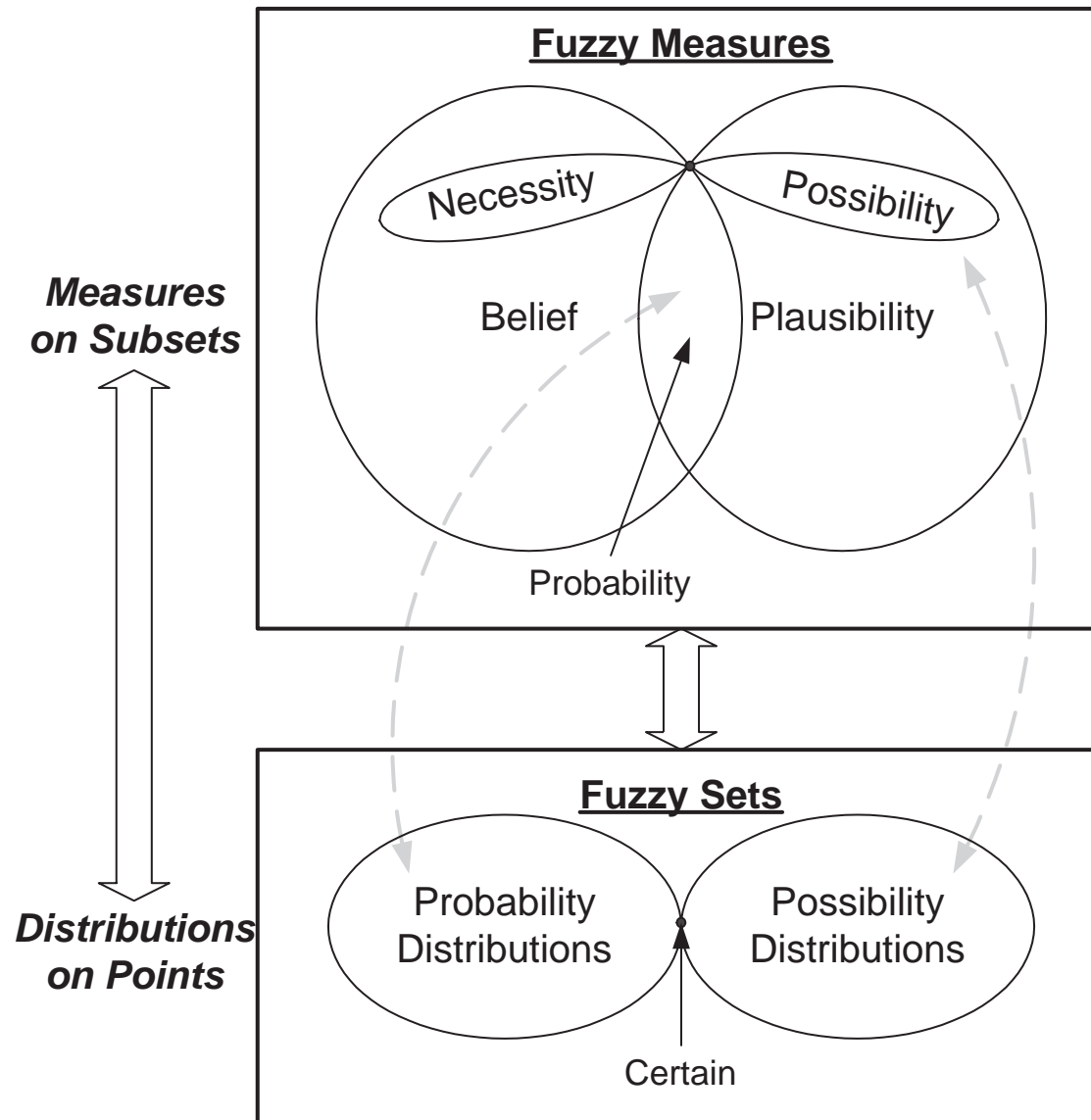
$$\begin{aligned} \Pi(B \cup C) &= \text{PI}(B \cup C) \\ &= .1 + .2 + .3 = .6 \\ &= \Pi(B) \vee \Pi(C) = .6 \vee .3 \end{aligned}$$



