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User's Guide Programs for Processing Altimeter Data Over Inland Seas

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Programs for Processing
Altimeter Data
Over Inland Seas**

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PREFACE

Satellite-based altimetric data taken by GEOS-3 and SEASAT over the Black Sea and Caspian Sea have been analyzed and a least-squares collocation technique used to predict the geoid undulations on a $.25^\circ \times .25^\circ$ grid and to transform these geoid undulations to free air gravity anomalies. The programs used to process and analyze these altimeter data are described and documented herein. A brief user's guide is presented for each program that summarizes the purpose for, input to, and output from the code. This is followed by a complete listing of well commented code in the FORTRAN-77 language. These programs read, organize, and plot profiles and ground tracks of the altimeter data. They also identify crossovers between altimeter passes, determine and remove biases from the data, sort, and grid the corrected altimetric sea surface heights. Other programs generate contour plots of the gridded data, determine the gravity and geoid auto- and cross-covariance functions, and use these functions in a collocation estimate of gravity anomalies.

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I INTRODUCTION

The programs described in this document have been developed to process GEODYN-formatted satellite altimeter data, and to apply the processed results to predict geoid undulations and gravity anomalies of inland sea areas (Au *et al.*, 1988). These programs are written in standard FORTRAN 77 and are designed to run on the NSESCC IBM 3081 (MVS) computer. Because of the experimental nature of these programs, they are tailored to the geographical area analyzed. The attached program listings are customized for processing the altimeter data over the Black Sea. Users interested in the Caspian Sea data are expected to modify each program, although the required modifications are generally minor. Program control parameters are defined in the programs via PARAMETER statements and/or DATA statements. Other auxiliary parameters, such as labels, are 'hard-wired' into the programs. Large data files are read in or written out through different input or output units. The program listings of these programs are accompanied by sample IBM Job Control Language (JCL) images. Familiarity with IBM JCL and the TEMPLATE graphic package is assumed.

II USER'S GUIDES

PRTDATA

This program reads a GEODYN-formatted altimeter data file, groups together the data records that belong to a satellite pass and extracts relevant geodetic and auxiliary information from each satellite pass. The process is repeated for all the passes in the input data file. For each satellite pass, the starting time in Julian day, the satellite identification number, the duration in seconds, the direction of the data arc (ascending or descending in latitude) and the number of data records associated with the pass are printed. For each data record, the corresponding record number in the file, the fraction of day in which the measurement is taken, the absolute altimeter observation (meters), the ground track geodetic latitude and longitude and the observed surface elevation (meters) are printed. If a reference geoid undulation surface is supplied to the program, a comparison between the reference geoid undulation and the measured one is given for each data record.

User-provided Parameters:

MAXREC	Maximum number of records in the input altimeter data file.
XMIN	Starting longitude of the input reference geoid undulation surface.
XMAX	Ending longitude of the input reference geoid undulation surface.
YMIN	Starting latitude of the input reference geoid undulation surface.
YMAX	Ending latitude of the input reference geoid undulation surface.
DX	Increment in longitude of the input geoid reference undulation surface.
DY	Increment in latitude of the input geoid reference undulation surface.

Input:

Reference geoid undulation surface (Unit 5):

The input file should be organized as follows:

starting geodetic latitude YMIN (unformatted).
geoid undulations of associated longitude from XMIN to XMAX
incremented by DX (6(2X,F10.3)).

.
YMIN + DY.
geoid undulations of associated longitude from XMIN to XMAX incremented by DX.

.
ending geodetic latitude YMAX.
geoid undulations of associated longitude from XMIN to XMAX incremented by DX.

Altimeter data file (Unit 8): This is a binary file of altimeter data written in GEODYN
format.

Output:

Organized printout (Unit 6).

Reference geoid undulation corresponding to each data record (Unit 9): Each output record
contains latitude, longitude and reference geoid undulation (5X,2F9.3,45X,F9.3). This
output file may be used in subsequent programs for the purpose of comparison between
measured geoid undulations and reference values.

PLTGRP

This program reads a GEODYN-formatted altimeter data file, groups together the data records that belong to a satellite pass and plots the surface elevation profile of each pass as a function of time (fraction of day past midnight). The process is repeated for all the passes in the input data file. A surface elevation profile will not be plotted if there are less than four records in the satellite pass. The graphic software package, TEMPLATE, is used with this program.

Input:

Altimeter data file (Unit 5): This is a binary file of altimeter data written in GEODYN format.

Output:

Summary (Unit 6): Number of records read in input data file and the number of surface elevation profiles plotted.

Plots of surface elevation profiles of each satellite pass as a function of time.

GRNTRK

This program reads a GEODYN-formatted altimeter data file, groups together the data records that belong to a satellite pass and plots the ground track onto a geographical map. The process is repeated for all the passes in the input data file. A graphic software package, TEMPLATE, is used in this program.

User-provided Parameters:

MAXREC Maximum number of records in the input altimeter data file.
NMAX Maximum number of data records associated with one satellite pass.
VLONG1 Starting east longitude of the output geographical map.
VLONG2 Ending east longitude of the output geographical map.
VLAT1 Starting latitude of the output geographical map.
VLAT2 Ending latitude of the output geographical map.

Input:

Altimeter data file (Unit 5): This is a binary file of altimeter data written in GEODYN format.

Output:

Summary (Unit 6): Number of records read in the input file, number of GEOS-3 and SEASAT ground tracks plotted.

Ground tracks plot.

XOVERO

This program reads a GEODYN-formatted altimeter data file, approximates the ground track of each satellite pass as a second-degree equation and determines potential crossovers of these satellite passes. An overview of satellite crossovers is provided by this program before crossover adjustments are performed in a subsequent program, XOVER. Crossovers that occur at data gaps can be edited out.

User-provided Parameters:

- MPASS** **Maximum number of satellite passes in the input altimeter data file.**
- XMAX** **Maximum number of data records associated with a satellite pass.**
- SIGE** **Discriminating criterion of a data spike. Observed surface elevation that deviates from adjacent one by more than SIGE will be treated as noise and, thereby, will not be included in subsequent data analyses.**

Input:

Altimeter data file (Unit 3): This is a binary file of altimeter data written in GEODYN format.

Output:

Summary (Unit 6): Possible satellite crossovers, including satellite types, crossover locations.

XOVER

Crossover adjustment is performed in this program. This program reads a GEODYN-formatted altimeter data file, approximates each satellite pass ground track by a second-degree equation and determines possible crossovers of these satellite passes. The geoid height at each crossover location for each pass is obtained by interpolating screened data in that pass. A weighted least-squares analysis is performed to determine biases for each pass so that the crossover residuals are minimized, holding one pass fixed as the reference pass. All satellite passes are then rectified to a common reference geoid through the chosen reference pass. The output includes the RMS of crossover residual before and after orbit bias adjustment, a GEODYN-formatted file with the original observed surface elevation replaced by the adjusted one, and an error covariance matrix of the bias adjustment.

User-provided Parameters:

SIGMAG	Assumed noise for GEOS-3 orbit.
SIGMAS	Assumed noise for SEASAT orbit.
XDMAX	Maximum crossover residual for that crossover to be considered.
ETOP	Upper limit of observed surface elevation to be accepted.
EBOT	Lower limit of observed surface elevation to be considered.
MAXOVR	Maximum number of crossovers.
MPASS	Maximum number of satellite passes in the input altimeter data file.
NMAX	Maximum number of data records associated with a satellite pass.
SIGE	Discrimination criterion of a data spike. Observed surface elevation that deviates from adjacent one by more than SIGE will be treated as noise and, thereby, will not be included in subsequent data analyses.

Input:

Reference geoid undulation model (Unit 2): Each record in the file contains latitude,

longitude and reference geoid undulation (5X,2F9.3,45X,F9.3). This is the output file from program PRTDATA.

Altimeter data file (Unit 3): This is a binary file of altimeter data written in GEODYN format.

Crossovers to be edited out (Unit 4): This file contains records of two passes that are to be excluded from crossover adjustment. Each record contains three variables, JC, IP, and JP, where IP and JP are the pass number of the two passes that form the crossover, and JC is an editing criterion. If JC is set to zero, that crossover will be excluded from crossover adjustment. The format of the record is (I1,2I10).

Output:

Adjusted altimeter data file (Unit 8): This is a binary file written in GEODYN format with the observed surface elevation replaced by the adjusted one.

Error covariance matrix of the bias adjustment (Unit 9): The format of this output matrix is (4D20.13).

PLTAEP

This program reads an adjusted altimeter data file in GEODYN format and a file containing reference geoid undulation that is in one-to-one correspondence with the adjusted altimeter data, and plots the adjusted elevation profile of each satellite pass. The reference geoid is also plotted onto each elevation profile for comparison. A graphic software package, **TEMPLATE**, is used in this program.

User-provided Parameters:

MAXPLT	Maximum number of plots to be performed.
ETOP	Upper limit of observed surface elevation to be accepted.
EBOT	Lower limit of observed surface elevation to be considered.
NMAX	Maximum number of data records associated with a satellite pass.
NINT	Number of intervals used in a smoothing routine to plot out a smoothed elevation profile of a satellite pass.
SIGE	Discriminating criterion of a data spike. Observed surface elevation that deviates from adjacent one by more than SIGE will be treated as noise and, thereby, will not be included in subsequent data analyses.
SIGT	Not used.

Input:

Reference geoid undulation model (Unit 3): Each record in the file contains latitude, longitude and reference geoid undulation (5X,2F9.3,45X,F9.3). This is the output file from program PRTDATA.

Altimeter data file (Unit 4): This is a binary file of altimeter data written in GEODYN format.

Output:

Plots of altimeter surface elevation profiles adjusted for orbit biases. A reference geoid is superimposed on each profile for comparison.

SORT

This program reads an adjusted altimeter data file and determines with which grid points a data record should be associated, according to a specified cap size. Each GEODYN data record is checked for grid point association. For each grid point associated with a record, an output record is written with latitude, longitude, adjusted surface elevation, grid points identification number, grid point counter, associated pass number, and standard deviation of that data point. A sort/merge process (TSORT in MVS system) can be performed to group together all the altimeter data points that are associated to each grid point.

User-provided Parameters:

ETOP	Upper limit of adjusted surface elevation to be accepted.
EBOT	Lower limit of adjusted surface elevation to be considered.
SIGE	Discriminating criterion of a data spike. Observed surface elevation that deviates from adjacent one by more than SIGE will be treated as noise and, thereby, will not be included in subsequent data analyses.
MIREC	Maximum number of data records associated with a satellite pass.
XMIN	Starting longitude of the chosen grid.
XMAX	Ending longitude of the chosen grid.
YMIN	Starting latitude of the chosen grid.
YMAX	Ending latitude of the chosen grid.
DX	Increment in longitude of the chosen grid.
DY	Increment in latitude of the chosen grid.
CAP	Cap size within which altimeter data is considered.

Input:

Altimeter data file (Unit 5): This is a binary file of adjusted altimeter data written in GEODYN format.

Output:

Summary (Unit 6): Data partitioning information and data distribution map.

Altimeter data partition file (Unit 8): Each record in this binary file contains the longitude, latitude, adjusted surface elevation, grid identification index for longitude, grid identification index for latitude, satellite pass number, and standard deviation of the adjusted surface elevation. In order to be used in subsequent Program GEOID, this output file should be sorted in ascending order of the grid longitude index and grid latitude index.

WGTAVG

This program reads an adjusted altimeter data file written in GEODYN format, sorts each data record into a .25° x .25° grid, and determines a weighted average of the data points at each grid point.

User-provided Parameters:

ETOP	Upper limit of adjusted surface elevation to be accepted.
EBOT	Lower limit of adjusted surface elevation to be considered.
SIGE	Discrimination criterion of a data spike. Observed surface elevation that deviates from adjacent one by more than SIGE will be treated as noise and, thereby, will not be included in subsequent data analyses.
MIREC	Maximum number of data records associated with a satellite pass.
XMIN	Starting longitude of the chosen grid.
XMAX	Ending longitude of the chosen grid.
YMIN	Starting latitude of the chosen grid.
YMAX	Ending latitude of the chosen grid.
DX	Increment in longitude of the chosen grid.
DY	Increment in latitude of the chosen grid.
MPX	Maximum number of data points associated with a grid point.

Input:

Altimeter data file (Unit 5): This is a binary file of adjusted altimeter data written in GEODYN format.

Output:

Summary (Unit 6): Data partitioning information, weighted averages and data distribution map.

Gridded weighted-averages (Unit 8): The output file contains sequences of grid longitude, grid latitude and surface elevation. The format of the output file is (3(2F7.2,F12.4)).

CONTOUR

This program reads a gridded data file and plots the corresponding contour. A geographical map defined within the chosen grid boundary is superimposed on the contour. Any grid point that has no physical value should be masked with the value of -1000.0 and it will not be contoured. A graphic software package, TEMPLATE, is used in this program.

User-provided Parameters:

BIAS	Overall bias that is to be subtracted off all the data points.
XMIN	Starting longitude of the chosen grid.
XMAX	Ending longitude of the chosen grid.
YMIN	Starting latitude of the chosen grid.
YMAX	Ending latitude of the chosen grid.
DX	Increment in longitude of the chosen grid.
DY	Increment in latitude of the chosen grid.
CHGH	Upper limit of contour.
CLOW	Lower limit of contour.
CINC	Increment interval of contour.
CLAB	Frequency of labelling the contour lines.

Input:

Gridded data file (Unit 5): The output file contains sequences of grid longitude, grid latitude and surface elevation. The format of the output file is (3(2F7.2,F12.4)).

Output:

A contour map of the gridded data.

GEOID

This program predicts and grids geoid undulations using a collocation technique. The input dataset is a sorted version, according to grid longitude and latitude indices, of the output file from Program SORT.

User-provided Parameters:

MPASS	Number of satellite passes considered in the adjusted altimeter dataset.
NREFP	Relative position number of the reference satellite pass in the altimeter dataset.
KUTOFF	Minimum number of data points associated with a grid point to be considered for geoid prediction.
LCTV	Set to 1.
MTR	Maximum number of data records associated with a grid point.
XMIN	Starting longitude of the chosen grid.
XMAX	Ending longitude of the chosen grid.
YMIN	Starting latitude of the chosen grid.
YMAX	Ending latitude of the chosen grid.
DX	Increment in longitude of the chosen grid.
DY	Increment in latitude of the chosen grid.
LCT	Number of intervals in the given covariance function.

Input:

Covariance table (Unit 5): Each record in the covariance table contains distance in degree, geoid-to-geoid value, geoid-to-gravity value, and gravity-to-gravity value. The format of the input file is (1X,D10.4,3D20.13).

Sorted altimeter data file (Unit 8): This is a sorted version of the binary output file from Program SORT. The sorting should be performed in ascending order of grid longitude index and then of grid latitude index.

Error covariance matrix of orbit adjustment (Unit 11): This is the output error covariance matrix from Program XOVER.

Output:

Gridded geoid undulations (Unit 9): The output file contains sequences of grid longitude, grid latitude and surface elevation. The format of the output file is (3(2F7.2,F12.4)).

Gridded variance of predictions (Unit 10): The output file contains sequences of grid longitude, grid latitude and variance in cm. The format of the output file is (3(2F7.2,F12.4)).

EMPCOV

This program determines a set of residual local empirical covariance functions based on a convolution technique. Reference models as well as gridded data of both geoid undulations and gravity anomalies must be supplied to the program.

User-provided Parameters:

XMIN Starting longitude of the chosen grid.
XMAX Ending longitude of the chosen grid.
YMIN Starting latitude of the chosen grid.
YMAX Ending latitude of the chosen grid.
DXY Increment in longitude and latitude of the chosen grid.

Input:

Reference geoid undulation surface (Unit 7):

The input file should be organized as follows:

starting geodetic latitude YMIN (unformatted).

geoid undulations of associated longitude from XMIN to XMAX incremented by DXY (6(2X,F10.3)).

.

YMIN + DXY.

geoid undulations of associated longitude from XMIN to XMAX incremented by DX.

.

ending geodetic latitude YMAX.

geoid undulations of associated longitude from XMIN to XMAX incremented by DX.

Reference gravity anomalies surface (Unit 9):

Input format similar to Unit 7.

Gridded geoid undulations (Unit 8): The input file contains sequences of grid longitude, grid latitude and surface elevation. The format of the input file is (3(2F7.2,F12.4)).

Gridded gravity anomalies (Unit 10): The input file contains sequences of grid

longitude, grid latitude and gravity anomalies. The format of the input file is (3(2F7.2,F12.4).

Output:

Covariance table (Unit 11): Each record in the covariance table contains distance in degree, geoid-to-geoid value, geoid-to-gravity value, and gravity-to-gravity value. The format of the output file is (1X,D10.4,3D20.13).

GRAVEN

This program transforms gridded geoid undulation data into gravity anomalies. Three reference models, Rapp's 36 x 36, 180 x 180, and 300 x 300 gravity models (Rapp, 1986) can be used as reference surfaces in this program. An iterative process to refine the reference surfaces can also be performed by this program.

User-provided Parameters:

MODEL	Reference model to be used. It can be 36, 180 or 300, which corresponds to Rapp's 36 x 36, 180 x 180, and 300 x 300 models.
ANOISE	Assumed noise of the geoid undulation data.
ITM	Maximum number of iterations to be carried out. When there is no iteration to be performed, ITM is set to zero.
CAP	Integration cap size used.
IPRT	Option for printouts. Set IPRT to zero for minimum output.
CNVRGE	Convergence criterion for iterative process.
SCX	Set to 1.
KUTOFF	Minimum number of data points associated with a grid point to be considered for gravity transformation.
MTR	Maximum number of data records associated with a grid point.
XMIN	Starting longitude of the chosen grid.
XMAX	Ending longitude of the chosen grid.
YMIN	Starting latitude of the chosen grid.
YMAX	Ending latitude of the chosen grid.
XG1	Set equal to XMIN.
XG2	Set equal to XMAX.
YG1	Set equal to YMIN.
YG2	Set equal to YMAX.

DX Increment in longitude of the chosen grid.

DY Increment in latitude of the chosen grid.

Input:

Covariance table (Unit 5): Each record in the covariance table contains distance in degree, geoid-to-geoid value, geoid-to-gravity value, and gravity-to-gravity value. The format of the input file is (1X,D10.4,3D20.13).

Gridded geoid undulations (Unit 8): The input file contains sequences of grid longitude, grid latitude and surface elevation. The format of the input file is (3(2F7.2,F12.4).

Gridded variance of geoid prediction (Unit 9): The input file contains sequences of grid longitude, grid latitude and variance in cm. The format of the input file is (3(2F7.2,F12.4).

Reference geoid undulation surface, Rapp's 180 x 180 model (Unit 10):

The input file should be organized as follows:

starting geodetic latitude YMIN (unformatted).

geoid undulations of associated longitude from XMIN to XMAX incremented by DX (6(2X,F10.3)).

.

YMIN + DY.

geoid undulations of associated longitude from XMIN to XMAX incremented by DX.

.

ending geodetic latitude YMAX.

geoid undulations of associated longitude from XMIN to XMAX incremented by DX.

Reference gravity anomalies surface, Rapp's 180 x 180 model (Unit 11):

Input format similar to Unit 10.

Reference geoid undulation surface, Rapp's 36 x 36 model (Unit 12):

Input format similar to Unit 10.

Reference gravity anomalies surface, Rapp's 36 x 36 model (Unit 13):

Input format similar to Unit 10.

Reference geoid undulation surface, Rapp's 300 x 300 model (Unit 14):

Input format similar to Unit 10.

Reference gravity anomalies surface, Rapp's 300 x 300 model (Unit 15):

Input format similar to Unit 10.

Mask of inland sea surface (Unit 16): This is an M x N mask of the inland sea surface, where M and N are the numbers of longitude and latitude grid points. A unitary value (1) indicates that a prediction and transformation are to be performed at that grid point. A zero (0) indicates that no prediction or transformation is to take place at that grid point.

Output:

Gridded gravity anomalies (Unit 17): The output file contains sequences of grid longitude, grid latitude and gravity anomalies. The format of the output file is (3(2F7.2,F12.4)).

Gridded variance of gravity transformation (Unit 18): The output file contains sequences of grid longitude, grid latitude and variance in mgal. The format of the output file is (3(2F7.2,F12.4)).

Gridded geoid undulations (Unit 19): The output file contains sequences of grid longitude, grid latitude and geoid undulations. The format of the output file is (3(2F7.2,F12.4)).

Gridded variance of geoid prediction (Unit 20): The output file contains sequences of grid longitude, grid latitude and variance in cm. The format of the output file is (3(2F7.2,F12.4)).

Gridded difference between gravity anomalies at the end of the iterative process and the reference surface used (Unit 21): The output file contains sequences of grid longitude, grid latitude and gravity anomalies. The format of the output file is (3(2F7.2,F12.4)).

Covariance table (Unit 22): This is a set of residual local empirical covariance functions obtained at the end of the iterative process. Each record in the covariance table contains distance in degree, geoid-to-geoid value, geoid-to-gravity value, and gravity-to-gravity value. The format of the output file is (1X,D10.4,3D20.13).

JORDAN

This program determines a set of theoretical covariance functions according to Jordan's formation (Jordan, 1972).

User-provided Parameters:

SN	Variance of geoid undulations at prediction point.
SG	Variance of gravity anomalies at prediction point.
D	Correlation distance.
DR	Increment in distance in degrees.
RMIN	Starting value of the distance in degrees.
RMAX	Ending value of the distance in degrees.

Output:

Covariance table (Unit 8): Each record in the covariance table contains distance in degree, geoid-to-geoid value, geoid-to-gravity value, and gravity-to-gravity value. The format of the output file is (1X,D10.4,3D20.13).

III. REFERENCES

- Au, A. Y., R. D. Brown and J. E. Welker (1988) *Analysis of Altimetry Over Inland Seas*. NASA Technical Memorandum - 100729.
- Jordan, S. K. (1972) *Self-constant statistical models for gravity anomaly, vertical deflections, and undulation of the geoid*. *J. Geophys. Res.*, 77, 3660-3670.
- Rapp, R. H. (1986) *Gravity anomalies and sea surface heights derived from a combined GEO-3/SEASAT altimeter data set*. *J. Geophys. Res.*, 91, 4867-4876.