CLASSES OF MEASURE TRACES

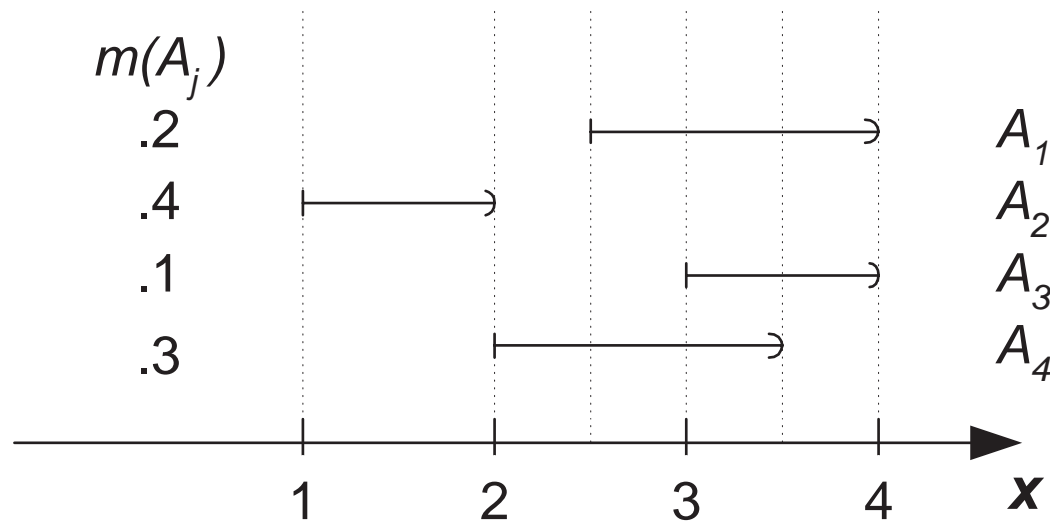


MEASURES AND DISTRIBUTIONS



RANDOM INTERVALS

- $\mathcal{D} := \{[a, b) \subseteq \mathbb{R} : a, b \in \mathbb{R}, a < b\}$.
- **Random Interval:** \mathcal{A} , is a random set on $\Omega = \mathbb{R}$ for which $\mathcal{F}(\mathcal{A}) = \{I_j\} \subseteq \mathcal{D}$



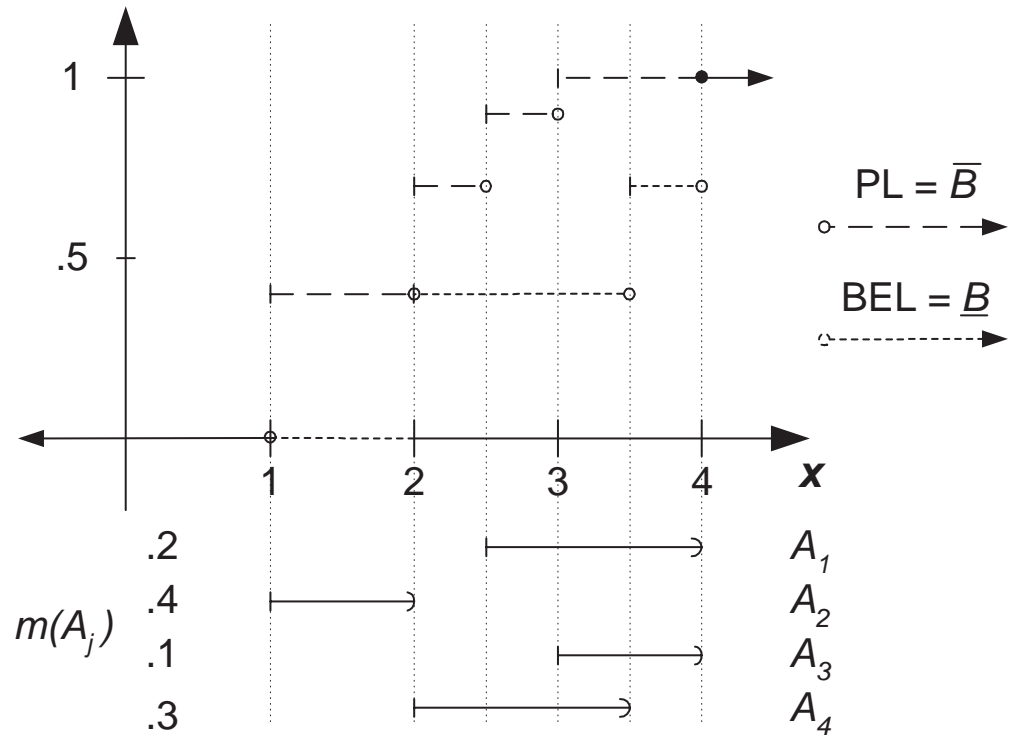
PROBABILITY BOUNDS

- **Cumulative Belief and Plausibility:** $PL, BEL: \mathbb{R} \mapsto [0, 1]$
 $BEL(x) := Bel((-\infty, x)), \quad PL(x) := Pl((-\infty, x)).$
- **Probability Bounds:** (Ferson) $\mathcal{B} := \langle \underline{B}, \overline{B} \rangle$, where $\underline{B}, \overline{B}: \mathbb{R} \mapsto [0, 1]$, $\lim_{x \rightarrow -\infty} B(x) \rightarrow 0$, $\lim_{x \rightarrow \infty} B(x) \rightarrow 1$, and $\underline{B}, \overline{B}$ are monotonic with $\underline{B} \leq \overline{B}$.