IV LISTINGS

A listing of PROGRAM PRDATA

```
//ZMAYABSR JOB (G0109,360,2),AYAU,TIME=(0,30),CLASS=O,MSGCLASS=X
/*JOBPARM LINES=60
// EXEC FORTVC
//SYSIN DD *
```

```
C
C FORMAT OF GEOS-3/SEASAT ALTIMETER DATA
C
C VARIABLE      TYPE      DESCRIPTION
C
C *            I4        SATELITE ID
C            I2        MEASUREMENT TYPE ( 42= OVER LAND , 43 = OVER WATER
C            I2        TIME SYSTEM ( NM )
C            I4        STATION NUMBER
C            I4        PREPROCESSING INDICATORS
C            I4        MODIFIED JULIAN DATE OF OBSERVATION
C *            R8        FRACTION OF DAY PAST MIDNIGHT (GMT)
C *            R8        ALTIMETER OBSERVATION (METERS)
C *            I4        SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
C *            I4        SATELLITE EAST LONGITUDE (1E-6 DEGREES)
C *            R4        MEASUREMENT STANDARD DEVIATION (METERS)
C            I4        NET INSTRUMENT CORRECTION (MM)
C            I4        METEOROLOGICAL DATA WORD (GEODYN VOL 3)
C            I4        NET MEDIA CORRECTIONS (MM)
C            R4        GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
C            I4        NET OCEAN DYNAMIC CORRECTIONS (MM)
C *            I4        INDICATED SURFACE ELEVATION (MM)
C *            I4        S/C REVOLUTION NUMBER
C            I4        MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
C            I4        DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
C            I2        H 1/3 (CM)
C            I2        AGC (DB)
C            I2        WIND SPEED (CM/SEC)
C            I2        SURFACE ELEVATION PREPROCESSING WORD
C            I2        DRY TROPOSPHERIC CORRECTION (MM)
C            I2        FNOC WET TROPOSPHERIC CORRECTION (MM)
C            I2        SMMR WET TROPOSPHERIC CORRECTION (MM)
C            I2        IONOSPHERIC CORRECTION (MM)
C            I2        BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
C            I2        SOLID EARTH TIDE (MM)
C            I2        SCHWIDERSKI OCEAN TIDE (MM)
C            I2        PARKE OCEAN TIDE (MM)
```

```
PARAMETER ( MAXREC = 10000 )
PARAMETER ( XMIN = 26.5 )
PARAMETER ( XMAX = 42.5 )
PARAMETER ( YMIN = 40.0 )
PARAMETER ( YMAX = 48.0 )
PARAMETER ( DX = 0.25 )
PARAMETER ( DY = 0.25 )
PARAMETER ( NLON = ( (XMAX-XMIN)/DX + 1 ) )
PARAMETER ( NLAT = ( (YMAX-YMIN)/DY + 1 ) )
PARAMETER ( IC = NLON )
PARAMETER ( IWK = 2*NLON*NLAT + 2*(NLON+NLAT) )
```

```
C
C
C INTEGER*2      I2, I3, I17, I18, I19, I20, I21, I22, I23, I24, I25, I26, I27, I28
C INTEGER*4      I1, I4, I5, I6, I7, I8, I9, I10, I11, I12, I13, I14, I15, I16
C REAL*8         R1, R2
C REAL*4         R3, R4
C REAL*4         LON(NLON), LAT(NLAT), GRID(NLON, NLAT)
C REAL*4         C(2, NLON, 2, NLAT), WK(IWK)
C REAL*4         GLAT, ELON, HSS, GUND
C REAL*4         DUR, SLAT1, SLAT2, SLON1, SLON2
```

```

REAL*8      STIM1, STIM2
INTEGER     ING, INP, OUP, OUR
INTEGER     IREC, LPP, NLINE, NPAGE, NREC
INTEGER     I1S, I6S, IDUM1
CHARACTER   TITLE*20 /' BLACK SEA DATA  '/
CHARACTER   NS*12 /' NORTH-SOUTH'/
CHARACTER   SN*12 /' SOUTH-NORTH'/
CHARACTER   EW*12 /' SINGLE-POINT'/
CHARACTER   DIR*12

C
DATA        ING / 5 //, INP / 8 //, OUP / 6 //, OUR / 9 /
DATA        K75 / 0 //, K78 / 0 /
DATA        LPP / 54 //, NLINE / 1 //, NPAGE / 1 //, NREC / 0 /

C
C
C.....GENERATE A GRID NET AND READ IN RAPP'S OSU300 180X180 GEOID
C
      LON(1) = XMIN
      DO 100 I = 2, NLON
        LON(I) = LON(I-1) + DX
100    CONTINUE
      LAT(1) = YMIN
      DO 110 J = 2, NLAT
        LAT(J) = LAT(J-1) + DY
110    CONTINUE
C
      DO 120 J = NLAT, 1, -1
        READ ( ING, * ) RL
        READ ( ING, 501 ) ( GRID(I,J), I=1, NLON)
120    CONTINUE
C
C.....DETERMINE A BICUBIC SPLINE TWO-DIMENSIONAL COEFFICIENT MATRIX
C
      CALL IBCCCU ( GRID, LON, NLON, LAT, NLAT, C, IC, WK, IER )
C
C
C.....START PROCESSING THE GEODYN DATA SET
C
      READ ( INP ) I1, I2, I3, I4, I5, I6, R1, R2, I7, I8, R3,
&                I9, I10, I11, R4, I12, I13, I14, I15, I16, I17, I18, I19,
&                I20, I21, I22, I23, I24, I25, I26, I27, I28
      NREV = I14
      I1S = I1
      I6S = I6
      SLAT1 = 1.0E-6 * FLOAT(I7)
      SLON1 = 1.0E-6 * FLOAT(I8)
      STIM1 = R1
      IF ( I1. EQ. 7502701 ) K75 = K75 + 1
      IF ( I1. EQ. 7806401 ) K78 = K78 + 1
      WRITE ( OUP, 601 ) TITLE, I6, NREV, I1, NPAGE
      WRITE ( OUP, 602 )
      REWIND INP
C
      DO 111 MJ = 1, MAXREC
C
      READ ( INP, END = 2000 ) I1, I2, I3, I4, I5, I6, R1, R2, I7, I8, R3,
&                I9, I10, I11, R4, I12, I13, I14, I15, I16, I17, I18, I19,
&                I20, I21, I22, I23, I24, I25, I26, I27, I28
      NREC = NREC + 1
      GLAT = 1.0E-6 * FLOAT(I7)
      ELON = 1.0E-6 * FLOAT(I8)
      HSS = 1.0E-3 * FLOAT(I13)
C
      CALL IBCEVL ( LON, NLON, LAT, NLAT, C, IC, ELON, GLAT, GUND, IER )
C
      WRITE ( OUR, 660 ) GLAT, ELON, GUND
C
      IF ( I14. EQ. NREV ) THEN
        IF ( NLINE. LE. LPP ) THEN
          WRITE( OUP, 603 ) NREC, R1, R2, GLAT, ELON, HSS, R3, GUND

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```

        NLINE = NLINE + 1
        IREC = IREC + 1
    ELSE
        NLINE = 1
        IREC = IREC + 1
        NPAGE = NPAGE + 1
        IF ( I6-I6S). EQ. 1 ) R1 = R1 + 1.0
        WRITE ( OUP, 601 ) TITLE, I6, NREV, I1, NPAGE
        WRITE ( OUP, 602 )
        WRITE ( OUP, 603 ) NREC,R1,R2,GLAT,ELON,HSS,R3,GUND
    END IF
    SLAT2 = GLAT
    SLON2 = ELON
    STIM2 = R1
ELSE
    IF ( SLAT2. EQ. 0.0. AND. SLON2. EQ. 0.0 ) THEN
        DIR = EW
        DUR = 0.0
    ELSE
        IF ( (SLAT2-SLAT1). LE. 0.0 ) THEN
            DIR = NS
        ELSE
            DIR = SN
        END IF
        DUR = 86400.0 * (STIM2 - STIM1 )
    END IF
    WRITE ( OUP, 610 ) DIR, DUR, IREC
    IF ( I1. EQ. 7502701 ) K75 = K75 + 1
    IF ( I1. EQ. 7806401 ) K78 = K78 + 1
    NREV = I14
    I1S = I1
    I6S = I6
    NLINE = 1
    IREC = 1
    NPAGE = NPAGE + 1
    WRITE ( OUP, 601 ) TITLE, I6, NREV, I1, NPAGE
    WRITE ( OUP, 602 )
    WRITE ( OUP, 603 ) NREC,R1,R2,GLAT,ELON,HSS,R3,GUND
    SLAT1 = GLAT
    SLON1 = ELON
    STIM1 = R1
    SLAT2 = 0.
    SLON2 = 0.
    STIM2 = 0.
END IF
C
111 CONTINUE
C
2000 CONTINUE
C
    IF ( SLAT2. EQ. 0.0. AND. SLON2. EQ. 0.0 ) THEN
        DIR = EW
        DUR = 0.0
    ELSE
        IF ( (SLAT2-SLAT1). LE. 0.0 ) THEN
            DIR = NS
        ELSE
            DIR = SN
        END IF
        DUR = 86400.0 * (STIM2 - STIM1 )
    END IF
    WRITE ( OUP, 610 ) DIR, DUR, IREC
C
    WRITE( OUP, 611 ) K75, K78
C
501 FORMAT((6(2X,F10.3)))
601 FORMAT('1',T2,A20,8X,'MOD. JULIAN DAY = ',I6,8X,'PASS = ',I6,
&
8X,'SATELLITE ID = ',I10,T120,'PAGE ',I4,/)
602 FORMAT(' ',RECORD # ',2X,' FRACTION OF DAY',3X,
&
ALTIMETER OBS. (M)',5X,' S/C GEOD LAT ',

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&          ' S/C EAST LONG ' ' ELEVATION (M) ' ,5X, ' RAPP-180 ' /
&          ' , ' , ' ,2X, ' , ' ,3X,
&          ' , ' , ' ,5X, ' , ' ,
&          ' , ' , ' ,5X, ' , ' ,
603 FORMAT(' ',I7,6X,F20.18,3X,F20.12,5X,2(4X,F9.6,2X),F9.3,
&          ' (',F4.2,')',5X,F10.3)
604 FORMAT(I5,I10,2F8.3,4F10.6)
610 FORMAT(1H,/,T5,'THE APPROX. DURATION OF THIS ',A12,' PASS IS',
&          F8.2,' SEC. WITH ',I6,' RECORDS.')
611 FORMAT(1H1,T20,'# OF PASSES FOR SATELLITE GEOS-3 IS:',I6,/,
&          T20,'# OF PASSES FOR SATELLITE SEASAT IS:',I6)
660 FORMAT(5X,2F9.3,45X,F9.3)
C
      STOP
      END
/**
// EXEC LINKGOV,REGION.GO=5000K
//SYSLIB DD DSN=SYS2.IMSL,DISP=SHR
/**
//GO.FT05F001 DD DSN=ZMAYA.ALTIM.DATA(BRH180),DISP=SHR
//GO.FT06F001 DD SYSOUT=*
//GO.FT08F001 DD DSN=ZMAYA.BLACK.DATA,DISP=SHR
/**
/** *****
/**
/**          BLACK SEA DATA
/**
/** *****
/**
//GO.FT09F001 DD DSN=ZMAYA.ALTIM.DATA(BLKRAPP),DISP=SHR
/**
// EXEC NOTIFYTS

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A listing of PROGRAM PLTGRP

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//ZMAYABEP JOB (G0109,360,75),AYAU,TIME=(12,00),CLASS=O,MSGCLASS=X
/*JOBPARM LINES=60
//TEMPLATE EXEC G38PLOT
//FORT.SYSIN DD *
C
C FORMAT OF SEASAT ALTIMETER DATA
C VARIABLE      TYPE      DESCRIPTION
C              I4        SATELLITE ID
C              I2        MEASUREMENT TYPE ( 42= OVER LAND , 43 = OVER WATER )
C              I2        TIME SYSTEM ( NM )
C              I4        STATION NUMBER
C              I4        PREPROCESSING INDICATORS
C      *         I4        MODIFIED JULIAN DATE OF OBSERVATION
C      *         R8        FRACTION OF DAY PAST MIDNIGHT (GMT)
C      *         R8        ALTIMETER OBSERVATION (METERS)
C      *         I4        SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
C      *         I4        SATELLITE EAST LONGITUDE (1E-6 DEGREES)
C              R4        MEASUREMENT STANDARD DEVIATION (METERS)
C              I4        NET INSTRUMENT CORRECTION (MM)
C              I4        METEOROLOGICAL DATA WORD (GEODYN VOL 3)
C              I4        NET MEDIA CORRECTIONS (MM)
C              R4        GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
C              I4        NET OCEAN DYNAMIC CORRECTIONS (MM)
C      *         I4        INDICATED SURFACE ELEVATION (MM)
C      *         I4        S/C REVOLUTION NUMBER
C              I4        MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
C              I4        DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
C              I2        H 1/3 (CM)
C              I2        AGC (DB)
C              I2        WIND SPEED (CM/SEC)
C              I2        SURFACE ELEVATION PREPROCESSING WORD
C              I2        DRY TROPOSPHERIC CORRECTION (MM)
C              I2        FNOC WET TROPOSPHERIC CORRECTION (MM)
C              I2        SMMR WET TROPOSPHERIC CORRECTION (MM)
C              I2        IONOSPHERIC CORRECTION (MM)
C              I2        BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
C              I2        SOLID EARTH TIDE (MM)
C              I2        SCHWIDERSKI OCEAN TIDE (MM)
C              I2        PARKE OCEAN TIDE (MM)
C
INTEGER*2  I2,I3,I17,I18,I19,I20,I21,I22,I23,I24,I25,I26,I27,I28
INTEGER*4  I1,I4,I5,I6,I7,I8,I9,I10,I11,I12,I13,I14,I15,I16
REAL*8     R1,R2
REAL*4     R3,R4
REAL*4     GLAT, ELON, HSS
REAL*4     X(5000),Y(5000)
INTEGER    INP, IREC, LPP, NLINE, NPAGE, IPLOT, NREC, NREV, OUP
INTEGER    IWRT, MAXPLT, LIST(6)
CHARACTER  TITLE*20 // BLACK SEA DATA //
C
DATA      INP / 5 //, OUP / 6 /
DATA      LIST / 8, 110, 75, 0, 7, 10 /
DATA      LPP / 54 //, NLINE / 1 //, NPAGE / 1 /
DATA      IREC / 0 //, NREC / 0 //, IPLOT / 0 /
DATA      IWRT / 0 //, MAXPLT / 99999 /
C
READ ( INP )  I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&            I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&            I20,I21,I22,I23,I24,I25,I26,I27,I28
NREV = I14
IF ( IWRT. GT. 0 ) THEN
  WRITE ( OUP, 601 )  TITLE, NREV, NPAGE
  WRITE ( OUP, 602 )
END IF
REWIND INP
CALL USTART
CALL UINQES(1.0,SUPRT)

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C      IF(SUPRT.NE.0.0) CALL UESCAP(1.0,LIST,6.0,IDUM,DUM)
C
1000 READ ( INP, END = 2000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
*      I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
*      I20,I21,I22,I23,I24,I25,I26,I27,I28
      NREC = NREC + 1
      GLAT = 1.0E-6 * FLOAT(I7)
      ELON = 1.0E-6 * FLOAT(I8)
      HSS = 1.0E-3 * FLOAT(I13)
C
      IF ( I14. EQ. NREV ) THEN
      IF ( NLINE. LE. LPP ) THEN
      IF (IWRT.GT.0) WRITE(OUT, 603) I6,R1,R2,GLAT,ELON,HSS,NREC
      NLINE = NLINE + 1
      ELSE
      NLINE = 1
      NPAGE = NPAGE + 1
      IF ( IWRT. GT. 0 ) THEN
      WRITE ( OUP, 601 ) TITLE, NREV, NPAGE
      WRITE ( OUP, 602 )
      WRITE ( OUP, 603 ) I6,R1,R2,GLAT,ELON,HSS,NREC
      END IF
      END IF
      IREC = IREC + 1
      RMJD = FLOAT(I6)
      RNREV = FLOAT(I14)
      X(IREC) = R1
      Y(IREC) = HSS
      ELSE
C
C.....PLOT THE PREVIOUS ELEVATION PROFILE
C
      IF ( IPLOT. GT. MAXPLT ) GO TO 3000
      IF ( IREC. GT. 3. AND. IPLOT. LE. MAXPLT ) THEN
C
      IPLOT = IPLOT + 1
      CALL PLOT(X,Y,IREC,RMJD,RNREV)
C
      END IF
C
      NREV = I14
      NLINE = 1
      NPAGE = NPAGE + 1
      IREC = 1
      X(IREC) = R1
      Y(IREC) = HSS
      IF ( IWRT. GT. 0 ) THEN
      WRITE ( OUP, 601 ) TITLE, NREV, NPAGE
      WRITE ( OUP, 602 )
      WRITE ( OUP, 603 ) I6,R1,R2,GLAT,ELON,HSS,NREC
      END IF
      END IF
C
      GO TO 1000
C
2000 CONTINUE
C
      IF ( IREC. GT. 3. AND. IPLOT. LE. MAXPLT ) THEN
      IPLOT = IPLOT + 1
      CALL PLOT(X,Y,IREC,RMJD,RNREV)
      END IF
C
3000 WRITE( OUP, * ) ' '
      WRITE( OUP, * ) ' ', NREC, ' RECORDS IN FILE.'
      WRITE( OUP, * ) ' '
      WRITE( OUP, * ) ' ', IPLOT, ' ELEVATION PROFILES PLOTTED.'
C
      CALL UEND
C
601 FORMAT('1',T10,A20,10X,'PASS # = ',I6,T90,'PAGE ',I4,/)

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602 FORMAT(' ', 'JULIAN DAY', 2X, '          FRACTION OF DAY', 3X,
&          '          ALTIMETER OBS. (M)', 5X, '          S/C GEOD LAT ',
&          '          S/C EAST LONG ', '          ELEVATION (M) ', 5X, '          RECORD # ' /
&          '+', '          ', 2X, '          ', 5X, '          ', 3X,
&          '          ', 5X, '          ', 5X, '          ')
603 FORMAT(' ', 17, 6X, F20.18, 3X, F20.12, 5X, 2(4X, F9.6, 2X), 5X, F7.3, 5X, I10)
C
  STOP
  END
C
  SUBROUTINE PLOT ( X, Y, IREC, RMJD, RNREV )
C
  REAL*4      X(IREC), Y(IREC), RMJD, RNREV
  INTEGER     IREC
  CHARACTER*1 DATE(10)
C
  CALL USET('PERCENTUNITS')
  CALL USET('EXTRALARGE')
  CALL UVWPRT(0.0, 99.0, 0.0, 99.0)
  CALL UOUTLN
C
C.....PRINT TITLE, JULIAN DATE AND PASS NUMBER.
C
  CALL USET('CJUST')
  CALL USET('TJUST')
  CALL UPSET('PRECISION', 5.0)
  CALL UPRINT(50., 96.,
& 'BLACK SEA ALTIMETER ELEVATION PROFILES')
  CALL UPRINT(50., 92., 'MODIFIED JULIAN DATE : $')
  CALL UMOVE(70., 92.)
  CALL UPRT1(RMJD, 'REAL')
  CALL UPRINT(50., 88., 'PASS : $')
  CALL UMOVE(60., 88.)
  CALL UPRT1(RNREV, 'REAL')
  CALL ZTIME(DATE, 8)
  CALL FMOVE(DATE(10), 1, '$')
  CALL UPRINT(88., 6., DATE)
  CALL UPRINT(88., 3., 'STX/ZMAYA$')
C
C.....DRAW AND LABEL AXES (DEFAULT TIC MARKS)
C
  CALL USET('NOORIGIN')
  CALL UVWPRT(5., 95., 7., 90.)
  CALL USET('DSYMBOL')
  CALL UPSET('SYMBOL', 5.0)
  CALL UPSET('SZSYMBOL', 1.0)
  CALL USET('LARGE')
  CALL UPSET('XLABEL', 'FRACTION OF DAY PAST MIDDNIGHTS$')
  CALL UPSET('YLABEL', 'SURFACE ELEVATION IN METERS$')
  CALL USET('XBOTH')
  CALL USET('YBOTH')
  CALL USET('OWNSCALE')
  CALL UPSET('TICX', TCX)
  CALL UPSET('TICY', TCY)
C
  XMIN = X(1)
  XMAX = X(IREC)
  YMIN = Y(1)
  YMAX = Y(1)
  DO 111 I = 1, IREC
    YMIN = AMIN1 ( Y(I), YMIN )
    YMAX = AMAX1 ( Y(I), YMAX )
111 CONTINUE
  SX = 0.05 * ( XMAX - XMIN )
  SY = 0.10 * ( YMAX - YMIN )
  XMIN = XMIN - SX
  XMAX = XMAX + SX
  YMIN = YMIN - SY
  YMAX = YMAX + SY
  CALL UWINDO(XMIN, XMAX, YMIN, YMAX)

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      CALL UAXIS(XMIN,XMAX,YMIN,YMAX)
C
C.....PLOT POLY-LINE
C
      XPT = FLOAT(IREC)
      CALL ULINE(X,Y,XPT)
C
C.....DISPLAY FOR SCREEN
C
C      CALL UPAUSE
C
C.....TERMINATED THIS PLOT
C
      CALL UERASE
      CALL URESET
C
      RETURN
      END
/**
//GO.FT05F001 DD DSN=ZMAYA.BLACK.DATA,DISP=SHR
/**
/** *****
/**
/**          BLACK SEA DATA
/**
/** *****
/**
//GO.FT06F001 DD SYSOUT=*
// EXEC NOTIFYTS

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A listing of PROGRAM GRNTRK

```
//ZMAYABAK JOB (G0109,360,7),AYAU,TIME=(1,00),CLASS=0,MSGCLASS=X
/*JOBPARM LINES=60
//TEMPLATE EXEC G38PLOT
//FORT.SYSIN DD *
C
C FORMAT OF GEOS-3/SEASAT ALTIMETER DATA
C VARIABLE      TYPE      DESCRIPTION
C              I4        SATELITE ID
C              I2        MEASUREMENT TYPE ( 42= OVER LAND , 43 = OVER WATER )
C              I2        TIME SYSTEM ( NM )
C              I4        STATION NUMBER
C              I4        PREPROCESSING INDICATORS
C      *         I4        MODIFIED JULIAN DATE OF OBSERVATION
C      *         R8        FRACTION OF DAY PAST MIDNIGHT (GMT)
C      *         R8        ALTIMETER OBSERVATION (METERS)
C      *         I4        SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
C      *         I4        SATELLITE EAST LONGITUDE (1E-6 DEGREES)
C              R4        MEASUREMENT STANDARD DEVIATION (METERS)
C              I4        NET INSTRUMENT CORRECTION (MM)
C              I4        METEOROLOGICAL DATA WORD (GEODYN VOL 3)
C              I4        NET MEDIA CORRECTIONS (MM)
C              R4        GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
C              I4        NET OCEAN DYNAMIC CORRECTIONS (MM)
C      *         I4        INDICATED SURFACE ELEVATION (MM)
C      *         I4        S/C REVOLUTION NUMBER
C              I4        MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
C              I4        DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
C              I2        H 1/3 (CM)
C              I2        AGC (DB)
C              I2        WIND SPEED (CM/SEC)
C              I2        SURFACE ELEVATION PREPROCESSING WORD
C              I2        DRY TROPOSPHERIC CORRECTION (MM)
C              I2        FNOC WET TROPOSPHERIC CORRECTION (MM)
C              I2        SMMR WET TROPOSPHERIC CORRECTION (MM)
C              I2        IONOSPHERIC CORRECTION (MM)
C              I2        BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
C              I2        SOLID EARTH TIDE (MM)
C              I2        SCHWIDERSKI OCEAN TIDE (MM)
C              I2        PARKE OCEAN TIDE (MM)
C
C      PARAMETER ( NMAX = 1000 )
C      PARAMETER ( MAXREC = 10000 )
C
C      INTEGER*2  I2,I3,I17,I18,I19,I20,I21,I22,I23,I24,I25,I26,I27,I28
C      INTEGER*4  I1,I4,I5,I6,I7,I8,I9,I10,I11,I12,I13,I14,I15,I16
C      INTEGER    IGRID, INP, IREC, ITRK, LPP, NLINE, NPAGE, NREC, OUP
C      INTEGER    K75, K78
C      REAL*8     R1,R2
C      REAL*4     R3,R4
C      REAL*4     GLAT, ELON, HSS
C      REAL*4     X(NMAX),Y(NMAX), XP(NMAX),YP(NMAX)
C
C      INTEGER    NPROJ, LINEH, LINEV
C      INTEGER    LIST(6)
C      REAL*4     PENS(7)
C      REAL*4     PLAT,PLONG,VLAT1,VLAT2,VLONG1,VLONG2
C      CHARACTER*1 DATE(10)
C
C      DATA PENS / 7*4.0 /
C      DATA LIST / 8, 110, 75, 0, 7, 10 /
C      DATA NPROJ / 16 /
C      DATA PLAT / 90. /, PLONG / 0. /
C      DATA VLONG1 / 26.5 /, VLONG2 / 42.5 /
C      DATA VLAT1 / 40. /, VLAT2 / 48. /
C      DATA LINEH / 0 /, LINEV / 0 /
C
C      DATA INP / 5 /, OUP / 6 /
```

```

DATA IREC / 0 //, NREC / 0 //, ITRK / 0 /
DATA IGRID / 1 /
C
C.....PROJECT REGIONAL MAP
C
CALL USTART
CALL UINQES(1.0,SUPRT)
IF (SUPRT.NE.0.0) CALL UESCAP(1.0,LIST,6.0,IDUM,DUM)
CALL USET('PERCENTUNITS')
CALL UVWPRT(0.0,99.0,0.0,99.0)
CALL UOUTLN
C
C.....PUT ON LABELS
C
CALL USET('CJUST')
CALL USET('TJUST')
CALL USET('YELLOW')
CALL USET('SOFTWARE')
CALL USET('EXTRALARGE')
CALL UPSET('VERTICAL SIZE',2.0)
CALL UPSET('HORIZONT SIZE',1.6)
CALL UFONT('TROM')
CALL UPRINT(50.,96.,
& 'GEOS-3/SEASAT GROUND TRACKS OVER BLACK SEAS')
IF ( IGRID. GT. 0 ) THEN
    LINEH = IFIX( VLAT2 - VLAT1 )
    LINEV = IFIX( VLONG2 - VLONG1 )
END IF
CALL WDMAP(NPROJ,PLAT,PLONG,VLAT1,VLAT2,VLONG1,VLONG2,
& LINEH,LINEV)
C
C.....LABEL AXIS AND WRITE LON AND LATS ON PLOT
C
IF ( IGRID. GT. 0 ) THEN
C
    DLONG = ABS(VLONG2 - VLONG1) / LINEV
    LINES = LINEV + 1
    DIX = 100.0 / LINEV
    YLONGI = -3.5
    DO 420 I = 1, LINES, 2
        V = VLONG1 + (DLONG * (I - 1))
        XLATIT = DIX * (I - 1)
        CALL UMOVE(XLATIT,YLONGI)
        CALL UPRNT1(V,'REAL')
420 CONTINUE
C
C.....WRITE LABEL
C
CALL USET('BJUS')
CALL UMOVE(50.,-7.5)
CALL UPRNT1('EAST LONGITUDES','HORIZ')
C
    DLAT = ABS(VLAT2 - VLAT1) / LINEH
    LINES = LINEH + 1
    DIY = 100.0 / LINEH
    XLT = -3.5
    DO 430 I = 1, LINES, 2
        V = VLAT1 + (DLAT * (I - 1))
        YLO = DIY * (I - 1)
        CALL UMOVE(XLT,YLO)
        CALL UPRNT1(V,'REAL')
430 CONTINUE
C
C.....WRITE LABEL
C
CALL USET('MJUS')
CALL UMOVE(-7.5,50.0)
CALL UPRNT1('GEODETIC LATITUDES','VERTI')
C
END IF

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C
C.....WRITE DATE AND ID ON PLOT
C
  CALL ZTIME( DATE, 8 )
  CALL FMOVE( DATE( 10 ), 1, '$' )
  CALL UPRINT( 79., -8., DATE )
  CALL UPRINT( 96., -8., 'STX/ZMAYAS' )
C
  READ ( INP ) I1, I2, I3, I4, I5, I6, R1, R2, I7, I8, R3,
  &           I9, I10, I11, R4, I12, I13, I14, I15, I16, I17, I18, I19,
  &           I20, I21, I22, I23, I24, I25, I26, I27, I28
  NREV = I14
  IF ( I1. EQ. 7502701 ) K75 = K75 + 1
  IF ( I1. EQ. 7806401 ) K78 = K78 + 1
  REWIND INP
C
  DO 111 IJK = 1, MAXREC
C
  READ ( INP, END = 2000 ) I1, I2, I3, I4, I5, I6, R1, R2, I7, I8, R3,
  &           I9, I10, I11, R4, I12, I13, I14, I15, I16, I17, I18, I19,
  &           I20, I21, I22, I23, I24, I25, I26, I27, I28
  NREC = NREC + 1
  GLAT = 1.0E-6 * FLOAT( I7 )
  ELON = 1.0E-6 * FLOAT( I8 )
  HSS = 1.0E-3 * FLOAT( I13 )
C
  IF ( I14. EQ. NREV ) THEN
    IREC = IREC + 1
    X( IREC ) = ELON
    Y( IREC ) = GLAT
  ELSE
C
C.....SET UP TO PLOT THE PREVIOUS GROUND TRACK
C
  IF ( IREC. GT. 1 ) THEN
C
  ITRK = ITRK + 1
  CALL PLGR TK ( X, Y, XP, YP, IREC )
C
  END IF
C
  NREV = I14
  IF ( I1. EQ. 7502701 ) K75 = K75 + 1
  IF ( I1. EQ. 7806401 ) K78 = K78 + 1
  IREC = 1
  X( IREC ) = ELON
  Y( IREC ) = GLAT
  END IF
C
  111 CONTINUE
C
  2000 CONTINUE
C
  IF ( IREC. GT. 1 ) THEN
    ITRK = ITRK + 1
    CALL PLGR TK ( X, Y, XP, YP, IREC )
  END IF
C
  WRITE( OUP, * ) ' '
  WRITE( OUP, * ) ' ', NREC, ' RECORDS IN FILE.'
  WRITE( OUP, * ) ' '
  WRITE( OUP, * ) ' ', ITRK, ' GROUND TRACKS PLOTTED, WHERE'
  WRITE( OUP, * ) ' '
  WRITE( OUP, * ) ' ', K75, ' TRACKS FROM GEOS-3 AND'
  WRITE( OUP, * ) ' '
  WRITE( OUP, * ) ' ', K78, ' TRACKS FROM SEASAT.'
C
  CALL UPAUSE
  CALL UEND
C

```

```

        STOP
        END
C
        SUBROUTINE PLGR TK ( X, Y, XP, YP, IREC )
C
        REAL*4 X(IREC), Y(IREC), XP(IREC), YP(IREC)
        INTEGER IREC
C
        CALL USET('PERCENTUNITS')
        CALL UVWPRT(0.0, 99.0, 0.0, 99.0)
        CALL USET('OWNSCALE')
C
C.....PLOT GROUND TRACK
C
        DO 111 I = 1, IREC
            CALL WDPOS(Y(I),X(I),XP(I),YP(I))
111 CONTINUE
C
        CALL USET('LNULL')
        XPT = FLOAT(IREC)
        CALL ULINE(XP,YP,XPT)
C
        RETURN
        END
/**
//GO.FT05F001 DD DSN=ZMAYA.BLACKA.DATA,DISP=SHR
/**
/** *****
/**
/**          BLACK SEA DATA
/**
/** *****
/**
//GO.FT06F001 DD SYSOUT=*
//GO.FT19F001 DD DSN=SYS2.WRLDATA2,DISP=SHR,LABEL=(, , IN)
// EXEC NOTIFYTS

```


A listing of PROGRAM KOVERO

```
//ZMAYABXO JOB (G0109,360,2),AYAU,TIME=(0,30),CLASS=O,MSGCLASS=X
// EXEC FORTVC
//SYSIN DD *
```

C
C FORMAT OF GEOS-3/SEASAT ALTIMETER DATA

VARIABLE	TYPE	DESCRIPTION
*	I4	SATELITE ID
	I2	MEASUREMENT TYPE (42= OVER LAND , 43 = OVER WATER)
	I2	TIME SYSTEM (NM)
	I4	STATION NUMBER
	I4	PREPROCESSING INDICATORS
	I4	MODIFIED JULIAN DATE OF OBSERVATION
	R8	FRACTION OF DAY PAST MIDNIGHT (GMT)
	R8	ALTIMETER OBSERVATION (METERS)
*	I4	SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
*	I4	SATELLITE EAST LONGITUDE (1E-6 DEGREES)
	R4	MEASUREMENT STANDARD DEVIATION (METERS)
	I4	NET INSTRUMENT CORRECTION (MM)
	I4	METEOROLOGICAL DATA WORD (GEODYN VOL 3)
	I4	NET MEDIA CORRECTIONS (MM)
	R4	GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
	I4	NET OCEAN DYNAMIC CORRECTIONS (MM)
	I4	INDICATED SURFACE ELEVATION (MM)
*	I4	S/C REVOLUTION NUMBER
	I4	MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
	I4	DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
	I2	H 1/3 (CM)
	I2	AGC (DB)
	I2	WIND SPEED (CM/SEC)
	I2	SURFACE ELEVATION PREPROCESSING WORD
	I2	DRY TROPOSPHERIC CORRECTION (MM)
	I2	FNOC WET TROPOSPHERIC CORRECTION (MM)
	I2	SMMR WET TROPOSPHERIC CORRECTION (MM)
	I2	IONOSPHERIC CORRECTION (MM)
	I2	BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
	I2	SOLID EARTH TIDE (MM)
	I2	SCHWIDERSKI OCEAN TIDE (MM)
	I2	PARKE OCEAN TIDE (MM)

PARAMETER (MPASS = 200)
PARAMETER (NMAX = 200)
PARAMETER (SIGE = 2.0)

C
INTEGER*2 I2, I3, I17, I18, I19, I20, I21, I22, I23, I24, I25, I26, I27, I28
INTEGER*4 I1, I4, I5, I6, I7, I8, I9, I10, I11, I12, I13, I14, I15, I16
REAL*8 R1, R2
REAL*4 R3, R4
INTEGER*4 IDSAT
REAL*4 GLAT, ELON
REAL*4 X(NMAX), Y(NMAX), Z(NMAX), YR(NMAX)
REAL*4 GX(NMAX), GY(NMAX), DDZ(NMAX), D(NMAX)
REAL*8 F(NMAX, 3), FT(3, NMAX)
REAL*8 G(NMAX)
REAL*8 A(MPASS), B(MPASS), C(MPASS)
REAL*4 SLON1(MPASS), SLAT1(MPASS), SLON2(MPASS), SLAT2(MPASS)
INTEGER*4 IDS(MPASS), NREV(MPASS), NBAD(MPASS)
INTEGER*4 ICX(MPASS, MPASS), ISUM(MPASS), LN(MPASS), LY(MPASS)
INTEGER IDP, INP, IREC, NPASS, NREC, OUP

C
DATA INP / 3 /, OUP / 6 /
DATA IREC / 0 /, NREC / 0 /, NPASS / 0 /

C
READ (INP) I1, I2, I3, I4, I5, I6, R1, R2, I7, I8, R3,
& I9, I10, I11, R4, I12, I13, I14, I15, I16, I17, I18, I19,
& I20, I21, I22, I23, I24, I25, I26, I27, I28

```

IDP = I14
REWIND INP
C
WRITE ( OUP, * ) ' ' ' ' CURVE FITTING FOR EACH SATELLITE PASS'
WRITE ( OUP, * ) ' ' ' '
C
1000 READ ( INP, END = 2000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
& I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
& I20,I21,I22,I23,I24,I25,I26,I27,I28
C*****
IF ( I14. EQ. 12793 ) GO TO 999
C*****
NREC = NREC + 1
GLAT = 1.0E-6 * FLOAT(I7)
ELON = 1.0E-6 * FLOAT(I8)
HSS = 1.0E-3 * FLOAT(I13)
IDSAT = I1
C
IF ( I14. EQ. IDP ) THEN
IREC = IREC + 1
IDP = I14
X(IREC) = ELON
Y(IREC) = GLAT
Z(IREC) = HSS
ELSE
C
C.....DETERMINE THE SECOND-ORDER POLYNOMIAL FOR A PASS
C
IF ( IREC. GE. 5 ) THEN
C
NPASS = NPASS + 1
NREV(NPASS) = IDP
IDS(NPASS) = IDSAT
SLON1(NPASS) = X(1)
SLAT1(NPASS) = Y(1)
SLON2(NPASS) = X(IREC)
SLAT2(NPASS) = Y(IREC)
CALL CURVE ( NPASS, X, Y, Z, YR, IREC, NREV(NPASS),
& IDS(NPASS), A(NPASS), B(NPASS), C(NPASS),
& NBAD(NPASS), F, FT, G, GX, GY, DDZ, D, SIGE )
C
END IF
C
IDP = I14
IREC = 1
X(IREC) = ELON
Y(IREC) = GLAT
Z(IREC) = HSS
END IF
C
999 CONTINUE
GO TO 1000
C
2000 CONTINUE
C
IF ( IREC. GE. 5 ) THEN
C
NPASS = NPASS + 1
NREV(NPASS) = IDP
IDS(NPASS) = IDSAT
SLON1(NPASS) = X(1)
SLAT1(NPASS) = Y(1)
SLON2(NPASS) = X(IREC)
SLAT2(NPASS) = Y(IREC)
CALL CURVE ( NPASS, X, Y, Z, YR, IREC, NREV(NPASS),
& IDS(NPASS), A(NPASS), B(NPASS), C(NPASS),
& NBAD(NPASS), F, FT, G, GX, GY, DDZ, D, SIGE )
C
END IF
C

```

```

3000 WRITE( OUP, * ) ' '
      WRITE( OUP, * ) ' ', NREC, ' RECORDS IN FILE.'
      WRITE( OUP, * ) ' '
      WRITE( OUP, * ) ' ', NPASS, ' PASSES REPRESENTED BY AX**2+BX+C'
C
      CALL XOVER ( NPASS, NREV, IDS, A, B, C, SLON1, SLAT1,
&                SLON2, SLAT2, ICX, ISUM, LN, LY, NBAD )
C
      STOP
      END
C
      SUBROUTINE CURVE ( NPASS, X, Y, Z, YR, IREC, IDP, IDSAT, A, B, C,
&                NB, F, FT, G, GX, GY, DDZ, D, SIGE )
C
      REAL*4      X(IREC), Y(IREC), Z(IREC), YR(IREC)
      REAL*4      GX(IREC), GY(IREC), DDZ(IREC), D(IREC)
      REAL*8      F(IREC,3), FT(3,IREC)
      REAL*8      E(3,3), EI(3,3), AE(6)
      REAL*8      G(IREC), H(3)
      REAL*8      A, B, C, DET, YD
      INTEGER*4   IDP, IDSAT, IREC, NB, NPASS
      INTEGER*4   IDIAG(3) / 1, 3, 6 /
      INTEGER*4   OUP / 6 /
C
C.....EVICT THE BAD DATA POINTS BY COMPARING THE ABSOLUTE DIFFERENCE
C      BETWEEN ADJACENT DATA POINTS
C
      NB = 0
      IREC1 = IREC - 1
C
      DO 111 I = 1, IREC
          GX(I) = -1.0
111 CONTINUE
C
      DO 112 I = 1, IREC1
          DDZ(I) = ABS( Z(I+1) - Z(I) )
112 CONTINUE
C
      DO 113 J = 1, IREC1
          IF(DDZ(J).LT.SIGE) THEN
              K = J
              GO TO 200
          END IF
113 CONTINUE
C
      200 CONTINUE
      DO 222 J = 1, IREC
          IF(DDZ(IREC-J).LT.SIGE) THEN
              IRECG = IREC-J
              GO TO 300
          END IF
222 CONTINUE
C
      300 KB = 0
      DO 333 I = 1, IRECG-1
          IF(DDZ(I).GT.SIGE) KB = KB + 1
333 CONTINUE
C
      LG = 1
      GX(LG) = X(K)
      GY(LG) = Y(K)
C
      400 LG = LG + 1
          K = K + 1
          IF(DDZ(K-1).GT.SIGE) THEN
              K = K + 1
              DO 444 I = 1, KB-1
                  IF(DDZ(K-1).GT.SIGE) K = K + 1
444 CONTINUE
          END IF

```

```

GX(LG) = X(K)
GY(LG) = Y(K)
IF(K.LE.IRECG) GO TO 400
C
DO 555 I = 1, LG
  F(I,1) = GX(I)*GX(I)
  F(I,2) = GX(I)
  F(I,3) = 1.0D0
  G(I) = GY(I)
555 CONTINUE
C
DO 666 I = 1, LG
  DO 667 J = 1, 3
    FT(J,I) = F(I,J)
667 CONTINUE
666 CONTINUE
C
DO 777 I = 1, 3
  DO 778 J = 1, 3
    E(I,J) = 0.D0
    DO 779 K = 1, LG
      E(I,J) = E(I,J) + FT(I,K)*F(K,J)
779 CONTINUE
778 CONTINUE
777 CONTINUE
C
DO 888 I = 1, 3
  H(I) = 0.D0
  DO 889 K = 1, LG
    H(I) = H(I) + FT(I,K)*G(K)
889 CONTINUE
888 CONTINUE
C
AE(1) = E(1,1)
AE(2) = E(1,2)
AE(3) = E(2,2)
AE(4) = E(1,3)
AE(5) = E(2,3)
AE(6) = E(3,3)
C
CALL DSOLVE ( AE, H, IDIAG, 3, .TRUE., .TRUE. )
C
A = H(1)
B = H(2)
C = H(3)
C
DET = E(1,1) * ( E(2,2)*E(3,3) - E(2,3)*E(2,3) ) +
&      E(1,2) * ( E(1,3)*E(2,3) - E(1,2)*E(3,3) ) +
&      E(1,3) * ( E(1,2)*E(2,3) - E(1,3)*E(2,2) )
C
EI(1,1) = ( E(2,2)*E(3,3) - E(2,3)*E(2,3) ) / DET
EI(2,2) = ( E(1,1)*E(3,3) - E(1,3)*E(1,3) ) / DET
EI(3,3) = ( E(1,1)*E(2,2) - E(1,2)*E(1,2) ) / DET
EI(2,3) = ( E(1,2)*E(1,3) - E(1,1)*E(2,3) ) / DET
EI(1,3) = ( E(1,2)*E(2,3) - E(1,3)*E(2,2) ) / DET
EI(1,2) = ( E(1,3)*E(2,3) - E(1,2)*E(3,3) ) / DET
C
A = ( EI(1,1)*H(1) + EI(1,2)*H(2) + EI(1,3)*H(3) )
B = ( EI(1,2)*H(1) + EI(2,2)*H(2) + EI(2,3)*H(3) )
C = ( EI(1,3)*H(1) + EI(2,3)*H(2) + EI(3,3)*H(3) )
C
RMS = 0.
DO 999 I = 1, LG
  YD = A*GX(I)*GX(I) + B*GX(I) + C
  YR(I) = SNGL(YD)
  D(I) = YR(I) - GY(I)
  RMS = RMS + D(I)*D(I)
999 CONTINUE
RMS = SQRT ( RMS/LOAT(LG) )
C

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```

C      IF ( RMS. GT. 1.00 ) NB = 1
C      WRITE ( OUP, 601 ) NPASS, IDP, IDSAT, A, B, C,
      &      GX(1), GY(1), GX(LG), GY(LG), RMS, LG, NB
      IF ( RMS. GT. 0.005 ) THEN
        WRITE ( 6, * )
        WRITE ( 6, 602 ) (M, GX(M), GY(M), YR(M), D(M), M=1, LG)
        WRITE ( 6, * )
      END IF
C
601 FORMAT(1H0, //, 1X, I3, I7, I9, 3E14.5, 5F10.4, I6, I3)
602 FORMAT((1H ,T5, I4, 3X, 3F10.4, 2X, F10.4))
C
      RETURN
      END
C
      SUBROUTINE XOVER ( NPASS, NREV, IDSAT, A, B, C, SLON1, SLAT1,
      &      SLON2, SLAT2, ICX, ISUM, LN, LY, NBAD )
C
      INTEGER      NREV(NPASS), IDSAT(NPASS), NBAD(NPASS)
      INTEGER      ICX(NPASS, NPASS), ISUM(NPASS), LN(NPASS), LY(NPASS)
      INTEGER      INDEX(2)
      REAL*4      SLAT1(NPASS), SLAT2(NPASS), SLON1(NPASS), SLON2(NPASS)
      REAL*8      A(NPASS), B(NPASS), C(NPASS)
      REAL*8      T(2)
      REAL*8      DA, DB, DC, RT, SRT, P, Q
      INTEGER      ITOTAL, IXM, MAXIX, MX, MXS, MX75, MX78, NPASS, OUP
      DATA      INP / 5 /, OUP / 6 /
      DATA      MAXIX / 0 /, MX / 0 /, MX75 / 0 /, MX78 / 0 /
      DATA      ITOTAL / 0 /
C
      DO 123 I = 1, NPASS
        ISUM(I) = 0
        DO 234 J = 1, NPASS
          ICX(I, J) = 0
234      CONTINUE
123      CONTINUE
C
      WRITE ( OUP, 600 )
C
      DO 222 I = 1, NPASS-1
C
        IF ( NBAD(I). EQ. 0 ) THEN
C
          WRITE( OUP, 601 ) NREV(I), IDSAT(I), SLON1(I), SLAT1(I),
          &      SLON2(I), SLAT2(I)
C
          DO 333 J = I+1, NPASS
C
            IF ( NBAD(J). EQ. 0 ) THEN
C
              INDEX(1) = 0
              INDEX(2) = 0
              DB = B(J) - B(I)
              DA = A(I) - A(J)
              DC = C(I) - C(J)
              RT = DB*DB - 4.0*DA*DC
C
              IF ( RT. GE. 0.0 ) THEN
                IF ( RT. EQ. 0.0 ) THEN
                  SRT = 0.0
                ELSE
                  SRT = DSQRT(RT)
                END IF
                T(1) = (DB+SRT)/(2.0*DA)
                T(2) = (DB-SRT)/(2.0*DA)
                WRITE(6,*) T, RT, SRT
C
                DO 135 L = 1, 2
                  IF ( SLON2(I). GT. SLON1(I) ) THEN

```

```

      IF( T(L). GE. SLON1(I). AND. T(L). LE. SLON2(I) )
&      INDEX(L) = INDEX(L) + 1
      ELSE
&      IF( T(L). LE. SLON1(I). AND. T(L). GE. SLON2(I) )
&      INDEX(L) = INDEX(L) + 1
      END IF
      IF ( SLON2(J). GT. SLON1(J) ) THEN
&      IF( T(L). GE. SLON1(J). AND. T(L). LE. SLON2(J) )
&      INDEX(L) = INDEX(L) + 1
      ELSE
&      IF( T(L). LE. SLON1(J). AND. T(L). GE. SLON2(J) )
&      INDEX(L) = INDEX(L) + 1
      END IF
135      CONTINUE
C
      DO 246 L = 1, 2
      IF ( INDEX(L). EQ. 2 ) THEN
      MX = MX + 1
      P = T(L)
      Q = A(I)*P*P + B(I)*P + C(I)
&      WRITE ( OUP, 602 ) NREV(J), IDSAT(J), P, Q,
&      SLON1(J), SLAT1(J),
&      SLON2(J), SLAT2(J)
      ICX(I,J) = ICX(I,J) + 1
      ICX(J,I) = ICX(I,J)
      IF ( IDSAT(I). EQ. IDSAT(J) ) THEN
      IF ( IDSAT(I). EQ. 7502701 ) MX75 = MX75 + 1
      IF ( IDSAT(I). EQ. 7806401 ) MX78 = MX78 + 1
      END IF
      END IF
246      CONTINUE
C
      END IF
C
      END IF
C
333      CONTINUE
C
      END IF
C
222      CONTINUE
C
      WRITE ( OUP, * ) ' '
      WRITE ( OUP, * ) ' '
      WRITE ( OUP, * ) ' TOTAL # OF POSSIBLE CROSSOVERS = ', MX
      WRITE ( OUP, * ) ' '
      WRITE ( OUP, * ) ' TOTAL # OF GEO3-GEO3 CROSSOVERS = ', MX75
      WRITE ( OUP, * ) ' '
      WRITE ( OUP, * ) ' TOTAL # OF SEASAT-SEASAT CROSSOVERS = ', MX78
      MXS = MX - MX75 - MX78
      WRITE ( OUP, * ) ' '
      WRITE ( OUP, * ) ' TOTAL # OF GEOS3-SEASAT CROSSOVERS = ', MXS
C
      DO 345 I = 1, NPASS
      DO 456 J = 1, NPASS
      ISUM(I) = ISUM(I) + ICX(I,J)
456      CONTINUE
      ITOTAL = ITOTAL + ISUM(I)
345      CONTINUE
      ITOTAL = ITOTAL/2
C
      DO 567 I = 1, NPASS
      MAXIX = MAX0 ( MAXIX, ISUM(I) )
567      CONTINUE
C
      DO 678 I = 1, NPASS
      IF ( ISUM(I). EQ. MAXIX ) IXM = I
678      CONTINUE
C
      WRITE ( OUP, 603 )

```

```

WRITE ( OUP, 604 ) ( I, NREV(I), I = 1, NPASS )
WRITE ( OUP, 605 ) NPASS
WRITE ( OUP, 606 ) ( NREV(I), (ICX(I,J),J=1,94), ISUM(I),
& I=1, NPASS )
C WRITE ( OUP, 607 ) NREV(IXM), MAXIX, ITOTAL

MM = 0
NN = 0
DO 789 I = 1, NPASS
  IF ( ICX(IXM,I). EQ. 1 ) THEN
    MM = MM + 1
    LY(MM) = I
  ELSE
    NN = NN + 1
    LN(NN) = I
  END IF
789 CONTINUE

C WRITE ( OUP, 608 ) NREV(IXM), MM, NN, MM+NN
C WRITE ( OUP, 609 ) ( NREV(LY(I)), I = 1, MM )

DO 987 J = 1, NN
  WRITE ( OUP, 610 ) NREV(LN(J))
  DO 876 I = 1, NPASS
    IF ( ICX(I,LN(J)). EQ. 1 ) THEN
      WRITE ( OUP, 611 ) NREV(I)
      GO TO 888
    END IF
876 CONTINUE
888 CONTINUE
987 CONTINUE

C WRITE ( 6, * ) ' '
WRITE ( 6, 612 )
DO 999 I = 1, NPASS
  DO 998 J = 1, NPASS
    IF ( ICX(I,J). GT. 1 ) WRITE ( 6, * ) NREV(I), NREV(J)
998 CONTINUE
999 CONTINUE

C 501 FORMAT(I5,I10,2F8.3,4F10.6)
600 FORMAT(1H1,T20,'BLACK SEA CROSSOVER LISTING:',//)
601 FORMAT(1H0,/,T5,'PASS = ',I6,5X,'SAT ID = ',I10,5X,4F10.6//)
602 FORMAT(1H ,T10,'XPASS = ',I6,5X,'SAT ID = ',I10,5X,2F10.3,
& 5X,4F10.6)
603 FORMAT(1H1,T20,'ROW-COLUMN ELEMENTS OF PASS CORRELATION MATRIX:',
& //)
604 FORMAT((1H ,10(3X,I4,I6)))
605 FORMAT(1H1,T20,'PARTIAL (94 COLUMNS) PASS CORRELATION MATRIX ',
& 'FOR',I5,' PASSES:',//)
606 FORMAT((1H ,10X,I8,5X,94I1,5X,I3))
607 FORMAT(1H0,/,T10,'PASS # ',I6,' HAS THE MAXIMUM OF ',I5,
& ' CROSSOVERS.',/,T10,'THE TOTAL # OF CROSSOVERS IS:',I5)
608 FORMAT(1H1,T5,'REFERENCE PASS = ',I6,T10,3I6,/,
& T10,'THE DIRECT CROSS-PASSES ARE:',//)
609 FORMAT((1H0,20I6))
610 FORMAT(1H0,/,T5,'PASS: ',I6,' IS INDIRECTLY RELATED TO THE')
611 FORMAT(1H ,T10,'REFERENCE PASS VIA PASS ',I6)
612 FORMAT(1H1,T10,'POSSIBLE COMBINATIONS OF PASSES THAT YIELD ',
& 'BAD CROSSOVERS:',//)

C RETURN
END

C SUBROUTINE DSOLVE (A,B, IDIAG,NEQ, FACT,BACK)
C Compute the U**T * D * U factorization of the symmetric matrix
C stored in A, if FACT = TRUE; and solve A * X = B if BACK = TRUE.
C
C

```

```

C A      Contains the compacted-column form of the upper triangular
C C      part of the coefficient matrix. After factorization, it
C C      contains D and U.
C C      B      Right-hand-side vector. After backsubstitution, it
C C      contains the solution.
C C      IDIAG   Addresses of the diagonal terms in A.
C C      NEQ     Number of equations
C C      FACT    If FACT = TRUE, then factor A; otherwise do not factor A.
C C      BACK    If BACK = TRUE, reduce B and backsubstitute; otherwise
C C      do not solve the equations.
C C
C C      IMPLICIT REAL*8 (A-H,O-Z)
C C      LOGICAL   FACT, BACK
C C      DIMENSION A(1), B(1), IDIAG(1)
C C
C C      Factor A, reduce B
C C      JR = 0.
C C      DO 400 J = 1, NEQ
C C          JD = IDIAG(J)
C C          JH = JD - JR
C C          IS = J - JH + 2
C C
C C          IF (JH .LT. 2) GOTO 390
C C
C C          IF (FACT) THEN
C C              IF (JH .GT. 2) THEN
C C              Reduce column J rows IS to J-1: do not divide by row diagonal
C C              K = JR + 2
C C              ID = IDIAG(IS - 1)
C C
C C              DO 100 I = IS, J-1
C C                  IR = ID
C C                  ID = IDIAG(I)
C C                  IH = MIN (ID-IR-1, I-IS+1)
C C                  IF (IH.GT.0) A(K) = A(K) - DOT(A(K-IH), A(ID-IH), IH)
C C                  K = K + 1
C C              100 CONTINUE
C C              ENDIF
C C
C C              Divide by row diagonal, and reduce diagonal term in column J
C C
C C              IR = JR + 1
C C              K = J - JD
C C              DO 200 I = IR, JD-1
C C                  ID = IDIAG(K+I)
C C                  IF (A(ID).EQ.0.0) GOTO 200
C C                  D = -A(I)
C C                  A(I) = A(I)/A(ID)
C C                  A(JD) = A(JD) + D*A(I)
C C              200 CONTINUE
C C
C C              ENDIF
C C
C C              Reduce RHS
C C              IF (BACK) B(J) = B(J) - DOT(A(JR+1), B(IS-1), JH-1)
C C
C C          390 JR = JD
C C          400 CONTINUE
C C
C C          IF (.NOT.BACK) RETURN
C C
C C      Divide by diagonal pivots

```


A listing of PROGRAM XOVER

```
//ZMAYABXW JOB (G0109,360,2),AYAU,TIME=(1,30),CLASS=O,MSGCLASS=X
/*JOBPARM LINES=60
// EXEC FORTVC
//SYSIN DD *
```

C FORMAT OF GEOS-3/SEASAT ALTIMETER DATA

VARIABLE	TYPE	DESCRIPTION
*	I4	SATELITE ID
	I2	MEASUREMENT TYPE (42= OVER LAND , 43 = OVER WATER)
	I2	TIME SYSTEM (NM)
	I4	STATION NUMBER
	I4	PREPROCESSING INDICATORS
	I4	MODIFIED JULIAN DATE OF OBSERVATION
	R8	FRACTION OF DAY PAST MIDNIGHT (GMT)
	R8	ALTIMETER OBSERVATION (METERS)
*	I4	SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
*	I4	SATELLITE EAST LONGITUDE (1E-6 DEGREES)
	R4	MEASUREMENT STANDARD DEVIATION (METERS)
	I4	NET INSTRUMENT CORRECTION (MM)
	I4	METEOROLOGICAL DATA WORD (GEODYN VOL 3)
	I4	NET MEDIA CORRECTIONS (MM)
	R4	GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
	I4	NET OCEAN DYNAMIC CORRECTIONS (MM)
*	I4	INDICATED SURFACE ELEVATION (MM)
*	I4	S/C REVOLUTION NUMBER
	I4	MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
	I4	DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
	I2	H 1/3 (CM)
	I2	AGC (DB)
	I2	WIND SPEED (CM/SEC)
	I2	SURFACE ELEVATION PREPROCESSING WORD
	I2	DRY TROPOSPHERIC CORRECTION (MM)
	I2	FNOC WET TROPOSPHERIC CORRECTION (MM)
	I2	SMMR WET TROPOSPHERIC CORRECTION (MM)
	I2	IONOSPHERIC CORRECTION (MM)
	I2	BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
	I2	SOLID EARTH TIDE (MM)
	I2	SCHWIDERSKI OCEAN TIDE (MM)
	I2	PARKE OCEAN TIDE (MM)

```
PARAMETER ( SIGMAG = 0.25 )
PARAMETER ( SIGMAS = 0.10 )
PARAMETER ( XDMAX = 100. )
PARAMETER ( ETOP = 100. )
PARAMETER ( EBOT = 0. )
PARAMETER ( SIGE = 2. )
PARAMETER ( MAXOVR = 2100 )
PARAMETER ( MPASS = 142 )
PARAMETER ( NMAX = 140 )
PARAMETER ( MSYM = (MPASS*(MPASS+1))/2 )
```

```
C
INTEGER*2 I2,I3,I17,I18,I19,I20,I21,I22,I23,I24,I25,I26,I27,I28
INTEGER*4 I1,I4,I5,I6,I7,I8,I9,I10,I11,I12,I13,I14,I15,I16
REAL*8 R1,R2
REAL*4 R3,R4
INTEGER*4 IDSAT
REAL*4 GLAT, ELON, HSS
REAL*4 XI(NMAX),YI(NMAX),ZI(NMAX), ZG(NMAX),YR(NMAX)
REAL*4 SX(NMAX),SY(NMAX),SZ(NMAX), SZG(NMAX),DDZ(NMAX),D(NMAX)
REAL*4 AX(MAXOVR,MPASS), BX(MAXOVR), XVR(MPASS,MPASS)
REAL*4 W(MAXOVR), AXT(MPASS,MAXOVR), SCR(MPASS,MPASS)
REAL*4 AXTBX(MPASS), AXTAX(MSYM)
REAL*4 X(MPASS,NMAX), H(MPASS,NMAX), HG(MPASS,NMAX)
REAL*4 SLON1(MPASS), SLAT1(MPASS), SLON2(MPASS), SLAT2(MPASS)
```