RANDOM INTERVALS TO PROBABILITY BOUNDS

- Given a random interval \mathcal{A} , then $\langle \text{BEL}, \text{PL} \rangle$ is a PBound.
- Given a PBound \mathcal{B} , then $\overline{B} - \underline{B} = \rho_{PI}$
- If a random interval \mathcal{A} is consonant, then $\overline{B} - \underline{B} = \pi$ is its possibility distribution



CURRENT PROBLEM

- Set of parameters $X = \{X_i\}$ with

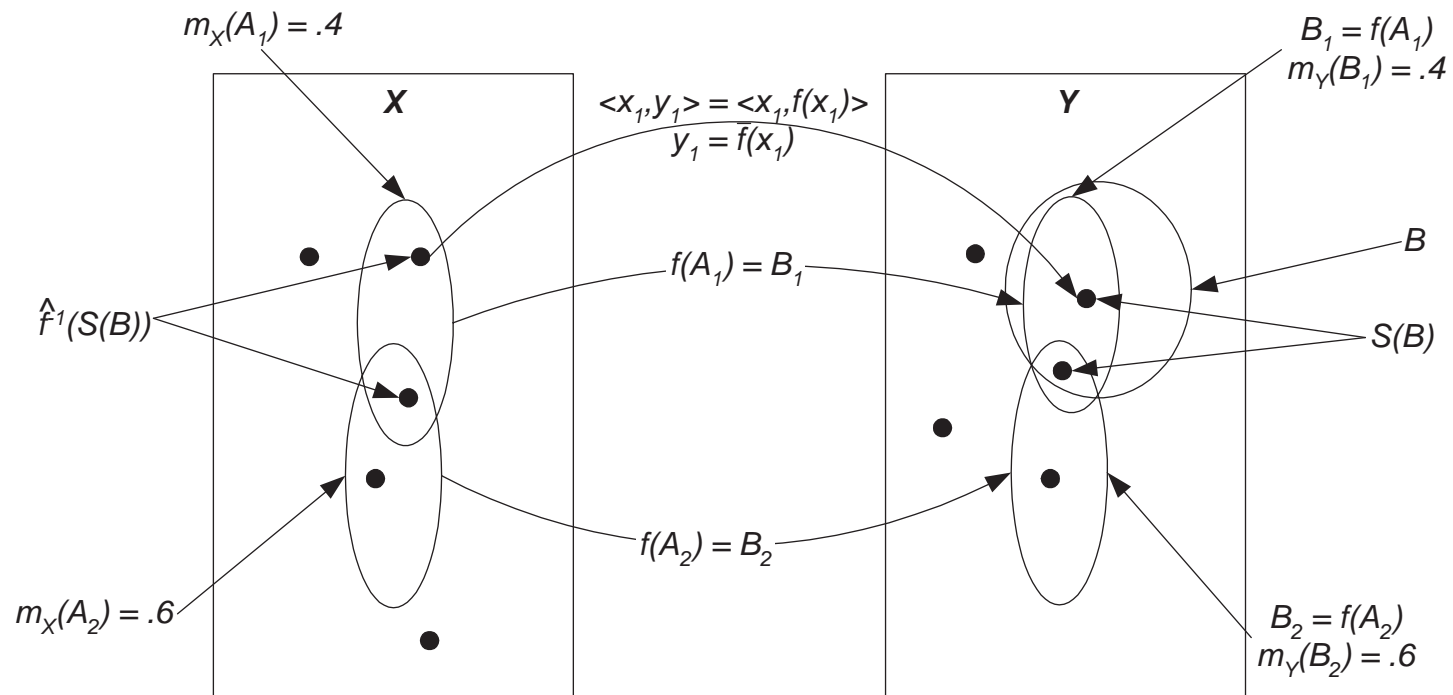
$$\mathbf{X} := \times_i X_i$$

- Unknown function $f: \mathbf{X} \mapsto \mathbf{Y}, f(\vec{x}) = \vec{y}$
- Knowledge on \mathbf{X} characterized by a random interval structure: statistical collection of intervals \mathcal{A}_i on each X_i
- Induces global n -dimensional \mathcal{A} on \mathbf{X}
- f induces an output random interval $f(\mathcal{A})$ on \mathbf{Y}
- What knowledge of $f(\mathcal{A})$ can be gained by samples of $f(\vec{x})$?



SAMPLING ESTIMATION OF RANDOM SET PROPAGATION

- Initially simplify to finite random sets
- Estimate $Pl_Y(B)$ by $\widehat{Pl}_Y(B) := Pl_X(\widehat{f}^{-1}(S(B)))$



BREATHE!

Thank you!