```

REAL*4      U(MPASS), S(MPASS), CIMSL(NMAX-1,3)
REAL*4      EX(MPASS,MPASS), GY(MPASS,MPASS)
REAL*8      DAXTBX(MPASS), DAXTAX(MSYM), ERCOV(MSYM)
REAL*8      F(NMAX,3), FT(3,NMAX)
REAL*8      G(NMAX)
REAL*8      A(MPASS), B(MPASS), C(MPASS)
INTEGER*4   IDS(MPASS), IDIAG(MPASS), NREV(MPASS), NIREC(MPASS)
INTEGER*4   ICB(MPASS), ISUM(MPASS), LN(MPASS), LY(MPASS)
INTEGER*4   ICX(MPASS,MPASS)
INTEGER     IDP, IREC, IRECA, IXM, NPASS, NREC
INTEGER     ING, INP, OUP, OUG, OUC

C
DATA      INP / 3 /, ING / 2 /, OUG / 8 /, OUP / 6 /, OUC / 9 /
DATA      IREC / 0 /, NREC / 0 /, NPASS / 1 /

C
G2 = SIGMAG*SIGMAG
S2 = SIGMAS*SIGMAS
SMGG = 1.0/(2.*G2)
SMSS = 1.0/(2.*S2)
SMSS = 1.0/(S2+G2)

C
READ ( INP )  I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&             I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&             I20,I21,I22,I23,I24,I25,I26,I27,I28
IDP = I14
REWIND INP

C
1000 READ ( INP, END = 2000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&             I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&             I20,I21,I22,I23,I24,I25,I26,I27,I28

C
READ ( ING, 501, END = 2000 ) IDUM1, GL, EL, DUM2, DUM3, DUM4,
&                             DUM5, DUM6, GUND
C*****
IF ( I14. EQ. 12793 ) GO TO 999
C*****
NREC = NREC + 1
GLAT = 1.0E-6 * FLOAT(I7)
ELON = 1.0E-6 * FLOAT(I8)
HSS = 1.0E-3 * FLOAT(I13)
IDSAT = I1

C
IF ( I14. EQ. IDP ) THEN
IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN

C
IREC = IREC + 1
IDP = I14
X(NPASS,IREC) = ELON
H(NPASS,IREC) = HSS
XI(IREC) = ELON
YI(IREC) = GLAT
ZI(IREC) = HSS
ZG(IREC) = GUND
END IF

C
ELSE

C
C.....DETERMINE THE SECOND-ORDER POLYNOMIAL FOR A PASS
C
IF ( IREC. GE. 5 ) THEN

C
NREV(NPASS) = IDP
IDS(NPASS) = IDSAT
CALL CURVE ( NPASS, XI, YI, ZI, ZG, YR, IREC, IDP,
&           IDSAT, A(NPASS), B(NPASS), C(NPASS),
&           F, FT, G, SX, SY, SZ, SZG, DDZ, D, SIGE )
NIREC(NPASS) = IREC
SLON1(NPASS) = XI(1)
SLAT1(NPASS) = YI(1)
SLON2(NPASS) = XI(IREC)

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```

        SLAT2(NPASS) = YI(IREC)
        DO 100 M = 1, IREC
            X(NPASS,M) = XI(M)
            H(NPASS,M) = ZI(M)
            HG(NPASS,M) = ZG(M)
100     CONTINUE
C
        ELSE
C
        NPASS = NPASS - 1
C
        END IF
C
        IDP = I14
        IREC = 1
        NPASS = NPASS + 1
        IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
            X(NPASS,IREC) = ELON
            H(NPASS,IREC) = HSS
            XI(IREC) = ELON
            YI(IREC) = GLAT
            ZI(IREC) = HSS
            ZG(IREC) = GUND
        ELSE
            IREC = IREC - 1
        END IF
        END IF
C
        999 CONTINUE
        GO TO 1000
C
        2000 CONTINUE
C
        IF ( IREC. GE. 5 ) THEN
C
            NREV(NPASS) = IDP
            IDS(NPASS) = IDSAT
            CALL CURVE ( NPASS, XI, YI, ZI, ZG, YR, IREC, IDP,
                & IDSAT, A(NPASS), B(NPASS), C(NPASS),
                & F, FT, G, SX, SY, SZ, SZG, DDZ, D, SIGE )
            NIREC(NPASS) = IREC
            SLON1(NPASS) = XI(1)
            SLAT1(NPASS) = YI(1)
            SLON2(NPASS) = XI(IREC)
            SLAT2(NPASS) = YI(IREC)
            DO 101 M = 1, IREC
                X(NPASS,M) = XI(M)
                H(NPASS,M) = ZI(M)
                HG(NPASS,M) = ZG(M)
101     CONTINUE
C
            ELSE
C
            NPASS = NPASS - 1
C
            END IF
C
            3000 WRITE( OUP, * ) ' '
                WRITE( OUP, * ) ' ', NREC, ' RECORDS IN FILE.'
                WRITE( OUP, * ) ' '
                WRITE( OUP, * ) ' ', NPASS, ' PASSES REPRESENTED BY AX**2+BX+C'
C
            CALL XOVER ( NPASS, NREV, IDS, A, B, C, SLON1, SLAT1,
                & SLON2, SLAT2, ICX, EX, GY, ISUM, LN, LY, IXM )
C
            CALL CLR ( XVR, MPASS*MPASS)
            CALL CLR ( AX, MAXOVR*MPASS)
            CALL CLR ( BX, MAXOVR)
            CALL CLR ( AXTAX, MSYM)
            CALL CLR ( AXTBX, MPASS)

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CALL DCLR ( DAXTAX, MSYM)
CALL DCLR ( DAXTBX, MPASS)
C
WRITE ( OUP, 600 )
C
WRITE ( OUP, * ) ' ', ' START INTERPOLATION FOR EACH PASS'
DO 200 I = 1, NPASS
  IREC = NIREC(I)
  IF ( X(I,1). LT. X(I,IREC) ) THEN
    DO 201 N = 1, IREC
      XI(N) = X(I,N)
      YI(N) = H(I,N)
    201 CONTINUE
    ELSE
      DO 202 N = 1, IREC
        NM = IREC + 1 - N
        XI(N) = X(I,NM)
        YI(N) = H(I,NM)
      202 CONTINUE
    END IF
    L = 1
    DO 203 N = 2, IREC
      IF ( XI(N). GT. XI(1) ) THEN
        L = L + 1
        XI(L) = XI(N)
        YI(L) = YI(N)
      END IF
    203 CONTINUE
    IRECA = IREC
    IREC = L
    WRITE ( 6, * ) ' '
    WRITE ( 6, * ) ' '
    WRITE ( 6, * ) ' ', 'SPLINE FITTING TO PASS:', NREV(I), ' ',
    & IREC, ' DATA POINTS'
    IF ( IRECA. NE. IREC ) THEN
      NJ = IRECA - IREC
      WRITE ( OUP, * ) ' ', NJ, ' DATA POINTS THAT ARE NOT IN ',
    & 'ASCENDING OR DECENDING ORDER HAVE BEEN REMOVED.'
    END IF
    CALL ICSCCU ( XI, YI, IREC, CIMSL, IREC-1, IER )
    IF ( IER. NE. 0 ) THEN
      WRITE ( OUP, 609 ) ( J, XI(J), YI(J), J=1, IREC)
    END IF
    L = 0
    DO 204 J = 1, NPASS
      IF ( ICX(I,J). NE. 0 ) THEN
        L = L + 1
        U(L) = EX(I,J)
        C
        & WRITE ( OUP, * ) ' ', ' PASS:', NREV(J), ' ELON = ',
        C & EX(I,J), ' U = ', U(L)
      END IF
    204 CONTINUE
    WRITE ( OUP, * ) ' ', ' NUMBER OF CROSSOVERS = ', L
    IF ( L. GT. 0 ) THEN
      CALL ICSEVU ( XI, YI, IREC, CIMSL, IREC-1, U, S, L, IER )
      IF ( IER. NE. 0 ) THEN
        WRITE ( 6, * ) ' ', ' ELON ARRAY'
        WRITE ( 6, * ) ( XI(MM), MM=1, IREC)
        WRITE ( 6, * ) ' ', ' HSS ARRAY'
        WRITE ( 6, * ) ( YI(MM), MM=1, IREC)
      END IF
      L = 0
      DO 205 J = 1, NPASS
        IF ( ICX(I,J). NE. 0 ) THEN
          L = L + 1
          XVR(I,J) = S(L)
          & WRITE ( OUP, * ) ' ', ' XPASS:', NREV(J), ' ELON = ',
          & U(L), ' HSS = ', S(L)
        END IF
      205 CONTINUE

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```

      END IF
200 CONTINUE
C
      NPASS1 = NPASS - 1
      WRITE ( OUP, 600 )
      WRITE ( OUP, * ) ' , , SUMMARY OF CROSSOVERS DIFFERENCES ' ,
& ' BEFORE ADJUSTING FOR BIASES: '
      WRITE ( OUP, 608 ) XDMAX
C
      CALL XOVD ( NPASS, IDS, ICX, ISUM, NREV, MAXOVR, XVR, AX, BX,
& EX, AXTBX, XDMAX, KC, XRMS,
& W, AXT, SMSS, SMGG, SMSG )
C
      DO 300 I = 1, KC
        DO 301 J = IXM+1, NPASS
          AX(I,J-1) = AX(I,J)
301 CONTINUE
300 CONTINUE
C
      DO 400 I = 1, KC
        DO 401 J = 1, NPASS1
          AXT(J,I) = AX(I,J) * W(I)
401 CONTINUE
400 CONTINUE
C
      CALL VMULFF ( AXT, AX, NPASS1, KC, NPASS1, MPASS, MAXOVR, SCR,
& MPASS, IER )
      CALL VCVTFS ( SCR, NPASS1, MPASS, AXTAX )
C
      CALL VMULFF ( AXT, BX, NPASS1, KC, 1, MPASS, MAXOVR, AXTBX,
& MPASS, IER )
C
      DO 700 I = 1, NPASS1
        IDIAG(I) = ( I * (I+1) ) / 2
700 CONTINUE
      DO 701 I = 1, IDIAG(NPASS1)
        DAXTAX(I) = DBLE(AXTAX(I))
701 CONTINUE
      DO 702 I = 1, NPASS1
        DAXTBX(I) = DBLE(AXTBX(I))
702 CONTINUE
      CALL SOLVE ( DAXTAX, DAXTBX, IDIAG, NPASS1, .TRUE., .TRUE. )
C
      DO 800 I = IXM, NPASS1
        K = NPASS + IXM - I
        DAXTBX(K) = DAXTBX(K-1)
800 CONTINUE
      DAXTBX(IXM) = 0.
C
      DO 801 I = 1, NPASS
        AXTBX(I) = SNGL(DAXTBX(I))
801 CONTINUE
C
      XRB = 0.
      DO 802 I = 1, NIREC(IXM)
        XRB = XRB + H(IXM,I) - HG(IXM,I)
802 CONTINUE
      XRB = XRB / FLOAT(NIREC(IXM))
C
      DO 803 I = 1, NPASS
        AXTBX(I) = AXTBX(I) + XRB
803 CONTINUE
C
      WRITE ( OUP, 600 )
      WRITE ( OUP, * ) ' , , SUMMARY OF CROSSOVERS DIFFERENCES ' ,
& ' AFTER ADJUSTING FOR BIASES: '
      WRITE ( OUP, 608 ) XDMAX
C
      CALL XOVD ( NPASS, IDS, ICX, ISUM, NREV, MAXOVR, XVR, AX, BX,
& EX, AXTBX, 1000.0, KC, XRMS,

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```

&          W, AXT, SMSS, SMCG, SMSG )
C
WRITE ( OUP, 601 ) NREV(IXM), XRB
DO 900 I = 1, NPASS
  IF ( ISUM(I).EQ. 0 ) THEN
    AXTBX(I) = 0.
    WRITE ( OUP, 603 ) I, NREV(I), AXTBX(I)
  ELSE IF ( I.EQ. IXM ) THEN
C
C
    WRITE ( OUP, 604 ) IXM, NREV(IXM)
  ELSE
    WRITE ( OUP, 602 ) I, NREV(I), AXTBX(I)
  END IF
900 CONTINUE
C
DO 1100 I = 1, NPASS
  ICB(I) = IFIX(AXTBX(I)*1000.)
1100 CONTINUE
C
REWIND INP
NREC = 0
4000 READ ( INP, END = 9000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&          I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&          I20,I21,I22,I23,I24,I25,I26,I27,I28
C*****
  IF ( I14.EQ. 12793 ) THEN
    I13 = -1000000
    GO TO 888
  END IF
C*****
  NREC = NREC + 1
  IBIAS = 0
C
DO 1101 I = 1, NPASS
  IF ( I14.EQ. NREV(I) ) THEN
    IBIAS = I
    GO TO 5000
  END IF
1101 CONTINUE
C
5000 CONTINUE
C
IF ( IBIAS.EQ. 0 ) THEN
  I13 = -1000000
ELSE
  I13 = I13 - ICB(IBIAS)
END IF
C
888 CONTINUE
WRITE ( OUG ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&          I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&          I20,I21,I22,I23,I24,I25,I26,I27,I28
GO TO 4000
C
9000 WRITE ( OUP, 600 )
WRITE ( OUP, * ) ' ', NREC, ' RECORDS ADJUSTED FOR ORBIT BIAS'
C
C.....DETERMINE THE ERROR COVARIANCE MATRIX
C
CALL SYMINV ( DAXTAX, DAXTBX, IDIAG, NPASS1, ERCOVM )
C
MM = (NPASS1*(NPASS1+1))/2
WRITE ( OUC, 610 ) (ERCOVM(I),I=1,MM)
C
WRITE ( OUP, * ) ' '
WRITE ( OUP, * ) ' ', 'THE COVARIANCE MATRIX OF BIAS ADJUSTMENT',
&          ' HAS BEEN WRITTEN TO FILE BLACK.PCOV.'
C
501 FORMAT(2X,I3,8F9.3)
600 FORMAT(1H1)
601 FORMAT(1H1,T20,'BIAS FOR SATELLITE PASSES OVER THE ',

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&          'BLACK SEA:',/,/,T23,'THE REFERENCE SATELLITE ',
&          'PASS IS # ',I5,/,/,T26,'THE BIAS OF THIS PASS WRT ',
&          'GEOID MODEL OSU-180 IS ',F10.4,' METERS',/)
602 FORMAT(1H0,T15,I4,5X,'PASS #',I6,5X,'BIAS (METERS):',F10.4)
603 FORMAT(1H0,T15,I4,5X,'PASS #',I6,5X,'BIAS (METERS):',F10.4,5X,
&          '***** THIS PASS HAS NO CROSSOVER *****')
604 FORMAT(1H0,T15,I4,5X,'PASS #',I6,5X,' ### REFERENCE PASS ###')
605 FORMAT((1H ,32F4.0))
606 FORMAT((1H ,26F5.0))
607 FORMAT((1H ,10(1PE12.4)))
608 FORMAT(1H ,/,T10,'THE CUTOFF WINDOW FOR CROSSOVER DIFFERENCES',
&          ' IS ',F7.2,' METERS',/)
609 FORMAT((1H ,T10,I6,2F12.4))
610 FORMAT((4D20.13))
C
  STOP
  END
C
  SUBROUTINE XOVD ( NPASS, IDS, ICX, ISUM, NREV, MAXOVR, XVR,
&                AX, BX, EX, BIAS, XDMAX, KC, XRMS,
&                W, AXT, SMSS, SMGG, SMSG )
C
  REAL*4      XVR(NPASS,NPASS), EX(NPASS,NPASS)
  REAL*4      BIAS(NPASS), AX(MAXOVR,NPASS), BX(MAXOVR)
  REAL*4      W(MAXOVR), AXT(NPASS,MAXOVR)
  INTEGER*4   ICX(NPASS,NPASS), IDS(NPASS), ISUM(NPASS), NREV(NPASS)
  INTEGER*4   K75, K78, K7578, KC, MAXOVR, OUP
  DATA      OUP / 6 /
C
  XRMS = 0.
  KC = 0
  K75 = 0
  K78 = 0
  K7578 = 0
C
  DO 100 I = 1, NPASS
    DO 101 J = I, NPASS
      IF ( ICX(I,J). NE. 0 ) THEN
        XVR(I,J) = XVR(I,J) - BIAS(I)
        XVR(J,I) = XVR(J,I) - BIAS(J)
        BXT = XVR(I,J) - XVR(J,I)
        IF ( ICX(I,J). EQ. -1 ) THEN
          ICX(I,J) = 0
          ICX(J,I) = 0
          WRITE ( OUP, 600 ) EX(I,J),NREV(I),XVR(I,J),NREV(J),
&                            XVR(J,I),BXT
        ELSE IF ( ABS(BXT). LE. XDMAX ) THEN
          KC = KC + 1
          AX(KC,I) = 1.0
          AX(KC,J) = -1.0
          BX(KC) = BXT
          XRMS = XRMS + BXT*BXT
          WRITE ( OUP, 601 ) EX(I,J),NREV(I),XVR(I,J),NREV(J),
&                            XVR(J,I),BX(KC)
        IF ( IDS(I). EQ. IDS(J) ) THEN
          IF ( IDS(I). EQ. 7502701 ) THEN
            K75 = K75 + 1
            W(KC) = SMGG
          END IF
          IF ( IDS(I). EQ. 7806401 ) THEN
            K78 = K78 + 1
            W(KC) = SMSS
          END IF
        ELSE
          K7578 = K7578 + 1
          W(KC) = SMSG
        END IF
      ELSE
        ICX(I,J) = 0
        ICX(J,I) = 0
    END DO
  END DO

```



```

        ISUM(I) = ISUM(I) - 1
        ISUM(J) = ISUM(J) - 1
        WRITE ( OUP, 602 ) EX(I,J),NREV(I),XVR(I,J),NREV(J),
& XVR(J,I),BXT
&
        END IF
    END IF
101 CONTINUE
100 CONTINUE
C
    XRMS = SQRT ( XRMS / FLOAT(KC) )
C
    WRITE ( OUP, 603 ) XRMS, K75, K78, K7578, KC
C
600 FORMAT(1H ,T15,'X @ E. LONG = ',F6.2,8X,
& '#',I5,'(',F6.2,') - #',I5,'(',F6.2,')',
& '-----> ',F8.2,5X,' ** EDITTED OUT (A PRIORI) **')
601 FORMAT(1H ,T15,'X @ E. LONG = ',F6.2,8X,
& '#',I5,'(',F6.2,') - #',I5,'(',F6.2,')',
& '-----> ',F8.2)
602 FORMAT(1H ,T15,'X @ E. LONG = ',F6.2,8X,
& '#',I5,'(',F6.2,') - #',I5,'(',F6.2,')',
& '-----> ',F8.2,5X,' ** DISCARDED (IN SITU) **')
603 FORMAT(1H0,/,T20,'RMS (M) = ',F10.4,/,
& T24,' # OF GEO3-GEO3 CROSSOVERS = ',I5,/,
& T24,' # OF SEASAT-SEASAT CROSSOVERS = ',I5,/,
& T24,' # OF GEO3-SEASAT CROSSOVERS = ',I5,/,
& T24,' TOTAL # OF CONSIDERED CROSSOVERS = ',I5)
C
    RETURN
    END
C
    SUBROUTINE CURVE ( NPASS, X, Y, Z, ZG, YR, IREC, IDP, IDSAT,
& A, B, C, F, FT, G,
& SX, SY, SZ, SZG, DDZ, D, SIGE )
C
    REAL*4 X(IREC), Y(IREC), Z(IREC), ZG(IREC), YR(IREC)
    REAL*4 SX(IREC), SY(IREC), SZ(IREC)
    REAL*4 SZG(IREC), DDZ(IREC), D(IREC)
    REAL*8 F(IREC,3), FT(3,IREC)
    REAL*8 E(3,3), EI(3,3), AE(6)
    REAL*8 G(IREC), H(3)
    REAL*8 A, B, C, DET, YD
    INTEGER*4 IDP, IDSAT, IREC, NPASS
    INTEGER*4 IDIAG(3) / 1, 3, 6 /
    INTEGER*4 OUP / 6 /
C
C.....EVICT THE BAD DATA POINTS BY COMPARING THE ABSOLUTE DIFFERENCE
C BETWEEN ADJACENT DATA POINTS
C
    NB = 0
    IREC1 = IREC - 1
C
    DO 111 I = 1, IREC
        SX(I) = -1.0
111 CONTINUE
C
    DO 112 I = 1, IREC1
        DDZ(I) = ABS( Z(I+1) - Z(I) )
112 CONTINUE
C
    DO 113 J = 1, IREC1
        IF(DDZ(J).LT.SIGE) THEN
            K = J
            GO TO 200
        END IF
113 CONTINUE
C
200 CONTINUE
    DO 222 J = 1, IREC
        IF(DDZ(IREC-J).LT.SIGE) THEN

```

```

                IRECG = IREC-J
                GO TO 300
            END IF
222 CONTINUE
C
300 KB = 0
    DO 333 I = 1, IRECG-1
        IF(DDZ(I).GT.SIGE) KB = KB + 1
333 CONTINUE
C
        LG = 1
        SX(LG) = X(K)
        SY(LG) = Y(K)
        SZ(LG) = Z(K)
        SZG(LG) = ZG(K)
C
400 LG = LG + 1
    K = K + 1
    IF(DDZ(K-1).GT.SIGE) THEN
        K = K + 1
        DO 444 I = 1, KB-1
            IF(DDZ(K-1).GT.SIGE) K = K + 1
444 CONTINUE
        END IF
        SX(LG) = X(K)
        SY(LG) = Y(K)
        SZ(LG) = Z(K)
        SZG(LG) = ZG(K)
        IF(K.LE.IRECG) GO TO 400
C
    DO 555 I = 1, LG
        F(I,1) = SX(I)*SX(I)
        F(I,2) = SX(I)
        F(I,3) = 1.0D0
        G(I) = SY(I)
555 CONTINUE
C
    DO 666 I = 1, LG
        DO 667 J = 1, 3
            FT(J,I) = F(I,J)
667 CONTINUE
666 CONTINUE
C
    DO 777 I = 1, 3
        DO 778 J = 1, 3
            E(I,J) = 0.D0
            DO 779 K = 1, LG
                E(I,J) = E(I,J) + FT(I,K)*F(K,J)
779 CONTINUE
778 CONTINUE
777 CONTINUE
C
    DO 888 I = 1, 3
        H(I) = 0.D0
        DO 889 K = 1, LG
            H(I) = H(I) + FT(I,K)*G(K)
889 CONTINUE
888 CONTINUE
C
        AE(1) = E(1,1)
        AE(2) = E(1,2)
        AE(3) = E(2,2)
        AE(4) = E(1,3)
        AE(5) = E(2,3)
        AE(6) = E(3,3)
C
    CALL SOLVE ( AE, H, IDIAG, 3, .TRUE., .TRUE. )
C
    A = H(1)
    B = H(2)

```

```

C      C = H(3)
C
C      DET = E(1,1) * ( E(2,2)*E(3,3) - E(2,3)*E(2,3) ) +
&      E(1,2) * ( E(1,3)*E(2,3) - E(1,2)*E(3,3) ) +
&      E(1,3) * ( E(1,2)*E(2,3) - E(1,3)*E(2,2) )
C
C      EI(1,1) = ( E(2,2)*E(3,3) - E(2,3)*E(2,3) ) / DET
C      EI(2,2) = ( E(1,1)*E(3,3) - E(1,3)*E(1,3) ) / DET
C      EI(3,3) = ( E(1,1)*E(2,2) - E(1,2)*E(1,2) ) / DET
C      EI(2,3) = ( E(1,2)*E(1,3) - E(1,1)*E(2,3) ) / DET
C      EI(1,3) = ( E(1,2)*E(2,3) - E(1,3)*E(2,2) ) / DET
C      EI(1,2) = ( E(1,3)*E(2,3) - E(1,2)*E(3,3) ) / DET
C
C      A = ( EI(1,1)*H(1) + EI(1,2)*H(2) + EI(1,3)*H(3) )
C      B = ( EI(1,2)*H(1) + EI(2,2)*H(2) + EI(2,3)*H(3) )
C      C = ( EI(1,3)*H(1) + EI(2,3)*H(2) + EI(3,3)*H(3) )
C
C      RMS = 0.
C      DO 999 I = 1, LG
C          YD = A*SX(I)*SX(I) + B*SX(I) + C
C          YR(I) = SNGL(YD)
C          D(I) = YR(I) - SY(I)
C          RMS = RMS + D(I)*D(I)
999 CONTINUE
C      RMS = SQRT ( RMS/FLOAT(LG) )
C
C      WRITE ( OUP, 601 ) NPASS, IDP, IDSAT, A, B, C,
&      SX(1), SY(1), SX(LG), SY(LG), RMS, LG
C      IF ( RMS.GT. 0.005 ) THEN
C          WRITE ( 6, * )
C          WRITE ( 6, 602 ) (M,SX(M),SY(M),YR(M),D(M),M=1,LG)
C          WRITE ( 6, * )
C      END IF
C
C      IF ( LG. NE. IREC ) THEN
C          IREC = LG
C          DO 1111 I = 1, IREC
C              X(I) = SX(I)
C              Y(I) = SY(I)
C              Z(I) = SZ(I)
C              ZG(I) = SZG(I)
1111 CONTINUE
C      END IF
C
C      601 FORMAT(1H0,/,1X,I3,I7,I9,3E14.5,5F10.4,I6)
C      602 FORMAT((1H ,T5,I4,3X,3F10.4,2X,F10.4))
C
C      RETURN
C      END
C
C      SUBROUTINE XOVER ( NPASS, NREV, IDSAT, A, B, C, SLON1, SLAT1,
&      SLON2, SLAT2, ICX, EX, GY, ISUM, LN, LY, IXM )
C
C      INTEGER      NREV(NPASS), IDSAT(NPASS)
C      INTEGER      ICX(NPASS,NPASS), ISUM(NPASS), LN(NPASS), LY(NPASS)
C      INTEGER      INDEX(2)
C      REAL*4      SLAT1(NPASS), SLAT2(NPASS), SLON1(NPASS), SLON2(NPASS)
C      REAL*4      EX(NPASS,NPASS), GY(NPASS,NPASS)
C      REAL*4      P, Q
C      REAL*8      A(NPASS), B(NPASS), C(NPASS)
C      REAL*8      T(2)
C      REAL*8      DA,DB,DC,RT,SRT
C      INTEGER      ITOTAL, IXM, MAXIX, MX, MXS, MX75, MX78, NPASS
C      INTEGER      IJK, IP, JP
C      INTEGER      JOUT, OUP
C      DATA      JOUT / 4 /, OUP / 6 /
C      DATA      MAXIX / 0 /, MX / 0 /, MX75 / 0 /, MX78 / 0 /
C      DATA      ITOTAL / 0 /
C
C      DO 123 I = 1, NPASS

```

```

        ISUM(I) = 0
        DO 234 J = 1, NPASS
            ICX(I,J) = 0
            EX(I,J) = 0.
            GY(I,J) = 0.
234    CONTINUE
123 CONTINUE
C
    WRITE ( OUP, 600 )
C
    DO 222 I = 1, NPASS-1
C
        WRITE( OUP, 601 ) NREV(I), IDSAT(I), SLON1(I), SLAT1(I),
        & SLON2(I), SLAT2(I)
C
        DO 333 J = I+1, NPASS
C
            INDEX(1) = 0
            INDEX(2) = 0
            DB = B(J) - B(I)
            DA = A(I) - A(J)
            DC = C(I) - C(J)
            RT = DB*DB - 4.0*DA*DC
C
            IF ( RT. GE. 0.0 ) THEN
                IF ( RT. EQ. 0.0 ) THEN
                    SRT = 0.0
                ELSE
                    SRT = DSQRT(RT)
                END IF
                T(1) = (DB+SRT)/(2.0*DA)
                T(2) = (DB-SRT)/(2.0*DA)
                WRITE(6,*) T, RT, SRT
C
                DO 135 L = 1, 2
                    IF ( SLON2(I). GT. SLON1(I) ) THEN
                        IF( T(L). GE. SLON1(I). AND. T(L). LE. SLON2(I) )
                            & INDEX(L) = INDEX(L) + 1
                    ELSE
                        IF( T(L). LE. SLON1(I). AND. T(L). GE. SLON2(I) )
                            & INDEX(L) = INDEX(L) + 1
                    END IF
                    IF ( SLON2(J). GT. SLON1(J) ) THEN
                        IF( T(L). GE. SLON1(J). AND. T(L). LE. SLON2(J) )
                            & INDEX(L) = INDEX(L) + 1
                    ELSE
                        IF( T(L). LE. SLON1(J). AND. T(L). GE. SLON2(J) )
                            & INDEX(L) = INDEX(L) + 1
                    END IF
135    CONTINUE
C
                DO 246 L = 1, 2
                    IF ( INDEX(L). EQ. 2 ) THEN
                        MX = MX + 1
                        P = SNGL (T(L) )
                        Q = SNGL ( A(I)*P*P + B(I)*P + C(I) )
                        EX(I,J) = P
                        GY(I,J) = Q
                        EX(J,I) = P
                        GY(J,I) = Q
                        WRITE ( OUP, 602 ) NREV(J), IDSAT(J), P, Q,
                        & SLON1(J), SLAT1(J), SLON2(J), SLAT2(J)
                        ICX(I,J) = ICX(I,J) + 1
                        ICX(J,I) = ICX(I,J)
                        IF ( IDSAT(I). EQ. IDSAT(J) ) THEN
                            IF ( IDSAT(I). EQ. 7502701 ) MX75 = MX75 + 1
                            IF ( IDSAT(I). EQ. 7806401 ) MX78 = MX78 + 1
                        END IF
                END IF
246    CONTINUE

```

```

C          END IF
C
C 333  CONTINUE
C
C 222  CONTINUE
C
WRITE ( OUP, * ) ' '
WRITE ( OUP, * ) ' '
WRITE ( OUP, * ) ' TOTAL # OF POSSIBLE CROSSOVERS = ', MX
WRITE ( OUP, * ) ' '
WRITE ( OUP, * ) ' TOTAL # OF GEO3-GEO3 CROSSOVERS = ', MX75
WRITE ( OUP, * ) ' '
WRITE ( OUP, * ) ' TOTAL # OF SEASAT-SEASAT CROSSOVERS = ', MX78
MXS = MX - MX75 - MX78
WRITE ( OUP, * ) ' '
WRITE ( OUP, * ) ' TOTAL # OF GEOS3-SEASAT CROSSOVERS = ', MXS
C
C.....EDIT OUT BAD CROSSOVERS BASED ON A PRIORI KNOWLEDGE
C
DO 555  IR = 1, 500
  READ ( JOUT, 501, END = 556 ) JC, IP, JP
  IF ( JC.EQ. 0. AND. ICX(IP,JP). NE. 0 ) THEN
    ICX(IP,JP) = -1
    ICX(JP,IP) = -1
  END IF
555 CONTINUE
C
556 CONTINUE
C
DO 345  I = 1, NPASS
  DO 456  J = 1, NPASS
    IJK = ICX(I,J)
    IF ( IJK. LT. 0 ) IJK = 0
    ISUM(I) = ISUM(I) + IJK
456 CONTINUE
  ITOTAL = ITOTAL + ISUM(I)
345 CONTINUE
  ITOTAL = ITOTAL/2
C
DO 567  I = 1, NPASS
  MAXIX = MAX0 ( MAXIX, ISUM(I) )
567 CONTINUE
C
DO 678  I = 1, NPASS
  IF ( ISUM(I). EQ. MAXIX ) IXM = I
678 CONTINUE
C
WRITE ( OUP, 603 )
WRITE ( OUP, 604 ) ( I, NREV(I), I = 1, NPASS )
WRITE ( OUP, 605 ) NPASS
WRITE ( OUP, 606 ) ( NREV(I), (ICX(I,J), J=1, 94), ISUM(I),
  I=1, NPASS )
WRITE ( OUP, 607 ) NREV(IXM), MAXIX, ITOTAL
C
MM = 0
NN = 0
DO 789  I = 1, NPASS
  IF ( ICX(IXM,I). EQ. 1 ) THEN
    MM = MM + 1
    LY(MM) = I
  ELSE
    NN = NN + 1
    LN(NN) = I
  END IF
789 CONTINUE
C
WRITE ( OUP, 608 ) NREV(IXM), MM, NN, MM+NN
WRITE ( OUP, 609 ) ( NREV(LY(I)), I = 1, MM )
C

```

```

DO 987 J = 1, NN
  WRITE ( OUP, 610 ) NREV(LN(J))
  DO 876 I = 1, NPASS
    IF ( ICX(I, LN(J)). EQ. 1 ) THEN
      WRITE ( OUP, 611 ) NREV(I)
      GO TO 888
    END IF
  876 CONTINUE
  888 CONTINUE
  987 CONTINUE
C
501 FORMAT(I1,2I10)
600 FORMAT(1H1,T20,'BLACK SEA CROSS-OVER LISTING:',//)
601 FORMAT(1H0,/,T5,'PASS = ',I6,5X,'SAT ID = ',I10,5X,4F10.6//)
602 FORMAT(1H ,T10,'XPASS = ',I6,5X,'SAT ID = ',I10,5X,2F10.3,
&
5X,4F10.6)
603 FORMAT(1H1,T20,'ROW-COLUMN ELEMENTS OF PASS CORRELATION MATRIX:',
&
//)
604 FORMAT((1H ,10(3X,I4,I6)))
605 FORMAT(1H1,T20,'PARTIAL (94) PASS CORRELATION MATRIX FOR',
&
I5,' PASSES:',//)
606 FORMAT((1H ,10X,I8,5X,94I1,5X,I3))
607 FORMAT(1H0,/,T10,'PASS # ',I6,' HAS THE MAXIMUM OF ',I5,
&
' CROSSOVERS.',//,T10,' THE TOTAL # OF CROSSOVERS IS:',I5)
608 FORMAT(1H1,T5,'REFERENCE PASS = ',I6,T10,3I6,/,
&
T10,' THE DIRECT CROSS-PASSES ARE:',//)
609 FORMAT((1H0,20I6))
610 FORMAT(1H0,/,T5,'PASS: ',I6,' IS INDIRECTLY RELATED TO THE')
611 FORMAT(1H ,T10,'REFERENCE PASS VIA PASS ',I6)
C
RETURN
END
C
SUBROUTINE SOLVE (A,B, IDIAG,NEQ, FACT,BACK)
C
C Compute the U**T * D * U factorization of the symmetric matrix
C stored in A, if FACT = TRUE; and solve A * X = B if BACK = TRUE.
C
C
C A Contains the compacted-column form of the upper triangular
C part of the coefficient matrix. After factorization, it
C contains D and U.
C B Right-hand-side vector. After backsubstitution, it
C contains the solution.
C
C IDIAG Addresses of the diagonal terms in A.
C NEQ Number of equations
C
C FACT If FACT = TRUE, then factor A; otherwise do not factor A.
C BACK If BACK = TRUE, reduce B and backsubstitute; otherwise
C do not solve the equations.
C
C
C
C IMPLICIT REAL*8 (A-H,O-Z)
C LOGICAL FACT,BACK
C DIMENSION A(1),B(1),IDIAG(1)
C
C Factor A, reduce B
  JR = 0
  DO 400 J = 1, NEQ
    JD = IDIAG(J)
    JH = JD - JR
    IS = J - JH + 2
C
    IF (JH .LT. 2) GOTO 390
C
    IF (FACT) THEN

```

```

      IF (JH .GT. 2) THEN
C..  Reduce column J rows IS to J-1: do not divide by row diagonal
      K = JR + 2
      ID = IDIAG(IS - 1)
C
      DO 100 I = IS, J-1
      IR = ID
      ID = IDIAG(I)
      IH = MIN (ID-IR-1,I-IS+1)
      IF (IH.GT.0) A(K) = A(K) - DOT(A(K-IH),A(ID-IH),IH)
      K = K + 1
100  CONTINUE
      ENDIF
C
C..  Divide by row diagonal, and reduce diagonal term in column J
C
      IR = JR + 1
      K = J - JD
      DO 200 I = IR, JD-1
      ID = IDIAG(K+I)
      IF (A(ID).EQ.0.0) GOTO 200
      D = -A(I)
      A(I) = A(I)/A(ID)
      A(JD) = A(JD) + D*A(I)
200  CONTINUE
C
      ENDIF
C
C..  Reduce RHS
      IF (BACK) B(J) = B(J) - DOT(A(JR+1),B(IS-1),JH-1)
C
390  JR = JD
400  CONTINUE
C
      IF (.NOT.BACK) RETURN
C
C
C  Divide by diagonal pivots
C
      DO 700 I = 1,NEQ
      ID = IDIAG(I)
      IF (A(ID).NE.0.0) B(I) = B(I)/A(ID)
700  CONTINUE
C
C  Backsubstitute
C
      J = NEQ
      JD = IDIAG(J)
C
801  D = -B(J)
      J = J - 1
      IF (J.LE.0) RETURN
C
      JR = IDIAG(J)
      IF (JD-JR.GT.1) THEN
      IS = J - JD + JR + 2
      K = JR - IS + 1
      DO 810 I = IS, J
810  B(I) = B(I) + A(I+K)*D
      ENDIF
C
      JD = JR
      GOTO 801
C
      END
C
      FUNCTION DOT (A,B,N)
C  Compute the dot product of the two N-vectors A and B.

```


//GO.FT09F001 DD DSN=ZMAYA.BLACK.PCOV,DISP=SHR
// EXEC NOTIFYTS

A listing of PROGRAM PLTAEF

```
//ZMAYABEA JOB (G0109,360,75),AYAU,TIME=(12,00),CLASS=O,MSGCLASS=X
/*JOBPARM LINES=60
//TEMPLATE EXEC G38PLOT
//FORT.SYSIN DD *
```

C
C FORMAT OF GEOS-3/SEASAT ALTIMETER DATA

VARIABLE	TYPE	DESCRIPTION
	I4	SATELLITE ID
	I2	MEASUREMENT TYPE (42= OVER LAND , 43 = OVER WATER)
	I2	TIME SYSTEM (NM)
	I4	STATION NUMBER
	I4	PREPROCESSING INDICATORS
*	I4	MODIFIED JULIAN DATE OF OBSERVATION
*	R8	FRACTION OF DAY PAST MIDNIGHT (GMT)
	R8	ALTIMETER OBSERVATION (METERS)
	I4	SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
	I4	SATELLITE EAST LONGITUDE (1E-6 DEGREES)
	R4	MEASUREMENT STANDARD DEVIATION (METERS)
	I4	NET INSTRUMENT CORRECTION (MM)
	I4	METEOROLOGICAL DATA WORD (GEODYN VOL 3)
	I4	NET MEDIA CORRECTIONS (MM)
	R4	GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
	I4	NET OCEAN DYNAMIC CORRECTIONS (MM)
*	I4	INDICATED SURFACE ELEVATION (MM)
*	I4	S/C REVOLUTION NUMBER
	I4	MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
	I4	DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
	I2	H 1/3 (CM)
	I2	AGC (DB)
	I2	WIND SPEED (CM/SEC)
	I2	SURFACE ELEVATION PREPROCESSING WORD
	I2	DRY TROPOSPHERIC CORRECTION (MM)
	I2	FNOC WET TROPOSPHERIC CORRECTION (MM)
	I2	SMMR WET TROPOSPHERIC CORRECTION (MM)
	I2	IONOSPHERIC CORRECTION (MM)
	I2	BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
	I2	SOLID EARTH TIDE (MM)
	I2	SCHWIDERSKI OCEAN TIDE (MM)
	I2	PARKE OCEAN TIDE (MM)

```
PARAMETER ( MAXPLT = 9999 )
PARAMETER ( NMAX = 2500 )
PARAMETER ( NINT = 150 )
PARAMETER ( ETOP = 100. )
PARAMETER ( EBOT = 0. )
PARAMETER ( SIGE = 2.0 )
PARAMETER ( SIGT = 8.0E-5 )
PARAMETER ( IC = NMAX - 1 )
```

```
C
INTEGER*2 I2,I3,I17,I18,I19,I20,I21,I22,I23,I24,I25,I26,I27,I28
INTEGER*4 I1,I4,I5,I6,I7,I8,I9,I10,I11,I12,I13,I14,I15,I16
REAL*8 R1,R2
REAL*4 R3,R4
INTEGER*4 IDSAT
REAL*4 GLAT, ELON, HSS
REAL*4 X(NMAX),Y(NMAX),YM(NMAX),DF(NMAX),C(NMAX-1,3)
REAL*4 F(NMAX),GX(NMAX),GY(NMAX),DGY(NMAX),DDY(NMAX)
REAL*4 DDT(NMAX),XA(NMAX),YA(NMAX),DYA(NMAX)
REAL*4 WK(7*NMAX+14),XF(NINT+1),YF(NINT+1)
INTEGER INP, IREC, IPLOT, NREC, NREV, OUP
INTEGER LIST(6)
INTEGER IBC(NMAX)
```

```
C
DATA INP / 3 /, ING / 4 /, OUP / 6 /
DATA LIST / 8, 110, 75, 0, 7, 10 /
DATA IREC / 0 /, NREC / 0 /, IPLOT / 0 /
```

```

      READ ( INP ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
& I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
& I20,I21,I22,I23,I24,I25,I26,I27,I28
      NREV = I14
      REWIND INP
      CALL USTART
      CALL UINQES(1.0,SUPRT)
      IF(SUPRT.NE.0.0) CALL UESCAP(1.0,LIST,6.0,IDUM,DUM)
C
1000 READ ( INP, END = 2000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
* I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
* I20,I21,I22,I23,I24,I25,I26,I27,I28
      READ ( ING, 500, END = 2000 ) IDUM1,GL,EL,DUM2,DUM3,DUM4,
* DUM5,DUM6,GUND
500 FORMAT(2X,I3,8F9.3)
      NREC = NREC + 1
      GLAT = 1.0E-6 * FLOAT(I7)
      ELON = 1.0E-6 * FLOAT(I8)
      HSS = 1.0E-3 * FLOAT(I13)
      IDSAT = I1
C
      IF ( I14. EQ. NREV ) THEN
        IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
          IREC = IREC + 1
          RMJD = FLOAT(I6)
          RNREV = FLOAT(I14)
          X(IREC) = R1
          Y(IREC) = HSS
          DF(IREC) = R3
          YM(IREC) = GUND
        END IF
      ELSE
C
C.....PLOT THE PREVIOUS ELEVATION PROFILE
C
        IF ( IPLOT. GT. MAXPLT ) GO TO 3000
        IF ( IREC. GT. 4 ) THEN
C
          IPLOT = IPLOT + 1
          WRITE ( OUP, 601 ) IPLOT, RNREV
          CALL PLOT(X,Y,YM,DF,IREC,RMJD,RNREV,IDSAT,IC,NINT,NMAX,
& C,F,GX,GY,DGY,DDY,WK,XF,YF,DDT,XA,YA,DYA,IBC,
& SIGE,SIGT)
C
        END IF
C
        NREV = I14
        IREC = 1
        IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
          X(IREC) = R1
          Y(IREC) = HSS
          DF(IREC) = R3
          YM(IREC) = GUND
        ELSE
          IREC = IREC - 1
        END IF
      END IF
C
      GO TO 1000
C
2000 CONTINUE
C
      IF ( IREC. GT. 4 ) THEN
        IPLOT = IPLOT + 1
        WRITE ( OUP, 601 ) IPLOT, RNREV
        CALL PLOT(X,Y,YM,DF,IREC,RMJD,RNREV,IDSAT,IC,NINT,NMAX,
& C,F,GX,GY,DGY,DDY,WK,XF,YF,DDT,XA,YA,DYA,IBC,
& SIGE,SIGT)
C
      END IF
C

```

```

3000 WRITE( OUP, * ) ' '
      WRITE( OUP, * ) ' ', NREC, ' RECORDS IN FILE.'
      WRITE( OUP, * ) ' ', IPLOT, ' ELEVATION PROFILES PLOTTED.'
C
      CALL UEND
C
601  FORMAT(1H0, //, T5, 'START PLOT # ', I4, ' OF PASS # ', F6.0)
      STOP
      END
C
      SUBROUTINE PLOT ( X, Y, YM, DF, IREC, RMJD, RNREV, IDSAT, IC,
& NINT, NMAX, C, F, GX, GY, DGY, DDY, WK, XF, YF,
& DDT, XA, YA, DYA, IBC, SIGE, SIGT )
C
      REAL*4      X(NMAX), Y(NMAX), YM(NMAX), DF(NMAX), C(NMAX-1,3)
      REAL*4      F(NMAX), GX(NMAX), GY(NMAX), DGY(NMAX), DDY(NMAX)
      REAL*4      WK(7*NMAX+14), XF(NINT+1), YF(NINT+1)
      REAL*4      DDT(NMAX), XA(NMAX), YA(NMAX), DYA(NMAX)
      INTEGER*4   IDSAT
      INTEGER     IBC(NMAX)
      CHARACTER*1 DATE(10)
C
C
C.....EVICT THE BAD DATA POINTS BY COMPARING THE ABSOLUTE DIFFERENCE
C      BETWEEN ADJACENT DATA POINTS
C
      IREC1 = IREC - 1
      RECL = FLOAT(IREC-1)
C
      DO 110 I = 1, NMAX
        GX(I) = -1.0
110  CONTINUE
C
      DO 111 I = 1, IREC1
        DDY(I) = ABS( Y(I+1) - Y(I) )
111  CONTINUE
C
      DO 112 J = 1, IREC1
        IF(DDY(J).LT.SIGE) THEN
          K = J
          GO TO 222
        END IF
112  CONTINUE
C
222  CONTINUE
      DO 113 J = 1, IREC
        IF(DDY(IREC-J).LT.SIGE) THEN
          IRECG = IREC-J
          GO TO 223
        END IF
113  CONTINUE
C
223  KB = 0
      DO 224 I = 1, IRECG-1
        IF(ABS(DDY(I)).GT.SIGE) KB = KB + 1
224  CONTINUE
C
      LG = 1
      GX(LG) = X(K)
      GY(LG) = Y(K)
      DGY(LG) = DF(K)
C
888  LG = LG + 1
      K = K + 1
      IF(ABS(DDY(K-1)).GT.SIGE) THEN
        K = K + 1
        DO 225 I = 1, KB-1
          IF(ABS(DDY(K-1)).GT.SIGE) K = K + 1

```

```

225  CONTINUE
      END IF
      GX(LG) = X(K)
      GY(LG) = Y(K)
      DGY(LG) = DF(K)
      IF(K.LE.IRECG) GO TO 888
C
C      IB = 0
C      DO 234 K = 1, LG-1
C          IF(DDT(K).GT.SIGT) THEN
C              IB = IB + 1
C              IBC(IB) = K
C          END IF
C      234 CONTINUE
C
C      IF(IB.EQ.1) THEN
C          KXG1 = IBC(1)
C          KXG2 = LG
C      END IF
C
C      IF(IB.EQ.1) LG = KXG1
C
C      NA = 0
C      DO 999 N = 1, LG, 3
C          NA = NA + 1
C          SX = 0.
C          SY = 0.
C          SYA = 0.
C          JC = 0
C          DO 900 L = N, N+2
C              IF(GX(L).LT.0.) GO TO 246
C              JC = JC + 1
C              SX = SX + GX(L)
C              SY = SY + GY(L)
C              SYA = SYA + DGY(L)
C          900 CONTINUE
C      246 RJC = FLOAT(JC)
C          XA(NA) = SX/RJC
C          YA(NA) = SY/RJC
C          DYA(NA) = SYA/RJC
C      999 CONTINUE
C
C      IF(IB.EQ.1) THEN
C          LG = KXG2
C          DO 998 N = KXG1+1, LG, 3
C              NA = NA + 1
C              SX = 0.
C              SY = 0.
C              SYA = 0.
C              JC = 0
C              DO 910 L = N, N+2
C                  IF(GX(L).LT.0.0) GO TO 357
C                  JC = JC + 1
C                  SX = SX + GX(L)
C                  SY = SY + GY(L)
C                  SYA = SYA + DGY(L)
C              910 CONTINUE
C          357 RJC = FLOAT(JC)
C              XA(NA) = SX/RJC
C              YA(NA) = SY/RJC
C              DYA(NA) = SYA/RJC
C          998 CONTINUE
C      END IF
C
C.....DETERMINE THE CUBIC SPLINE COEFFICIENTS C OF THE ELEVATION PROFILE
C
C      IF(LG.GE.8) THEN
C          SM = FLOAT(LG)
C          CALL ICSSCU(GX,GY,DGY,LG,SM,F,C,IC,WK,IER)
C      END IF

```

```

C
C.....START THE GRAPHIC PROCEDURES
C
    CALL USET('PERCENTUNITS')
    CALL USET('EXTRALARGE')
    CALL UVWPRT(0.0, 99.0, 0.0, 99.0)
    CALL UOUTLN
C
C.....PRINT TITLE, JULIAN DATE AND PASS NUMBER.
C
    CALL USET('CJUST')
    CALL USET('TJUST')
    CALL UPSET('PRECISION',6.0)
    CALL UPRINT(50.,97.,
    * 'ADJUSTED BLACK SEA ALTIMETER ELEVATION PROFILES')
    CALL UPRINT(50.,93.,'MODIFIED JULIAN DATE : $')
    CALL UMOVE(68.,93.)
    CALL UPRT1(RMJD,'REAL')
    CALL UPRINT(50.,89.,'PASS : $')
    CALL UMOVE(58.,89.)
    CALL UPRT1(RNREV,'REAL')
    IF ( IDSAT. EQ. 7502701 ) THEN
        CALL UPRINT(50.,85.,'SATELLITE : GEOS-3$')
    END IF
    IF ( IDSAT. EQ. 7806401 ) THEN
        CALL UPRINT(50.,85.,'SATELLITE : SEASATS')
    END IF
    CALL ZTIME( DATE, 8 )
    CALL FMOVE( DATE(10), 1, '$' )
    CALL UPRINT(88.,6.,DATE)
    CALL UPRINT(88.,3.,'STX/ZMAYAS')
C
C.....DRAW AND LABEL AXES (DEFAULT TIC MARKS)
C
    CALL USET('NOORIGIN')
    CALL UVWPRT(5.,95.,7.,85.)
C
    CALL USET('DSYMBOL')
C
    CALL UPSET('SYMBOL',5.0)
C
    CALL UPSET('SZSYMBOL',1.0)
    CALL USET('LARGE')
    CALL UPSET('XLABEL','FRACTION OF DAY PAST MIDDNIGHTS$')
    CALL UPSET('YLABEL','SURFACE ELEVATION IN METERS$')
    CALL USET('XBOTH')
    CALL USET('YBOTH')
    CALL USET('OWNSCALE')
C
    CALL UPSET('TICK',TCX)
C
    CALL UPSET('TICY',TCY)
    XMIN = X(1)
    XMAX = X(IREC)
    YMIN = GY(1)
    YMAX = GY(1)
    DO 444 I = 1, LG
        YMIN = AMIN1 ( GY(I), YMIN )
        YMAX = AMAX1 ( GY(I), YMAX )
    444 CONTINUE
    DO 445 I = 1, IREC
        YMIN = AMIN1 ( YM(I), YMIN )
        YMAX = AMAX1 ( YM(I), YMAX )
    445 CONTINUE
C
C.....DETERMINE THE INTERPOLATION INTERVALS AND PERFORM INTERPOLATION
C
    DX = ( GX(LG) - GX(1) ) / FLOAT(NINT)
    XF(1) = GX(1)
    DO 555 I = 2, NINT+1
        XF(I) = XF(I-1) + DX
    555 CONTINUE
C
    IF(LG.GE.8) THEN
        CALL ICSEVU(GX,F,LG,C,IC,XF,YF,NINT+1,IER)

```

```

      END IF
C
      DO 666 I = 1,NINT+1
          YMIN = AMIN1 ( YF(I), YMIN )
          YMAX = AMAX1 ( YF(I), YMAX )
666 CONTINUE
C
      SX = 0.020 * ( XMAX - XMIN )
      SY = 0.020 * ( YMAX - YMIN )
      XMIN = XMIN - SX
      XMAX = XMAX + SX
      YMIN = YMIN - SY
      YMAX = YMAX + SY
C
      SINDEXT = AINT ( ABS(ALOG10(XMIN)) ) + 4.
C
      XSCALE = 10.**SINDEXT
C
      XMIN = AINT(XMIN*XSCALE)/XSCALE
C
      XMAX = AINT((XMAX*XSCALE)+1.)/XSCALE
C
      YMIN = AINT(YMIN) - AMOD(AINT(YMIN),2.)
      YMAX = AINT(YMAX) + 2. - AMOD( AINT(YMAX), 2. )
      CALL UWINDO(XMIN,XMAX,YMIN,YMAX)
      CALL UAXIS(XMIN,XMAX,YMIN,YMAX)
C
C.....PLOT THE DATA POINTS
C
      DO 777 I = 1, LG
          CALL UMOVE(GX(I),GY(I))
          CALL UPRNT1('X$', 'HORIZ')
777 CONTINUE
C
C.....PLOT THE SMOOTHED PROFILE
C
      IF(LG.GE.8) THEN
          PTS = FLOAT(NINT+1)
          CALL USET('LNULL')
          CALL ULINE(XF,YF,PTS)
      END IF
C
C.....PLOT THE CORRESPONDING GEOID MODEL
C
      PTS = FLOAT(IREC)
      CALL USET('DNULL')
      CALL ULINE(X,YM,PTS)
C
C.....DISPLAY FOR SCREEN
C
      CALL UPAUSE
C
C.....TERMINATED THIS PLOT
C
      CALL UERASE
      CALL URESET
C
      RETURN
      END
/**
/**SYSLIB DD DSN=SYS2.IMSLD,DISP=SHR
/** DD DSN=SYS2.IMSL,DISP=SHR
/**
/**GO.FT03F001 DD DSN=ZMAYA.BLACKA.DATA,DISP=SHR
/**GO.FT04F001 DD DSN=ZMAYA.ALTIM.DATA(BLKRAPP),DISP=SHR
/**
/** *****
/**
/** BLACK SEA DATA ADJUSTED FOR ORBIT BIAS
/**
/** *****
/**
/**GO.FT06F001 DD SYSOUT=*
/** EXEC NOTIFYTS

```



```

      INTEGER      IREC, NREC, NP, NPASS, IDSAT
      INTEGER      NEG, LG, ND, NREV, MG, NTOTAL
      INTEGER      INP, OUP, OUG
C
      DATA      INP / 5 /, OUP / 6 /, OUG / 8 /
      DATA      IREC / 0 /, NREC / 0 /, NEG / 0 /, ND / 0 /, NTOTAL / 0 /
      DATA      NPASS / 1 /
C
      DATA      DTR / 3.490658505E-2 /
      DATA      HSUM / 0.0 /
C
C.....FIRST GENERATE THE GRID NET
C
      GRIDX(1) = XMIN
      DO 100 I = 2, NXI
        GRIDX(I) = GRIDX(I-1) + DX
100 CONTINUE
      GRIDY(1) = YMIN
      DO 101 I = 2, NYI
        GRIDY(I) = GRIDY(I-1) + DY
101 CONTINUE
C
      READ ( INP )  I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&                 I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&                 I20,I21,I22,I23,I24,I25,I26,I27,I28
      IDSAT = I1
      NREV = I14
      REWIND INP
C
1000 READ ( INP, END = 2000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
*                               I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
*                               I20,I21,I22,I23,I24,I25,I26,I27,I28
C*****
      IF ( I14. EQ. 12793 ) GO TO 999
C*****
      NREC = NREC + 1
      GLAT = 1.0E-6 * FLOAT(I7)
      ELON = 1.0E-6 * FLOAT(I8)
      HSS = 1.0E-3 * FLOAT(I13)
C
      IF ( I14. EQ. NREV ) THEN
        IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
          IREC = IREC + 1
          X(IREC) = ELON
          Y(IREC) = GLAT
          Z(IREC) = HSS
          ER(IREC) = R3
        END IF
      ELSE
C
C.....ASSIGN THE PREVIOUS ELEVATION DATA INTO AN ARRAY FOR GRIDDING
C
      IF ( IREC. GT. 4 ) THEN
C
      CALL SELECT( X,Y,Z,ER,IREC, SIGE, LG,BX,BY,BZ,BER,DDZ )
C
      DO 200 I = 1, LG
        ND = ND + 1
        I1 = NINT((BX(I)-CAP-XMIN)/DX)
        J1 = NINT((BY(I)-CAP-YMIN)/DY)
        I2 = NINT((BX(I)+CAP-XMIN)/DX) + 2
        J2 = NINT((BY(I)+CAP-YMIN)/DY) + 2
        IF ( I1. LT. 1 ) I1 = 1
        IF ( J1. LT. 1 ) J1 = 1
        IF ( I2 .GT. NXI ) I2 = NXI
        IF ( J2 .GT. NYI ) J2 = NYI
        DO 201 M = I1, I2
          DO 202 N = J1, J2
            R = (GRIDX(M)-BX(I))**2 + (GRIDY(N)-BY(I))**2
            IF ( R. LE. CAP2 ) THEN
              NGD(M,N) = NGD(M,N) + 1
            END IF
          END DO
        END DO
      END DO

```

```

                WRITE ( OUG ) BX(I),BY(I),BZ(I), M,N, NPASS,BER(I)
            END IF
202     CONTINUE
201     CONTINUE
        HSUM = HSUM + BZ(I)
200     CONTINUE
C
        ELSE
C
            NPASS = NPASS - 1
C
        END IF
C
        IDSAT = I1
        NREV = I14
        NPASS = NPASS + 1
        IREC = 1
        IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
            X(IREC) = ELON
            Y(IREC) = GLAT
            Z(IREC) = HSS
            ER(IREC) = R3
        ELSE
            IREC = IREC - 1
        END IF
    END IF
C
999 CONTINUE
    GO TO 1000
C
2000 CONTINUE
C
    IF ( IREC. GT. 4 ) THEN
C
        CALL SELECT( X,Y,Z,ER,IREC, SIGE, LG,BX,BY,BZ,BER,DDZ )
C
        DO 210 I = 1, LG
            ND = ND + 1
            I1 = NINT((BX(I)-CAP-XMIN)/DX)
            J1 = NINT((BY(I)-CAP-YMIN)/DY)
            I2 = NINT((BX(I)+CAP-XMIN)/DX) + 2
            J2 = NINT((BY(I)+CAP-YMIN)/DY) + 2
            IF ( I1. LT. 1 ) I1 = 1
            IF ( J1. LT. 1 ) J1 = 1
            IF ( I2 .GT. NXI ) I2 = NXI
            IF ( J2 .GT. NYI ) J2 = NYI
            DO 211 M = I1, I2
                DO 212 N = J1, J2
                    R = (GRIDX(M)-BX(I))**2 + (GRIDY(N)-BY(I))**2
                    IF ( R. LE. CAP2 ) THEN
                        NGD(M,N) = NGD(M,N) + 1
                        WRITE ( OUG ) BX(I),BY(I),BZ(I), M,N, NPASS,BER(I)
                    END IF
                CONTINUE
            CONTINUE
            HSUM = HSUM + BZ(I)
        CONTINUE
210
    END IF
C
    HAVG = HSUM/FLOAT(ND)
C
    MG = -1
    DO 300 I = 1, NXI
        DO 301 J = 1, NYI
            MG = MAX0( MG, NGD(I,J) )
            NTOTAL = NTOTAL + NGD(I,J)
        CONTINUE
    CONTINUE
301
300 CONTINUE
C

```

```

C.....WRITE OUT THE DATA SET ASSOCIATED WITH EACH GRID POINT
C
      DO 400 I = 1, NXI
      DO 401 J = 1, NYI
      NP = NGD(I,J)
      IF ( NP. GT. 0 ) THEN
      NEG = NEG + 1
      WRITE ( OUP, 601 ) I, J, GRIDX(I), GRIDY(J), NP
      END IF
401 CONTINUE
400 CONTINUE
C
      WRITE ( OUP, 604 )
      DO 700 I = 1, NXI
      WRITE ( OUP, 605 ) I, (NGD(I,J),J=1,NYI)
700 CONTINUE
C
      WRITE( OUP, 606 ) NREC, ND, NEG, MG, NTOTAL, HAVG
C
601 FORMAT(1H0,T5,'GRID (',I2,',',I2,'):',
& 3X,'ELON = ',F6.2,3X,'GLAT = ',F6.2,
& 5X,'TOTAL DATA POINTS = ',I6)
C 602 FORMAT((1H ,T5,2F9.4,F12.4))
603 FORMAT((3(2F7.2,F12.4)))
604 FORMAT(1H1,///,T20,'DATA DISTRIBUTION MAP:',///)
605 FORMAT(1H ,T5,I4,5X,33I3)
606 FORMAT(1H1,////,T5,'# OF RECORDS READ: ',I8,///,
& T5,'# OF RECORDS USED IN GRIDDING: ',I8,///,
& T5,'# OF NONEMPTY GRID POINTS: ',I4,///,
& T5,'MAXIUM # OF DATA PTS TO A GRID PT: ',I5,///,
& T5,'TOTAL # OF DATA RECORDS: ',I10,///,
& T5,'MEAN GEOID HEIGHT OF THE BLACK SEA: ',F10.4,///,
& T5,'GRIDDED DATA HAVE BEEN WRITTEN TO BLACK4B.SORT.')
C
      STOP
      END
      SUBROUTINE SELECT ( X,Y,Z,E,IREC, SIGE, LG,GX,GY,GZ,GE, DDZ )
C
      REAL*4      X(IREC), Y(IREC), Z(IREC), E(IREC)
      REAL*4      GX(IREC), GY(IREC), GZ(IREC), GE(IREC), DDZ(IREC)
C
C.....EVICT THE BAD DATA POINTS BY COMPARING THE ABSOLUTE DIFFERENCE
C      BETWEEN ADJACENT DATA POINTS
C
      IREC1 = IREC - 1
      RECI = FLOAT(IREC-1)
C
      DO 110 I = 1, IREC
      GX(I) = -1.0
110 CONTINUE
C
      DO 111 I = 1, IREC1
      DDZ(I) = ABS( Z(I+1) - Z(I) )
111 CONTINUE
C
      DO 112 J = 1, IREC1
      IF(DDZ(J).LT.SIGE) THEN
      K = J
      GO TO 222
      END IF
112 CONTINUE
C
222 CONTINUE
      DO 113 J = 1, IREC
      IF(DDZ(IREC-J).LT.SIGE) THEN
      IRECG = IREC-J
      GO TO 223
      END IF
113 CONTINUE
C

```

```

223 KB = 0
    DO 224 I = 1, IRECG-1
        IF (ABS(DDZ(I)).GT.SIGE) KB = KB + 1
224 CONTINUE
C
    LG = 1
    GX(LG) = X(K)
    GY(LG) = Y(K)
    GZ(LG) = Z(K)
    GE(LG) = E(K)
C
888 LG = LG + 1
    K = K + 1
    IF (ABS(DDZ(K-1)).GT.SIGE) THEN
        K = K + 1
        DO 225 I = 1, KB-1
            IF (ABS(DDZ(K-1)).GT.SIGE) K = K + 1
225 CONTINUE
        END IF
        GX(LG) = X(K)
        GY(LG) = Y(K)
        GZ(LG) = Z(K)
        GE(LG) = E(K)
        IF (K.LE.IRECG) GO TO 888
C
    RETURN
    END
/**
/** EXEC LINKGOV,REGION=5000K
/**EXEC LINKGOV,REGION.LINK=5000K,REGION.GO=5000K,
/** PARM='MAP,LIST,SIZE=(4096K,512K)'
/**SYSLIB DD DSN=SYS2.IMSL5,DISP=SHR
/** DD DSN=SYS2.IMSLD,DISP=SHR
/**
/** *****
/**
/** ADJUSTED BLACK SEA DATA
/**
/** *****
/**
/**GO.FT05F001 DD DSN=ZMAYA.BLACKA.DATA,DISP=SHR
/**GO.FT06F001 DD SYSOUT=*
/**GO.FT08F001 DD DSN=ZMAYA.BLACK4B.SORT,DISP=SHR
/** EXEC NOTIFYTS

```

A listing of PROGRAM WGTAVG

```
//ZMAYABWA JOB (G0109,360,2),AYAU,TIME=(0,30),CLASS=0,MSGCLASS=X
/*JOBPARM LINES=60
// EXEC FORTVC
//SYSIN DD *
```

```
C
C FORMAT OF GEOS-3/SEASAT ALTIMETER DATA
C
C VARIABLE      TYPE      DESCRIPTION
C
C      *         I4        SATELITE ID
C      I2        MEASUREMENT TYPE ( 42= OVER LAND , 43 = OVER WATER )
C      I2        TIME SYSTEM ( NM )
C      I4        STATION NUMBER
C      I4        PREPROCESSING INDICATORS
C      I4        MODIFIED JULIAN DATE OF OBSERVATION
C      R8        FRACTION OF DAY PAST MIDNIGHT (GMT)
C      R8        ALTIMETER OBSERVATION (METERS)
C      *         I4        SATELLITE GEODETIC LATITUDE (1E-6 DEGREES)
C      *         I4        SATELLITE EAST LONGITUDE (1E-6 DEGREES)
C      R4        MEASUREMENT STANDARD DEVIATION (METERS)
C      I4        NET INSTRUMENT CORRECTION (MM)
C      I4        METEOROLOGICAL DATA WORD (GEODYN VOL 3)
C      I4        NET MEDIA CORRECTIONS (MM)
C      R4        GEOID HEIGHT ABOVE REFERENCE ELLIPSOID (METERS)
C      I4        NET OCEAN DYNAMIC CORRECTIONS (MM)
C      *         I4        INDICATED SURFACE ELEVATION (MM)
C      *         I4        S/C REVOLUTION NUMBER
C      I4        MEAN SEA SURFACE ELEVATION (MARSH/MARTIN '81 (MM))
C      I4        DOD REFERENCE RADIAL ORBIT DIFFERENCE (MM)
C      I2        H 1/3 (CM)
C      I2        AGC (DB)
C      I2        WIND SPEED (CM/SEC)
C      I2        SURFACE ELEVATION PREPROCESSING WORD
C      I2        DRY TROPOSPHERIC CORRECTION (MM)
C      I2        FNOC WET TROPOSPHERIC CORRECTION (MM)
C      I2        SMMR WET TROPOSPHERIC CORRECTION (MM)
C      I2        IONOSPHERIC CORRECTION (MM)
C      I2        BAROTROPIC DYNAMIC SEA SURFACE CORRECTION (MM)
C      I2        SOLID EARTH TIDE (MM)
C      I2        SCHWIDERSKI OCEAN TIDE (MM)
C      I2        PARKE OCEAN TIDE (MM)
```

```
PARAMETER ( ETOP = 50. )
PARAMETER ( EBOT = 10. )
PARAMETER ( SIGE = 2. )
PARAMETER ( MIREC = 150 )
PARAMETER ( XMIN = 26.5 )
PARAMETER ( XMAX = 42.5 )
PARAMETER ( YMIN = 40.0 )
PARAMETER ( YMAX = 48.0 )
PARAMETER ( DX = 0.25 )
PARAMETER ( DY = 0.25 )
PARAMETER ( MXP = 100 )
PARAMETER ( NXI = (XMAX-XMIN)/DX + 1 )
PARAMETER ( NYI = (YMAX-YMIN)/DY + 1 )
```

```
C
INTEGER*2  I2,I3,I17,I18,I19,I20,I21,I22,I23,I24,I25,I26,I27,I28
INTEGER*4  I1,I4,I5,I6,I7,I8,I9,I10,I11,I12,I13,I14,I15,I16
REAL*8     R1,R2
REAL*4     R3,R4
REAL*4     GLAT, ELON, HSS, HSUM, HAVG, RSQ, W, WF, GMIN, GMAX
REAL*4     EX(NXI,NYI,MXP), GY(NXI,NYI,MXP), H(NXI,NYI,MXP)
REAL*4     GRIDX(NXI), GRIDY(NYI), GRID(NXI,NYI)
REAL*4     X(MIREC), Y(MIREC), Z(MIREC)
REAL*4     BX(MIREC), BY(MIREC), BZ(MIREC), DDZ(MIREC)
INTEGER    NGD(NXI,NYI)
```

```

      INTEGER      IREC, NREC, NP, NEG, LG, ND, NREV, MG
      INTEGER      INP, OUP, OUG
C
      DATA  INP / 5 /, OUP / 6 /, OUG / 8 /
      DATA  IREC / 0 /, NREC / 0 /, NEG / 0 /, ND / 0 /
      DATA  HSUM / 0.0 /, GMIN / 1000.0 /, GMAX / -1000.0 /
C
C.....FIRST GENERATE THE GRID NET
C
      GRIDX(1) = XMIN
      DO 100 I = 2, NXI
        GRIDX(I) = GRIDX(I-1) + DX
100 CONTINUE
      GRIDY(1) = YMIN
      DO 101 I = 2, NYI
        GRIDY(I) = GRIDY(I-1) + DY
101 CONTINUE
C
      READ ( INP )  I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
&                I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
&                I20,I21,I22,I23,I24,I25,I26,I27,I28
      NREV = I14
      REWIND INP
C
1000 READ ( INP, END = 2000 ) I1,I2,I3,I4,I5,I6,R1,R2,I7,I8,R3,
*                I9,I10,I11,R4,I12,I13,I14,I15,I16,I17,I18,I19,
*                I20,I21,I22,I23,I24,I25,I26,I27,I28
C*****
      IF ( I14. EQ. 12793 ) GO TO 999
C*****
      NREC = NREC + 1
      GLAT = 1.0E-6 * FLOAT(I7)
      ELON = 1.0E-6 * FLOAT(I8)
      HSS = 1.0E-3 * FLOAT(I13)
C
      IF ( I14. EQ. NREV ) THEN
        IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
          IREC = IREC + 1
          X(IREC) = ELON
          Y(IREC) = GLAT
          Z(IREC) = HSS
        END IF
      ELSE
C
C.....ASSIGN THE PREVIOUS ELEVATION DATA INTO AN ARRAY FOR GRIDDING
C
      IF ( IREC. GT. 4 ) THEN
C
      CALL SELECT( X,Y,Z,IREC, SIGE, LG,BX,BY,BZ,DDZ )
C
      DO 200 I = 1, LG
        ND = ND + 1
        LX = NINT((BX(I)-XMIN)/DX) + 1
        LY = NINT((BY(I)-YMIN)/DY) + 1
        NGD(LX,LY) = NGD(LX,LY) + 1
        EX(LX,LY,NGD(LX,LY)) = BX(I)
        GY(LX,LY,NGD(LX,LY)) = BY(I)
        H(LX,LY,NGD(LX,LY)) = BZ(I)
200 CONTINUE
C
      END IF
C
      NREV = I14
      IREC = 1
      IF ( HSS. GT. EBOT. AND. HSS. LT. ETOP ) THEN
        X(IREC) = ELON
        Y(IREC) = GLAT
        Z(IREC) = HSS
      ELSE

```

```

        IREC = IREC - 1
        END IF
        END IF
C
C 999 CONTINUE
        GO TO 1000
C
C 2000 CONTINUE
C
        IF ( IREC. GT. 4 ) THEN
C
        CALL SELECT( X,Y,Z,IREC, SIGE, LG,BX,BY,BZ,DDZ )
C
        DO 201 I = 1, LG
            ND = ND + 1
            LX = NINT((BX(I)-XMIN)/DX) + 1
            LY = NINT((BY(I)-YMIN)/DY) + 1
            NGD(LX,LY) = NGD(LX,LY) + 1
            EX(LX,LY,NGD(LX,LY)) = BX(I)
            GY(LX,LY,NGD(LX,LY)) = BY(I)
            H(LX,LY,NGD(LX,LY)) = BZ(I)
            HSUM = HSUM + BZ(I)
201        CONTINUE
C
        END IF
C
        HAVG = HSUM/FLOAT(ND)
C
        MG = -1
        DO 300 I = 1, NXI
            DO 301 J = 1, NYI
                MG = MAX0( MG, NGD(I,J) )
301        CONTINUE
300        CONTINUE
C
C.....WRITE OUT THE DATA SET ASSOCIATED WITH EACH GRID POINT
C
        DO 400 I = 1, NXI
            DO 401 J = 1, NYI
                NP = NGD(I,J)
                GRID(I,J) = -1000.0
                IF ( NP. GT. 0 ) THEN
                    IF ( NP. EQ. 1 ) THEN
                        GRID(I,J) = H(I,J,1)
                    ELSE
                        WF = 0.0
                        W = 0.0
                        DO 402 K = 1, NP
                            RSQ = (EX(I,J,K)-GRIDX(I))**2 + (GY(I,J,K)-GRIDY(J))**2
                            RSQ = 1.0/RSQ
                            WF = WF + RSQ*H(I,J,K)
                            W = W + RSQ
402                        CONTINUE
                            GRID(I,J) = WF/W
                        END IF
                        GMIN = AMIN1 ( GMIN, GRID(I,J) )
                        GMAX = AMAX1 ( GMAX, GRID(I,J) )
                        NEG = NEG + 1
                        WRITE ( OUP, 601 ) I, J, GRIDX(I), GRIDY(J), GRID(I,J), NP
                        WRITE ( OUP, 602 ) (EX(I,J,K),GY(I,J,K),H(I,J,K),K=1, NP)
                    END IF
201                CONTINUE
401            CONTINUE
400        CONTINUE
C
        DO 700 I = 1, NXI
            WRITE ( OUG, 603 ) (GRIDX(I),GRIDY(J),GRID(I,J),J=1,NYI)
700        CONTINUE
C
        WRITE ( OUP, 604 )
        DO 800 I = 1, NXI

```

```

      WRITE ( OUP, 605 ) I, (NGD(I,J),J=1,NYI)
800 CONTINUE
C
      WRITE( OUP, 606 ) NREC, ND, NEG, MG, GMIN, GMAX, HAVG
C
601 FORMAT(1H0,///,T5,'GRID (',I2,',',I2,'):',
&          3X,'ELON = ',F6.2,3X,'GLAT = ',F6.2,
&          3X,'WT. H = ',F10.4,5X,'TOTAL DATA POINTS = ',I3/)
602 FORMAT((1H,T5,2F9.4,F12.4))
603 FORMAT((3(2F7.2,F12.4)))
604 FORMAT(1H1,///,T20,'DATA DISTRIBUTION MAP:',//)
605 FORMAT(1H,T5,I4,5X,3I3)
606 FORMAT(1H1,///,T5,'# OF RECORDS READ: ',I8,///,
&          T5,'# OF RECORDS USED IN GRIDDING: ',I8,///,
&          T5,'# OF NONEMPTY GRID POINTS: ',I4,///,
&          T5,'MAXIMUM # OF DATA PTS TO A GRID PT: ',I3,///,
&          T5,'THE RANGE OF GEOID HEIGHT IS: ',2F14.4,///,
&          T5,'MEAN GEOID HEIGHT OF THE BLACK SEA: ',F10.4,///,
&          T5,'GRIDDED DATA HAVE BEEN WRITTEN TO BLACKA.GRID.')
C
      STOP
      END
C
      SUBROUTINE SELECT ( X, Y, Z, IREC, SIGE, LG, GX, GY, GZ, DDZ )
C
      REAL*4      X(IREC), Y(IREC), Z(IREC)
      REAL*4      GX(IREC), GY(IREC), GZ(IREC), DDZ(IREC)
C
C.....EVICT THE BAD DATA POINTS BY COMPARING THE ABSOLUTE DIFFERENCE
C      BETWEEN ADJACENT DATA POINTS
C
      IREC1 = IREC - 1
      RECI = FLOAT(IREC-1)
C
      DO 110 I = 1, IREC
          GX(I) = -1.0
110 CONTINUE
C
      DO 111 I = 1, IREC1
          DDZ(I) = ABS( Z(I+1) - Z(I) )
111 CONTINUE
C
      DO 112 J = 1, IREC1
          IF(DDZ(J).LT.SIGE) THEN
              K = J
              GO TO 222
          END IF
112 CONTINUE
C
222 CONTINUE
      DO 113 J = 1, IREC
          IF(DDZ(IREC-J).LT.SIGE) THEN
              IRECG = IREC-J
              GO TO 223
          END IF
113 CONTINUE
C
223 KB = 0
      DO 224 I = 1, IRECG-1
          IF(ABS(DDZ(I)).GT.SIGE) KB = KB + 1
224 CONTINUE
C
      LG = 1
      GX(LG) = X(K)
      GY(LG) = Y(K)
      GZ(LG) = Z(K)
C
888 LG = LG + 1
      K = K + 1
      IF(ABS(DDZ(K-1)).GT.SIGE) THEN
          K = K + 1

```



```

        DO 225 I = 1, KB-1
          IF (ABS(DDZ(K-1)).GT.SIGE) K = K + 1
225     CONTINUE
        END IF
        GX(LG) = X(K)
        GY(LG) = Y(K)
        GZ(LG) = Z(K)
        IF(K.LE.IRECG) GO TO 888
C
        RETURN
        END
/**
// EXEC LINKGOV,REGION=5000K
/**SYSLIB DD DSN=SYS2.IMSL5,DISP=SHR
/** DD DSN=SYS2.IMSLD,DISP=SHR
/**
/** *****
/**
/** ADJUSTED BLACK SEA DATA
/**
/** *****
/**
//GO.FT05F001 DD DSN=ZMAYA.BLACKA.DATA,DISP=SHR
//GO.FT06F001 DD SYSOUT=*
//GO.FT08F001 DD DSN=ZMAYA.BLACKA.GRID,DISP=SHR
// EXEC NOTIFYTS

```

A listing of PROGRAM CONTOUR

```

//ZMAYABGA JOB (G0109,360,10),AYAU,TIME=(1,00),CLASS=O,MSGCLASS=X
//TEMPLATE EXEC G38PLOT
//FORT.SYSIN DD *
C
    PARAMETER ( BIAS = 0.0 )
    PARAMETER ( XMIN = 26.5 )
    PARAMETER ( XMAX = 42.5 )
    PARAMETER ( YMIN = 40.0 )
    PARAMETER ( YMAX = 48.0 )
    PARAMETER ( DX = 0.25 )
    PARAMETER ( DY = 0.25 )
    PARAMETER ( CHGH = 50. )
    PARAMETER ( CLOW = 10. )
    PARAMETER ( CINC = 1. )
    PARAMETER ( CLAB = 2. )
    PARAMETER ( NLON = ( (XMAX-XMIN)/DX + 1 ) )
    PARAMETER ( NLAT = ( (YMAX-YMIN)/DY + 1 ) )
C
    INTEGER      INP, NRU, OUP
    INTEGER      NPROJ, LINEH, LINEV
    INTEGER      LIST(6)
    INTEGER      MASK(NLON,NLAT)
    REAL*4      LON(NLON), LAT(NLAT), GRID(NLON,NLAT)
    REAL*4      WKCNTN(NLON,NLAT), XP(NLON), YP(NLAT)
    REAL*4      PENS(7)
    REAL*4      PLAT, PLONG, VLAT1, VLAT2, VLONG1, VLONG2
    CHARACTER*1  DATE(10)
C
    DATA INP / 5 /, OUP / 6 /, NRU / 0 /
    DATA GMAX / -999.0 /, GMIN / 1000.0 /
    DATA PENS / 7*4.0 /
    DATA LIST / 8, 110, 75, 0, 7, 10 /
    DATA NPROJ / 16 /
    DATA PLAT / 90. /, PLONG / 0. /
C
    DO 100 I = 1, NLON
      READ ( INP, 510, END = 777 ) (LON(I),LAT(J),GRID(I,J),J=1,NLAT)
100 CONTINUE
C
    777 CONTINUE
C
    DO 111 I = 1, NLON
      DO 112 J = 1, NLAT
        IF ( GRID(I,J).NE. -1000.0 ) THEN
          NRU = NRU + 1
          GRID(I,J) = GRID(I,J) - BIAS
          GMAX = AMAX1 ( GRID(I,J), GMAX )
          GMIN = AMIN1 ( GRID(I,J), GMIN )
        END IF
112 CONTINUE
111 CONTINUE
C
    WRITE( OUP, 610 ) GMIN, GMAX, NRU
C
    WRITE(OUP,620) ((LON(IX),LAT(IY),GRID(IX,IY),IY=1,NLAT),IX=1,NLON)
C
C.....START GRAPHIC PROCEDURES
C
    CALL USTART
    CALL UINQES(1.0,SUPRT)
    IF (SUPRT.NE.0.0) CALL UESCAP(1.0,LIST,6.0,IDUM,DUM)
    CALL USET('PERCENTUNITS')
    CALL UVWPRT(0.0,99.0,0.0,99.0)
    CALL UOUTLN
C
C.....PUT ON LABELS
C

```

```

CALL USET('CJUST')
CALL USET('TJUST')
CALL USET('YELLOW')
CALL USET('SOFTWARE')
CALL USET('EXTRALARGE')
CALL UPSET('VERTICAL SIZE',2.0)
CALL UPSET('HORIZONTAL SIZE',1.6)
CALL UFONT('TROM')
CALL UPRINT(50.,96.,
& 'WT. AVG. GEOIDAL HEIGHT OF THE BLACK SEAS')
C
VLAT1 = YMIN
VLAT2 = YMAX
VLONG1 = XMIN
VLONG2 = XMAX
LINEH = IFIX(YMAX-YMIN)
LINEV = IFIX(XMAX-XMIN)
CALL WDMAP(NPROJ,PLAT,PLONG,VLAT1,VLAT2,VLONG1,VLONG2,
& LINEH,LINEV)
C
C.....LABEL AXIS AND WRITE LON AND LATS ON PLOT
C
DLONG = ABS(VLONG2 - VLONG1) / LINEV
LINES = LINEV + 1
DIX = 100.0 / LINEV
YLONGI = -3.5
DO 420 I = 1, LINES, 2
  V = VLONG1 + (DLONG * (I - 1))
  XLATIT = DIX * (I - 1)
  CALL UMOVE(XLATIT,YLONGI)
  CALL UPRNT1(V,'REAL')
420 CONTINUE
C
C.....WRITE LABEL
C
CALL USET('BJUS')
CALL UMOVE(50.,-7.5)
CALL UPRNT1('LONGITUDES','HORIZ')
C
DLAT = ABS(VLAT2 - VLAT1) / LINEH
LINES = LINEH + 1
DIY = 100.0 / LINEH
XLT = -3.5
DO 430 I = 1, LINES, 2
  V = VLAT1 + (DLAT * (I - 1))
  YLO = DIY * (I - 1)
  CALL UMOVE(XLT,YLO)
  CALL UPRNT1(V,'REAL')
430 CONTINUE
C
C.....WRITE LABEL
C
CALL USET('MJUS')
CALL UMOVE(-7.5,50.0)
CALL UPRNT1('LATITUDES','VERTI')
C
C.....WRITE DATE AND ID ON PLOT
C
CALL ZTIME(8)
CALL FMOVE(10,1,'$')
CALL UPRINT(78.,-8.,DATE)
CALL UPRINT(95.,-8.,'STX/ZMAYAS')
C
C.....START CONTOURING PROCEDURES
C
CALL USET('NOMI')
CALL USET('SMOOTH')
CALL UPSET('CLOWEST',CLOW)
CALL UPSET('CINCREMENT',CINC)
CALL UPSET('CHIGHEST',CHGH)

```


A listing of PROGRAM GEOID

```
//ZMAYABSH JOB (G0109,360,2),AYAU,TIME=(2,30),CLASS=O,MSGCLASS=X
// EXEC FORTVC
//SYSIN DD *
```

C

```
PARAMETER ( MPASS = 142 )
PARAMETER ( NREFF = 73 )
PARAMETER ( KUTOFF = 3 )
PARAMETER ( LCTV = 1 )
PARAMETER ( MTR = 160 )
PARAMETER ( XMIN = 26.5 )
PARAMETER ( XMAX = 42.5 )
PARAMETER ( YMIN = 40.0 )
PARAMETER ( YMAX = 48.0 )
PARAMETER ( DX = 0.25 )
PARAMETER ( DY = 0.25 )
PARAMETER ( LCT = 33 )
PARAMETER ( NXI = (XMAX-XMIN)/DX + 1 )
PARAMETER ( NYI = (YMAX-YMIN)/DY + 1 )
PARAMETER ( LEN = (MTR*(MTR+1))/2 )
PARAMETER ( MSYM = (MPASS*(MPASS-1))/2 )
```

C

```
REAL*4 SE(MTR)
REAL*4 GRIDX(NXI), GRIDY(NYI)
REAL*4 GRID(NXI,NYI), VARM(NXI,NYI)
REAL*8 RGRIDX(NXI), RGRIDY(NYI)
REAL*8 SY(MTR), CY(MTR)
REAL*8 EX(MTR), GY(MTR), GH(MTR), SGY(MTR), CGY(MTR)
REAL*8 CM(LEN), CMI(LEN), CMS(LEN), DM(LEN), DLL(LEN)
REAL*8 CP(MTR), SRC(MTR), AP(MTR)
REAL*8 SD(LCT), CTV(LCT,3), CV(LCT), SC(LCT-1,3)
REAL*8 DTR, ELON, GLAT, X1, Y1, SY1, CY1, PVAL, VAR
INTEGER IDIAG(MTR), NPASS(MTR)
INTEGER INP, OUP, OUG, OUH, OUC, OUE
```

C

```
DATA INP / 5 /, OUP / 6 /, OUG / 8 /, OUH / 9 /
DATA OUC / 10 /, OUE / 11 /
DATA NIER / 0 /
DATA DTR / 3.490658504D-2 /
DATA GMIN / 1000.0 /, GMAX / -999.0 /
DATA VMIN / 1000.0 /, VMAX / -999.0 /
```

C

C

C.....GENERATE A GRID NET

C

```
GRIDX(1) = XMIN
DO 100 I = 2, NXI
  GRIDX(I) = GRIDX(I-1) + DX
  RGRIDX(I) = DBLE(GRIDX(I)) * DTR
100 CONTINUE
GRIDY(1) = YMIN
DO 101 I = 2, NYI
  GRIDY(I) = GRIDY(I-1) + DY
  RGRIDY(I) = DBLE(GRIDY(I)) * DTR
  SY(I) = DSIN(RGRIDY(I))
  CY(I) = DCOS(RGRIDY(I))
101 CONTINUE
DO 102 I = 1, NXI
  DO 103 J = 1, NYI
    GRID(I,J) = -1000.0
    VARM(I,J) = -1000.0
103 CONTINUE
102 CONTINUE
```

C

C.....READ IN THE COVARIANCE TABLE

C

```
DO 110 I = 1, LCT
  READ ( INP, 501 ) SD(I), (CTV(I,J),J=1,3)
```



```

        GRID(IKEEP,JKEEP) = PVAL
        VARM(IKEEP,JKEEP) = VAR
    ELSE
        JC = JC - 1
        WRITE ( OUP, * ) 'IER =',IER,'          PVAL =',PVAL,
*                               VAR =',VAR
    END IF
    WRITE ( OUP, 603 ) IKEEP,JKEEP,GRIDX(IKEEP),GRIDY(JKEEP),
*   GRID(IKEEP,JKEEP), VARM(IKEEP,JKEEP), IREC,JC
    END IF
C
    IKEEP = I1
    JKEEP = I2
    IREC = 1
    EX(IREC) = ELON
    GY(IREC) = GLAT
    GH(IREC) = DBLE(HSS)
    NPASS(IREC) = I3
    SE(IREC) = R4
    IF ( NPASS(IREC). EQ. NREFP ) NPASS(IREC) = 0
    IF ( NPASS(IREC). GT. NREFP ) NPASS(IREC) = NPASS(IREC) - 1
C
    END IF
C
    GO TO 1000
C
    2000 CONTINUE
C
    IF ( IREC. GT. KUTOFF ) THEN
        X1 = RGRIDX(I1)
        Y1 = RGRIDY(I2)
        SY1 = SY(JKEEP)
        CY1 = CY(JKEEP)
        JREC = (IREC*(IREC+1))/2
        JC = JC + 1
        CALL PREDIC ( PVAL,VAR, EX,GY,GH,SGY,CGY,IREC,
*   NPASS, SE, DM, DLL, X1,Y1,SY1,CY1,
*   CM,CMS,CMI,JREC, IDIAG,CP, SRC,AP,
*   SD,CTV,CV,SC,LCT,ISC,
*   LCTV,DTR, IER, NIER )
        IF ( IER. EQ. 0 ) THEN
            GRID(I1,I2) = PVAL
            VARM(I1,I2) = VAR
        ELSE
            JC = JC - 1
            WRITE ( OUP, * ) 'IER =',IER,'          PVAL =',PVAL,
*                               VAR =',VAR
        END IF
        WRITE ( OUP, 603 ) I1,I2,GRIDX(I1),GRIDY(I2),
*   GRID(I1,I2), VARM(I1,I2), IREC,JC
    END IF
C
C.....DETERMINE THE RANGE OF THE PREDICTED VALUES AND THEIR VARIANCE
C
    DO 300 I = 1, NXI
        DO 301 J = 1, NYI
            IF ( GRID(I,J). NE. -1000.0 ) THEN
                GMIN = AMIN1 ( GMIN, GRID(I,J) )
                GMAX = AMAX1 ( GMAX, GRID(I,J) )
            END IF
            IF ( VARM(I,J). NE. -1000.0 ) THEN
                VMIN = AMIN1 ( VMIN, VARM(I,J) )
                VMAX = AMAX1 ( VMAX, VARM(I,J) )
            END IF
        301 CONTINUE
    300 CONTINUE
C
C.....PRINT OUT THE GRIDDED VALUES AND THE VARIANCE
C
    NXY = NXI*NYI

```

```

WRITE ( OUP, 604 ) NIER, JC, NXY, GMIN, GMAX
DO 400 I = 1, NXI
  WRITE ( OUP, 605 ) ( GRIDX(I), GRIDY(J), GRID(I,J), J=1, NYI)
  WRITE ( OUH, 606 ) ( GRIDX(I), GRIDY(J), GRID(I,J), J=1, NYI)
400 CONTINUE
C
  WRITE ( OUP, 607 ) VMIN, VMAX
  DO 410 I = 1, NXI
    WRITE ( OUP, 605 ) ( GRIDX(I), GRIDY(J), VARM(I,J), J=1, NYI)
    WRITE ( OUC, 606 ) ( GRIDX(I), GRIDY(J), VARM(I,J), J=1, NYI)
410 CONTINUE
C
501 FORMAT(1X,D10.4,3D20.13)
502 FORMAT((4D20.13))
600 FORMAT(1H1)
601 FORMAT(1H1,T5,'VALUES OF THE COVARIANCE TABLE USED:',//)
602 FORMAT((1H,5X,D10.4,5X,D20.13))
603 FORMAT(1H,T2,'GRID(',I2,',',I2,')',3X,'ELON = ',F6.2,2X,
*         ',GLAT = ',F6.2,5X,'GEOID HEIGHT = ',F10.4,' +- ',F8.2,5X,
*         'RECORD #: ',I5,5X,'COUNTER: ',I5,/)
604 FORMAT(1H1,T5,I4,' GRID POINTS HAVING NEGATIVE VARIANCE',//,
*         T5,'THERE ARE ',I4,' POINTS GRIDDED OUT OF A NET ',
*         'OF ',I5,' GRID POINTS.',//,T8,'THE RANGE OF THE',
*         ' GEODIAL HEIGHT IN METERS IS:',2F12.4,/)
605 FORMAT((1H,5(2F7.2,F12.4)))
606 FORMAT((3(2F7.2,F12.4)))
607 FORMAT(1H1,T5,'THE RANGE OF THE VARIANCE IN CM IS:',2F12.4,/)
C
STOP
END
SUBROUTINE PREDIC ( PVAL,VAR, EX,GY,GH, SGY,CGY, IREC,
*                 NPASS, SE, DM, DLL, X1,Y1,SY1,CY1,
*                 CM,CMS,CMI,JREC, IDIAG,CP, SRC,AP,
*                 SD,CTV,CV,SC,LCT,ISC,
*                 LCTV,DTR, IER, NIER )
C
REAL*4          SE(IREC)
REAL*8          EX(IREC), GY(IREC), GH(IREC), SGY(IREC), CGY(IREC)
REAL*8          CP(IREC), SRC(IREC), AP(IREC)
REAL*8          CM(JREC), CMI(JREC), CMS(JREC), DM(JREC), DLL(JREC)
REAL*8          SD(LCT), CTV(LCT,3), CV(LCT), SC(LCT-1,3)
REAL*8          D1, D2, CSD, DSD, VDSD, AVG, DTR
REAL*8          X1, Y1, SY1, CY1, PVAL, VAR
INTEGER         IDIAG(IREC), NPASS(IREC)
C
C.....RESET THE ERROR COUNTER
C
IER = 0
C
C.....CLEAR THE COVARIANCE MATRIX ARRAY
C
CALL DCLR( CM, JREC )
CALL DCLR( CMI, JREC )
CALL DCLR( CMS, JREC )
CALL DCLR( DLL, JREC )
C
C.....DETERMINE THE AVERAGE VALUE OF THE DATA SET
C
AVG = 0.0
DO 100 I = 1, IREC
  AVG = AVG + GH(I)
100 CONTINUE
AVG = AVG / DFLOAT(IREC)
C
C.....CONSTRUCT THE DIAGONAL TERMS OF THE SIGNAL COVARIANCE MATRIX,
C REMOVE THE AVERAGE VALUE FROM DATA SET TO MAKE IT ZERO MEAN
C AND SET UP THE DATA VECTOR IN DOUBLE PRECISION
C
DO 110 I = 1, IREC
  CM(IDIAG(I)) = CTV(1,LCTV) + DBLE(SE(I)*SE(I))

```



```

      GH(I) = GH(I) - AVG
110 CONTINUE
C
C.....EVALUATE ALL THE SINE AND COSINE TERMS
C
      DO 200 I = 1, IREC
          SGY(I) = DSIN(GY(I))
          CGY(I) = DCOS(GY(I))
200 CONTINUE
C
C.....CONSTRUCT THE OFF-DIAGONAL TERMS OF THE SIGNAL COVARIANCE MATRIX
C
      DO 300 J = 2, IREC
          DO 301 I = 1, J-1
C
              CSD = SGY(I)*SGY(J) + CGY(I)*CGY(J)*DCOS(EX(I)-EX(J))
              DSD = DACOS(CSD)/DTR
              CALL ICSEVU ( SD, CV, LCT, SC, ISC, DSD, VDSD, 1, IER )
              K = (J*(J-1))/2 + I
              CM(K) = VDSD
C
          301 CONTINUE
      300 CONTINUE
C
C.....ASSEMBLE THE ERROR COVARIANCE MATRIX FROM BIAS ADJUSTMENT
C
      DO 310 J = 1, IREC
          DO 311 I = 1, J
C
              K = (J*(J-1))/2 + I
              IF ( NPASS(I). NE. 0. AND. NPASS(J). NE. 0 ) THEN
                  M1 = MIN0 ( NPASS(I), NPASS(J) )
                  M2 = MAX0 ( NPASS(I), NPASS(J) )
                  L = (M2*(M2-1))/2 + M1
                  DLL(K) = DM(L)
              ELSE
                  DLL(K) = 0.0D0
              END IF
C
          311 CONTINUE
      310 CONTINUE
C
C.....ASSEMBLE THE COMPLETE COVARIANCE MATRIX AND
C..... DUPLICATE THE COVARIANCE MATRIX FOR STORAGE
C
      DO 320 I = 1, JREC
          CM(I) = CM(I) + DLL(I)
          CMS(I) = CM(I)
320 CONTINUE
C
C.....INVERT THE COVARIANCE MATRIX
C
      CALL LINVIP ( CMS,IREC,CMI, IDGT, D1,D2, IER )
      CALL SOLVE ( CMS, SRC, IDIAG, IREC, .TRUE., .FALSE. )
      CALL SYMINV ( CMS, SRC, IDIAG, IREC, CMI )
C
      IF ( IER. EQ. 0 ) THEN
C
C.....CONSTRUCT THE COVARIANCE VECTOR
C
          DO 330 I = 1, IREC
C
              CSD = SY1*SGY(I) + CY1*CGY(I)*DCOS(X1-EX(I))
              DSD = DACOS(CSD)/DTR
              CALL ICSEVU ( SD, CV, LCT, SC, ISC, DSD, VDSD, 1, IER )
              CP(I) = VDSD
C
          330 CONTINUE
C
C.....DETERMINE THE PREDICTED VALUE AT A GRID POINT

```

```

C
C      CALL VMULSF ( CMI,IREC, GH,1,IREC, SRC,IREC )
C      CALL DCLR ( SRC, IREC )
C      CALL VSMXVT ( CMI, GH, SRC, IDIAG, IREC )
C      PVAL = DOT ( CP, SRC, IREC ) + AVG
C
C.....DETERMINE THE VARIANCE OF THE PREDICTED VALUE
C
C      CALL VMULSF ( CMI,IREC, CP,1,IREC, AP,IREC )
C      CALL VMULSF ( CM,IREC, AP,1,IREC, SRC,IREC )
C      CALL DCLR ( AP, IREC )
C      CALL DCLR ( SRC, IREC )
C      CALL VSMXVT ( CMI, CP, AP, IDIAG, IREC )
C      CALL VSMXVT ( CM, AP, SRC, IDIAG, IREC )
C      VAR = CTV(1,LCTV) - 2.0D0*DOT(AP,CP,IREC) + DOT(AP,SRC,IREC)
C
C      IF ( VAR. GT. 0.0 ) THEN
C          VAR = 100.0D0*DSQRT(VAR)
C      ELSE
C          IER = 1
C          NIER = NIER + 1
C      END IF
C
C      END IF
C
C      RETURN
C      END
C      FUNCTION DOT ( A,B,N)
C      Compute the dot product of the two N-vectors A and B.
C
C      INTEGER N, I
C      REAL*4 DOT
C      REAL*8 A(1),B(1)
C
C      DOT=0.0
C
C      DO 100 I=1,N
100 DOT=DOT + A(I)*B(I)
C
C      RETURN
C      END
C      SUBROUTINE SYMINV ( A, B, IDIAG, NEQ, AINV )
C
C      IMPLICIT REAL*8 (A-H,O-Z)
C      DIMENSION A(1), B(1), AINV(1), IDIAG(1)
C
C      K = 0
C      DO 100 I = 1, NEQ
C          DO 101 L = 1, NEQ
C              B(L) = 0.0D0
101 CONTINUE
C          B(I) = 1.0D0
C          CALL SOLVE ( A, B, IDIAG, NEQ, .FALSE., .TRUE. )
C          DO 110 J = 1, I
C              K = K + 1
C              AINV(K) = B(J)
110 CONTINUE
100 CONTINUE
C
C      RETURN
C      END
C      SUBROUTINE SOLVE ( A,B, IDIAG,NEQ, FACT,BACK)
C
C      Compute the U**T * D * U factorization of the symmetric matrix
C      stored in A, if FACT = TRUE; and solve A * X = B if BACK = TRUE.
C
C
C      A
C      contains the compacted-column form of the upper triangular
C      part of the coefficient matrix. After factorization, it

```

```

C          contains D and U.
C B          Right-hand-side vector. After backsubstitution, it
C           contains the solution.
C
C IDIAG      Addresses of the diagonal terms in A.
C NEQ       Number of equations
C
C FACT      If FACT = TRUE, then factor A; otherwise do not factor A.
C BACK      If BACK = TRUE, reduce B and backsubstitute; otherwise
C           do not solve the equations.
C
C
C           IMPLICIT REAL*8 (A-H,O-Z)
C           LOGICAL FACT,BACK
C           DIMENSION A(1),B(1),IDIAG(1)
C
C Factor A, reduce B
C   JR = 0
C   DO 400 J = 1, NEQ
C     JD = IDIAG(J)
C     JH = JD - JR
C     IS = J - JH + 2
C
C     IF (JH .LT. 2) GOTO 390
C
C     IF (FACT) THEN
C       IF (JH .GT. 2) THEN
C..      Reduce column J rows IS to J-1: do not divide by row diagonal
C         K = JR + 2
C         ID = IDIAG(IS - 1)
C
C         DO 100 I = IS, J-1
C           IR = ID
C           ID = IDIAG(I)
C           IH = MIN (ID-IR-1, I-IS+1)
C           IF (IH.GT.0) A(K) = A(K) - DOT(A(K-IH),A(ID-IH),IH)
C           K = K + 1
C 100      CONTINUE
C         ENDIF
C
C..      Divide by row diagonal, and reduce diagonal term in column J
C
C         IR = JR + 1
C         K = J - JD
C         DO 200 I = IR, JD-1
C           ID = IDIAG(K+I)
C           IF (A(ID).EQ.0.0) GOTO 200
C           D = -A(I)
C           A(I) = A(I)/A(ID)
C           A(JD) = A(JD) + D*A(I)
C 200      CONTINUE
C
C         ENDIF
C
C..      Reduce RHS
C         IF (BACK) B(J) = B(J) - DOT(A(JR+1),B(IS-1),JH-1)
C
C 390     JR = JD
C 400     CONTINUE
C
C
C           IF (.NOT.BACK) RETURN
C
C Divide by diagonal pivots
C DO 700 I = 1,NEQ

```



```
//SYSLIB DD DSN=SYS2.IMSLD,DISP=SHR
//* DD DSN=SYS2.IMSLS,DISP=SHR
//*
//GO.FT05F001 DD DSN=ZMAYA.ALTIM.DATA(BE180),DISP=SHR
//*
//* *****
//* BLACK SEA DATA AFTER SORT
//* *****
//*
//GO.FT06F001 DD SYSOUT=*
//GO.FT08F001 DD DSN=ZMAYA.BLACK4.SORT,DISP=SHR
//GO.FT09F001 DD DSN=ZMAYA.BLACKC4H.GRID,DISP=SHR
//GO.FT10F001 DD DSN=ZMAYA.BLACKC4H.COVN,DISP=SHR
//GO.FT11F001 DD DSN=ZMAYA.BLACK.PCOV,DISP=SHR
// EXEC NOTIFYTS
```

A listing of PROGRAM EMPCOV

```

//ZMAYAB36 JOB (G0109,360,2),AYAU,TIME=(00,30),CLASS=F,MSGCLASS=X
// EXEC FORTVC
//SYSIN DD *
C
C
PARAMETER ( XMIN = 26.5 )
PARAMETER ( XMAX = 42.5 )
PARAMETER ( YMIN = 40.0 )
PARAMETER ( YMAX = 48.0 )
PARAMETER ( DXY = 0.25 )
PARAMETER ( M = (XMAX-XMIN)/DXY + 1 )
PARAMETER ( N = (YMAX-YMIN)/DXY + 1 )
PARAMETER ( MN = N )
C
IMPLICIT REAL*8 (A-Z)
DIMENSION G(M,N), DG(M,N), H(M,N), DH(M,N)
DIMENSION D(0:MN)
DIMENSION CHH(0:MN), CHHNS(0:MN), CHHEW(0:MN)
DIMENSION CHG(0:MN), CHGNS(0:MN), CHGEW(0:MN)
DIMENSION CGG(0:MN), CGGNS(0:MN), CGGEW(0:MN)
INTEGER INP, OUP, IMH, INH, IMG, ING, OUF
C
DATA INP / 5 /, OUP / 6 /, IMH / 7 /, INH / 8 /,
* IMG / 9 /, ING / 10 /, OUF / 11 /
C
C
C.....READ IN THE MODEL GEOIDAL HEIGHT AND GRAVITY ANOMALY
C
DO 100 J = N, 1, -1
  READ ( IMH, * ) RL
  READ ( IMH, 501 ) (H(I,J),I=1,M)
100 CONTINUE
C
DO 101 J = N, 1, -1
  READ ( IMG, * ) RL
  READ ( IMG, 501 ) (G(I,J),I=1,M)
101 CONTINUE
C
C.....READ IN THE GEOIDAL HEIGHT AND GRAVITY ANOMALY DATA
C
DO 110 I = 1, M
  READ ( INH, 502 ) (DH(I,J),J=1,N)
110 CONTINUE
C
DO 111 I = 1, M
  READ ( ING, 502 ) (DG(I,J),J=1,N)
111 CONTINUE
C
C.....REMOVE THE MODEL VALUE FROM THE DATA
C
DO 120 I = 1, M
  DO 121 J = 1, N
    IF ( DH(I,J) .NE. -1000.0 ) DH(I,J) = DH(I,J) - H(I,J)
    IF ( DG(I,J) .NE. -1000.0 ) DG(I,J) = DG(I,J) - G(I,J)
121 CONTINUE
120 CONTINUE
C
C.....PERFORM THE CONVOLUTION
C
DO 200 K = 0, MN-1
C
SHH = 0.
SHG = 0.
SGG = 0.
CHHNS(K) = 0.
CHGNS(K) = 0.
CGGNS(K) = 0.

```

```

DO 210 J = 1, N
  DO 211 I = K+1, M
    IF ( DH(I-K,J).NE.-1000.0 .AND. DH(I,J).NE.-1000.0 ) THEN
      SHH = SHH + DH(I-K,J)*DH(I,J)
    END IF
    IF ( DH(I-K,J).NE.-1000.0 .AND. DG(I,J).NE.-1000.0 ) THEN
      SHG = SHG + DH(I-K,J)*DG(I,J)
    END IF
    IF ( DG(I-K,J).NE.-1000.0 .AND. DG(I,J).NE.-1000.0 ) THEN
      SGG = SGG + DG(I-K,J)*DG(I,J)
    END IF
  211 CONTINUE
210 CONTINUE
C1 = ((M-K)*N)
CHHNS(K) = SHH / C1
CHGNS(K) = SHG / C1
CGGNS(K) = SGG / C1
C
SHH = 0.
SHG = 0.
SGG = 0.
CHHEW(K) = 0.
CHGEW(K) = 0.
CGGEW(K) = 0.
DO 220 I = 1, M
  DO 221 J = K+1, N
    IF ( DH(I,J-K).NE.-1000.0 .AND. DH(I,J).NE.-1000.0 ) THEN
      SHH = SHH + DH(I,J-K)*DH(I,J)
    END IF
    IF ( DH(I,J-K).NE.-1000.0 .AND. DG(I,J).NE.-1000.0 ) THEN
      SHG = SHG + DH(I,J-K)*DG(I,J)
    END IF
    IF ( DG(I,J-K).NE.-1000.0 .AND. DG(I,J).NE.-1000.0 ) THEN
      SGG = SGG + DG(I,J-K)*DG(I,J)
    END IF
  221 CONTINUE
220 CONTINUE
C2 = (M*(N-K))
CHHEW(K) = SHH / C2
CHGEW(K) = SHG / C2
CGGEW(K) = SGG / C2
C
D(K) = K * DXY
CHH(K) = ( C1*CHHNS(K) + C2*CHHEW(K) ) / ( C1 + C2 )
CHG(K) = ( C1*CHGNS(K) + C2*CHGEW(K) ) / ( C1 + C2 )
CGG(K) = ( C1*CGGNS(K) + C2*CGGEW(K) ) / ( C1 + C2 )
C
200 CONTINUE
C
WRITE ( OUP, 601 )
WRITE ( OUP, 602 ) ( D(I), CHH(I), CHG(I), CGG(I), I = 0, MN-1 )
WRITE ( OUP, 603 ) ( D(I), CHH(I), CHG(I), CGG(I), I = 0, MN-1 )
C
C
501 FORMAT((6(2X,F10.3)))
502 FORMAT((3(14X,F12.4)))
601 FORMAT(1H1,///,T5,'SPHERICAL DISTANCE',T30,'C(NN) IN M**2',
*          T48,'C(NG) IN M*MGAL',T67,'C(GG) IN MGAL**2',/
*          T5,'-----',T30,'-----',/
*          T48,'-----',T67,'-----',/ )
602 FORMAT((1H ,T15,F5.2,T30,F12.4,T50,F12.4,T70,F12.4))
603 FORMAT((1X,D10.4,3D20.13))
C
STOP
END
/**
// EXEC LINKGOV,REGION=5000K
/**
//GO.FT06F001 DD SYSOUT=*
//GO.FT07F001 DD DSN=ZMAYA.ALTIM.DATA(BRH36),DISP=SHR

```

```
//GO.FT08F001 DD DSN=ZMAYA.ALTIM.DATA(RDH300),DISP=SHR
//GO.FT09F001 DD DSN=ZMAYA.ALTIM.DATA(BRG36),DISP=SHR
//GO.FT10F001 DD DSN=ZMAYA.ALTIM.DATA(RDG300),DISP=SHR
//GO.FT11F001 DD DSN=ZMAYA.ALTIM.DATA(BEI036),DISP=SHR
//*
// EXEC NOTIFYTS
```


A listing of PROGRAM GRAVEN

```
//ZMAYABOR JOB (G0109,360,2),AYAU,TIME=(04,00),CLASS=O,MSGCLASS=X
/*JOBPARM LINES=60
// EXEC FORTVC
//SYSIN DD *
C
```

```
PARAMETER ( MODEL = 180 )
PARAMETER ( ANOISE = 0.25 )
PARAMETER ( ITM = 0 )
PARAMETER ( CAP = 1.00 )
PARAMETER ( IPRT = 0 )
PARAMETER ( CNVRGE = 1.0E-4 )
PARAMETER ( SCX = 1.00 )
PARAMETER ( KUTOFF = 3 )
PARAMETER ( MTR = 600 )
PARAMETER ( XMIN = 26.5 )
PARAMETER ( XMAX = 42.5 )
PARAMETER ( YMIN = 40.0 )
PARAMETER ( YMAX = 48.0 )
PARAMETER ( XG1 = 26.5 )
PARAMETER ( XG2 = 42.5 )
PARAMETER ( YG1 = 40.0 )
PARAMETER ( YG2 = 48.0 )
PARAMETER ( DX = 0.25 )
PARAMETER ( DY = 0.25 )
PARAMETER ( NXI = (XG2-XG1)/DX + 1 )
PARAMETER ( NYI = (YG2-YG1)/DY + 1 )
PARAMETER ( M1 = (XMIN-XG1)/DX + 1 )
PARAMETER ( M2 = (XMAX-XG1)/DX + 1 )
PARAMETER ( N1 = (YMIN-YG1)/DY + 1 )
PARAMETER ( N2 = (YMAX-YG1)/DY + 1 )
PARAMETER ( LCT = NYI )
PARAMETER ( INC = 4. * CAP + 1 )
PARAMETER ( CAP2 = CAP*CAP )
PARAMETER ( LEN = (MTR*(MTR+1))/2 )
PARAMETER ( LCTF = (2*LCT-1) )
PARAMETER ( NFFT = (6*LCTF/2)+150 )
```

C

```
REAL*4 GRIDX(NXI), GRIDY(NYI)
REAL*4 GUI(NXI,NYI), HVARI(NXI,NYI)
REAL*4 GU(NXI,NYI), HVAR(NXI,NYI)
REAL*4 GA(NXI,NYI), GVAR(NXI,NYI)
REAL*4 DIFF(NXI,NYI)
REAL*4 GRA300(NXI,NYI), GUN300(NXI,NYI)
REAL*4 GRA180(NXI,NYI), GUN180(NXI,NYI)
REAL*4 GRA036(NXI,NYI), GUN036(NXI,NYI)
REAL*4 GRAN(NXI,NYI), GUND(NXI,NYI)
REAL*4 WKCG(NXI,NYI), WKCH(NXI,NYI)
REAL*4 CHHNS(0:NYI-1), CHHEW(0:NYI-1)
REAL*4 CHGNS(0:NYI-1), CHGEW(0:NYI-1)
REAL*4 CGGNS(0:NYI-1), CGGEW(0:NYI-1)
REAL*8 RGRIDX(NXI), RGRIDY(NYI)
REAL*8 RMSH(0:ITM), RMSG(0:ITM)
REAL*8 RMSH1(0:ITM), RMSG1(0:ITM)
REAL*8 RMSH2(0:ITM), RMSG2(0:ITM)
REAL*8 RMSH3(0:ITM), RMSG3(0:ITM)
REAL*8 SY(MTR), CY(MTR), SE(MTR)
REAL*8 EX(MTR), GY(MTR), GH(MTR), SGY(MTR), CGY(MTR)
REAL*8 CM(LEN), CMI(LEN), CMS(LEN)
REAL*8 CP(MTR), SRC(MTR), AP(MTR)
REAL*8 SD(LCT), CTV(LCT,3)
REAL*8 CVUU(LCT), SCUU(LCT-1,3)
REAL*8 CVUG(LCT), SCUG(LCT-1,3)
REAL*8 CVGG(LCT), SCGG(LCT-1,3)
REAL*8 WKF(NFFT), A(LCTF)
REAL*8 PCVUU(LCTF), PCVUG(LCTF), PCVGG(LCTF)
REAL*8 DTR, ELON, GLAT, X1, Y1, SY1, CY1, PVAL, VAR
COMPLEX*16 X(LCTF)
```

```

      INTEGER      IDIAG(MTR), MASK(NXI,NYI), IWKF(NFFT)
      INTEGER      INP, OUP, INH, INV, INU1, ING1, INU2, ING2, INM
      INTEGER      OUG, OVG, OUH, OVH, OUD, OUB
C
      DATA      INP / 5 //, OUP / 6 //, INH / 8 //, INV / 9 /
      DATA      INU1 / 10 //, ING1 / 11 //, INU2 / 12 //, ING2 / 13 /
      DATA      INU3 / 14 //, ING3 / 15 /
      DATA      INM / 16 /
      DATA      OUG / 17 //, OVG / 18 //, OUH / 19 //, OVH / 20 //, OUD / 21 /
      DATA      OUB / 22 /
      DATA      NIER / 0 /
      DATA      DTR / 3.490658504D-2 /
      DATA      GMING / 1000.0 //, GMAXG / -999.0 /
      DATA      VMING / 1000.0 //, VMAXG / -999.0 /
      DATA      GMINH / 1000.0 //, GMAXH / -999.0 /
      DATA      VMINH / 1000.0 //, VMAXH / -999.0 /
C
C.....READ IN THE BLACK SEA MASK
C
      READ ( INM, 505 ) ((MASK(I,J),I=M1,M2),J=N2,N1,-1)
      WRITE ( OUP, 612 )
      WRITE ( OUP, 505 ) ((MASK(I,J),I=M1,M2),J=N2,N1,-1)
C
C.....GENERATE A GRID NET OF SINE AND COSINE
C
      GRIDX(1) = XG1
      RGRIDX(1) = DBLE ( GRIDX(1) ) * DTR
      DO 100 I = 2, NXI
         GRIDX(I) = GRIDX(I-1) + DX
         RGRIDX(I) = DBLE ( GRIDX(I) ) * DTR
100 CONTINUE
      GRIDY(1) = YG1
      RGRIDY(1) = DBLE ( GRIDY(1) ) * DTR
      SY(1) = DSIN(RGRIDY(1))
      CY(1) = DCOS(RGRIDY(1))
      DO 101 I = 2, NYI
         GRIDY(I) = GRIDY(I-1) + DY
         RGRIDY(I) = DBLE ( GRIDY(I) ) * DTR
         SY(I) = DSIN(RGRIDY(I))
         CY(I) = DCOS(RGRIDY(I))
101 CONTINUE
C
C.....READ IN THE MODEL GEOIDAL HEIGHT AND GRAVITY ANOMALY
C..... THE OSU 180X180, 36X36 AND 300X300 MODELS
C
      DO 102 J = NYI, 1, -1
         READ ( INU1, * ) RL
         READ ( INU1, 503 ) (GUN180(I,J),I=1,NXI)
102 CONTINUE
C
      DO 103 J = NYI, 1, -1
         READ ( ING1, * ) RL
         READ ( ING1, 503 ) (GRA180(I,J),I=1,NXI)
103 CONTINUE
C
      DO 104 J = NYI, 1, -1
         READ ( INU2, * ) RL
         READ ( INU2, 503 ) (GUN036(I,J),I=1,NXI)
104 CONTINUE
C
      DO 105 J = NYI, 1, -1
         READ ( ING2, * ) RL
         READ ( ING2, 503 ) (GRA036(I,J),I=1,NXI)
105 CONTINUE
C
      DO 106 J = NYI, 1, -1
         READ ( INU3, * ) RL
         READ ( INU3, 503 ) (GUN300(I,J),I=1,NXI)
106 CONTINUE
C

```

```

        DO 107 J = NYI, 1, -1
          READ ( ING3, * ) RL
          READ ( ING3, 503 ) (GRA300(I,J),I=1,NXI)
107 CONTINUE
C
C.....READ IN THE GRIDDED GEOID UNDULATION DATA AND VARIANCES
C
        DO 108 I = M1, M2
          READ ( INH, 504 ) (GRIDX(I),GRIDY(J),GUI(I,J),J=N1,N2)
108 CONTINUE
C
        DO 109 I = M1, M2
          READ ( INV, 504 ) (GRIDX(I),GRIDY(J),HVARI(I,J),J=N1,N2)
109 CONTINUE
C
        IF ( IPRT .NE. 0 ) THEN
          WRITE ( OUP, 608 )
          WRITE ( OUP, 609 ) ((GRIDX(I),GRIDY(J),GRA036(I,J),GUN036(I,J),
*                          GRA180(I,J),GUN180(I,J),GRA300(I,J),
*                          GUN300(I,J),GUI(I,J),HVARI(I,J),
*                          J=1,NYI),I=1,NXI)
          END IF
C
C.....SELECT THE APPROPRIATE OSU MODEL
C
        IF ( MODEL .EQ. 180 ) THEN
C
          DO 110 I = M1, M2
            DO 111 J = N1, N2
              GRAN(I,J) = GRA180(I,J)
              GUND(I,J) = GUN180(I,J)
111 CONTINUE
110 CONTINUE
C
          ELSE IF ( MODEL .EQ. 36 ) THEN
C
            DO 112 I = M1, M2
              DO 113 J = N1, N2
                GRAN(I,J) = GRA036(I,J)
                GUND(I,J) = GUN036(I,J)
113 CONTINUE
112 CONTINUE
C
            ELSE IF ( MODEL .EQ. 300 ) THEN
C
              DO 114 I = M1, M2
                DO 115 J = N1, N2
                  GRAN(I,J) = GRA300(I,J)
                  GUND(I,J) = GUN300(I,J)
115 CONTINUE
114 CONTINUE
C
            ELSE
C
              WRITE ( OUP, 999 ) MODEL
              STOP
C
            END IF
C
C.....READ IN THE COVARIANCE TABLE
C
          READ ( INP, 501 ) ( SD(I), (CTV(I,J),J=1,3), I=1,LCT)
C
C.....SCALE THE CORRELATION LENGTH OF THE COVARIANCE FUNCTION
C
          DO 149 I = 1, LCT
            SD(I) = SD(I) * DBLE(SCX)
149 CONTINUE
C
C.....CONSTRUCT THE COVARIANCE MATRIX DIAGONAL ADDRESS

```

```

C
DO 116 I = 1, MTR
  IDIAG(I) = (I*(I+1))/2
116 CONTINUE
C
C
C.....START AN ITERATION PROCESS TO REFINE THE GRAVITY ANOMALY
C
DO 900 IJK = 0, ITM
C
DO 150 I = 1, LCT
  CVUU(I) = CTV(I,1)
  CVUG(I) = CTV(I,2)
  CVGG(I) = CTV(I,3)
150 CONTINUE
C
C.....DETERMINE THE POWER SPECTRA OF THE COVARIANCE FUNCTIONS
C
CALL POWSPC ( A, CVUU, X, PCVUU, LCT, LCTF, NFFT, IWKF, WKF )
CALL POWSPC ( A, CVUG, X, PCVUG, LCT, LCTF, NFFT, IWKF, WKF )
CALL POWSPC ( A, CVGG, X, PCVGG, LCT, LCTF, NFFT, IWKF, WKF )
C
C.....DETERMINE A CUBIC SPLINE COEFFICIENT MATRIX SC
C
CALL ICSCCU ( SD, CVUU, LCT, SCUU, LCT-1, IER )
CALL ICSCCU ( SD, CVUG, LCT, SCUG, LCT-1, IER )
CALL ICSCCU ( SD, CVGG, LCT, SCGG, LCT-1, IER )
C
C.....WRITE OUT THE VALUES OF THE COVARIANCE FUNCTIONS AND THE
CORRESPONDING POWER SPECTRA
C
WRITE ( OUB, 631 ) IJK
WRITE ( OUB, 501 ) (SD(I),CTV(I,1),CTV(I,2),CTV(I,3),I=1,LCT)
WRITE ( OUB, 632 ) IJK
WRITE ( OUB, 501 ) (SD(I),PCVUU(I),PCVUG(I),PCVGG(I),I=1,LCT)
WRITE ( OUP, 601 ) IJK
WRITE ( OUP, 602 ) (SD(I),CTV(I,1),CTV(I,2),CTV(I,3),I=1,LCT)
WRITE ( OUP, 634 ) IJK
WRITE ( OUP, 602 ) (SD(I),PCVUU(I),PCVUG(I),PCVGG(I),I=1,LCT)
C
C.....TRANSFORM THE GEOIDAL HEIGHT TO GRAVITY ANOMALY
C
WRITE ( OUP, 600 )
WRITE ( OUP, * ) ' GEOIDAL HEIGHT TO GRAVITY ANOMALY: ', IJK
WRITE ( OUP, * )
C
RMS = 0.
RMS1 = 0.
RMS2 = 0.
RMS3 = 0.
JCG = 0
DO 200 I = M1, M2
DO 201 J = N1, N2
C
GA(I,J) = -1000.0
GVAR(I,J) = -1000.0
C
* IF ( MASK(I,J) .NE. 0 .AND. GRAN(I,J) .NE. -1000.0 .AND.
GUI(I,J) .NE. -1000.0 .AND. GUND(I,J) .NE. -1000.0 ) THEN
C
I1 = I - INC
I2 = I + INC
J1 = J - INC
J2 = J + INC
IF ( I1. LT. 1 ) I1 = 1
IF ( I2. GT. NXI ) I2 = NXI
IF ( J1. LT. 1 ) J1 = 1
IF ( J2. GT. NYI ) J2 = NYI
C
IREC = 0

```

```

C
DO 210 M = I1, I2
C
DO 211 N = J1, J2
IF ( GUI(M,N).NE.-1000..AND.GUND(M,N).NE.-1000.) THEN
RS = (GRIDX(I)-GRIDX(M))**2 + (GRIDY(J)-GRIDY(N))**2
IF ( RS. LT. CAP2 ) THEN
IREC = IREC + 1
EX(IREC) = RGRIDX(M)
GY(IREC) = RGRIDY(N)
GH(IREC) = DBLE ( GUI(M,N) - GUND(M,N) )
SE(IREC) = DBLE ( 0.01*HVARI(M,N) + ANOISE )
END IF
END IF
C
211 CONTINUE
210 CONTINUE
C
IF ( IREC. GT. KUTOFF ) THEN
X1 = RGRIDX(I)
Y1 = RGRIDY(J)
SY1 = SY(J)
CY1 = CY(J)
JREC = (IREC*(IREC+1))/2
JCG = JCG + 1
CALL PREDIC ( 1, PVAL,VAR, EX,GY,GH,SGY,CGY,IREC,
* SE, X1,Y1,SY1,CY1,
* CM,CMS,CMI,JREC, IDIAG,CP, SRC,AP,
* SD,CTV,CVUU,SCUU,CVUG,SCUG,CVGG,SCGG,
* LCT, DTR, IER, NIER )
IF ( IER. EQ. 0 ) THEN
GA(I,J) = PVAL + GRAN(I,J)
GVAR(I,J) = VAR
RMS = RMS + PVAL*PVAL
D1 = GA(I,J) - GRA180(I,J)
D2 = GA(I,J) - GRA036(I,J)
D3 = GA(I,J) - GRA300(I,J)
RMS1 = RMS1 + D1*D1
RMS2 = RMS2 + D2*D2
RMS3 = RMS3 + D3*D3
ELSE
JCG = JCG - 1
IF ( IPRT .NE. 0 ) WRITE ( OUP, * ) 'IER =',IER,
* PVAL =',PVAL,' VAR =',VAR
END IF
IF ( IPRT .NE. 0 ) WRITE ( OUP, 603 ) I,J,GRIDX(I),
* GRIDY(J),GA(I,J), GVAR(I,J), PVAL, IREC,JCG
END IF
C
END IF
C
201 CONTINUE
200 CONTINUE
C
RMSG(IJK) = SQRT ( RMS / FLOAT(JCG) )
RMSG1(IJK) = SQRT ( RMS1 / FLOAT(JCG) )
RMSG2(IJK) = SQRT ( RMS2 / FLOAT(JCG) )
RMSG3(IJK) = SQRT ( RMS3 / FLOAT(JCG) )
C
WRITE ( OUP, 614 ) RMSG(IJK),RMSG3(IJK),RMSG1(IJK),RMSG2(IJK)
C
C.....TRANSFORM BACK FROM GRAVITY ANOMALY TO GEOID HEIGHT
C
WRITE ( OUP, 600 )
WRITE ( OUP, * ) ' GRAVITY ANOMALY BACK TO GEOIDAL HEIGHT:',
* IJK
WRITE ( OUP, * ) ' '
C
RMS = 0.
RMS1 = 0.

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```

RMS2 = 0.
RMS3 = 0.
JCH = 0
DO 250 I = M1, M2
C
DO 251 J = N1, N2
C
GU(I,J) = -1000.0
HVAR(I,J) = -1000.0
C
IF ( MASK(I,J) .NE. 0 .AND. GUND(I,J) .NE. -1000.0 .AND.
C
* GA(I,J) .NE. -1000.0 .AND. GRAN(I,J) .NE. -1000.0 ) THEN
C
I1 = I - INC
I2 = I + INC
J1 = J - INC
J2 = J + INC
IF ( I1. LT. 1 ) I1 = 1
IF ( I2. GT. NXI ) I2 = NXI
IF ( J1. LT. 1 ) J1 = 1
IF ( J2. GT. NYI ) J2 = NYI
C
IREC = 0
C
DO 260 M = I1, I2
C
DO 261 N = J1, J2
C
IF ( GA(M,N) .NE. -1000. .AND. GRAN(M,N) .NE. -1000. ) THEN
RS = (GRIDX(I)-GRIDX(M))**2 + (GRIDY(J)-GRIDY(N))**2
IF ( RS. LT. CAP2 ) THEN
IREC = IREC + 1
EX(IREC) = RGRIDX(M)
GY(IREC) = RGRIDY(N)
GH(IREC) = DBLE ( GA(M,N) - GRAN(M,N) )
SE(IREC) = DBLE ( GVAR(M,N) )
END IF
END IF
C
261 CONTINUE
260 CONTINUE
C
IF ( IREC. GT. KUTOFF ) THEN
X1 = RGRIDX(I)
Y1 = RGRIDY(J)
SY1 = SY(J)
CY1 = CY(J)
JREC = (IREC*(IREC+1))/2
JCH = JCH + 1
CALL PREDIC ( 2, PVAL, VAR, EX, GY, GH, SGY, CGY, IREC,
* SE, X1, Y1, SY1, CY1,
* CM, CMS, CMI, JREC, IDIAG, CP, SRC, AP,
* SD, CTV, CVUU, SCUU, CVUG, SCUG, CVGG, SCGG,
* LCT, DTR, IER, NIER )
IF ( IER. EQ. 0 ) THEN
GU(I,J) = PVAL + GUND(I,J)
HVAR(I,J) = 100.*VAR
RMS = RMS + PVAL*PVAL
D1 = GU(I,J) - GUN180(I,J)
D2 = GU(I,J) - GUN036(I,J)
D3 = GU(I,J) - GUN300(I,J)
RMS1 = RMS1 + D1*D1
RMS2 = RMS2 + D2*D2
RMS3 = RMS3 + D3*D3
ELSE
JCH = JCH - 1
IF ( IPRT .NE. 0 ) WRITE ( OUP, * ) 'IER =', IER,
* PVAL =', PVAL,' VAR =', VAR
END IF
IF ( IPRT .NE. 0 ) WRITE ( OUP, 617 ) I, J, GRIDX(I),
* GRIDY(J), GU(I,J), HVAR(I,J), PVAL, IREC, JCH
END IF

```

```

C
      END IF
C
251   CONTINUE
250   CONTINUE
C
      RMSH(IJK) = SQRT ( RMS / FLOAT(JCH) )
      RMSH1(IJK) = SQRT ( RMS1 / FLOAT(JCH) )
      RMSH2(IJK) = SQRT ( RMS2 / FLOAT(JCH) )
      RMSH3(IJK) = SQRT ( RMS3 / FLOAT(JCH) )
C
      WRITE ( OUP, 614 ) RMSH(IJK),RMSH3(IJK),RMSH1(IJK),RMSH2(IJK)
C
C.....CHECK CONVERGENCE CRITERION
C
      IF ( RMSG(IJK) .LT. CNVRGE ) GO TO 777
C
C.....REDETERMINE THE EMPIRICAL COVARIANCE FUNCTION
C
      CALL EMPCVF ( SD,CTV, NXI,NYI,DX,NYI, GRAN,GA, GUND,GUI,
*                WKCG,WKCH, CHHNS,CHHEW, CHGNS,CHGEW, CGGNS,CGGEW )
C
C.....USE THE RESULTANT GEODIAL HEIGHT AND GRAVITY ANOMALY AS A
C      WORKING MODEL FOR THE NEXT ITERATION STEP
C
      DO 270 I = 1, NXI
        DO 271 J = 1, NYI
          GUND(I,J) = GU(I,J)
271   CONTINUE
270   CONTINUE
C
      DO 280 I = 1, NXI
        DO 281 J = 1, NYI
          GRAN(I,J) = GA(I,J)
281   CONTINUE
280   CONTINUE
C
900 CONTINUE
C
C
C.....WRITE OUT THE SUMMARY OF THE ITERATION.
C
777 IF ( IJK .GT. ITM ) IJK = ITM
      WRITE ( OUP, 618 ) MODEL
      WRITE ( OUP, 621 ) ( L, RMSG(L), RMSH(L), RMSG3(L), RMSH3(L),
*                      RMSG1(L), RMSH1(L), RMSG2(L), RMSH2(L),
*                      L = 0, IJK )
C
C.....DETERMINE THE RANGE OF THE PREDICTED VALUES AND THEIR VARIANCE
C
      DO 300 I = M1, M2
        DO 301 J = N1, N2
          IF ( GA(I,J). NE. -1000.0 ) THEN
            GMING = AMIN1 ( GMING, GA(I,J) )
            GMAXG = AMAX1 ( GMAXG, GA(I,J) )
          END IF
          IF ( GVAR(I,J). NE. -1000.0 ) THEN
            VMING = AMIN1 ( VMING, GVAR(I,J) )
            VMAXG = AMAX1 ( VMAXG, GVAR(I,J) )
          END IF
          IF ( GU(I,J). NE. -1000.0 ) THEN
            GMINH = AMIN1 ( GMINH, GU(I,J) )
            GMAXH = AMAX1 ( GMAXH, GU(I,J) )
          END IF
          IF ( HVAR(I,J). NE. -1000.0 ) THEN
            VMINH = AMIN1 ( VMINH, HVAR(I,J) )
            VMAXH = AMAX1 ( VMAXH, HVAR(I,J) )
          END IF
        END DO
301 CONTINUE
300 CONTINUE

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C
C.....PRINT OUT THE GRIDDED VALUES AND THE VARIANCE
C
      NXY = (M2-M1+1)*(N2-N1+1)
      WRITE ( OUP, 604 ) NIER, JCG, NXY, GMING, GMAXG
      DO 400 I = M1, M2
        WRITE ( OUP, 605 ) (GRIDX(I),GRIDY(J),GA(I,J),J=N1,N2)
        WRITE ( OUG, 606 ) (GRIDX(I),GRIDY(J),GA(I,J),J=N1,N2)
400 CONTINUE
C
      WRITE ( OUP, 615 ) NIER, JCH, NXY, GMINH, GMAXH
      DO 401 I = M1, M2
        WRITE ( OUP, 605 ) (GRIDX(I),GRIDY(J),GU(I,J),J=N1,N2)
        WRITE ( OUH, 606 ) (GRIDX(I),GRIDY(J),GU(I,J),J=N1,N2)
401 CONTINUE
C
      WRITE ( OUP, 607 ) VMING, VMAXG
      DO 410 I = M1, M2
        WRITE ( OUP, 605 ) (GRIDX(I),GRIDY(J),GVAR(I,J),J=N1,N2)
        WRITE ( OVG, 606 ) (GRIDX(I),GRIDY(J),GVAR(I,J),J=N1,N2)
410 CONTINUE
C
      WRITE ( OUP, 616 ) VMINH, VMAXH
      DO 411 I = M1, M2
        WRITE ( OUP, 605 ) (GRIDX(I),GRIDY(J),HVAR(I,J),J=N1,N2)
        WRITE ( OVH, 606 ) (GRIDX(I),GRIDY(J),HVAR(I,J),J=N1,N2)
411 CONTINUE
C
C.....DETERMINE THE DIFFERENCE BETWEEN THE PREDICTED GRAVITY ANOMALIES
C      AND THE MODEL VALUES USED
C
      IF ( MODEL .EQ. 180 ) THEN
C
        DO 420 I = 1, NXI
          DO 421 J = 1, NYI
            DIFF(I,J) = -1000.0
            IF ( GA(I,J) .NE. -1000.0 ) THEN
              DIFF(I,J) = GA(I,J) - GRA180(I,J)
            END IF
421 CONTINUE
420 CONTINUE
C
        ELSE IF ( M .EQ. 36 ) THEN
C
          DO 430 I = 1, NXI
            DO 431 J = 1, NYI
              DIFF(I,J) = -1000.0
              IF ( GA(I,J) .NE. -1000.0 ) THEN
                DIFF(I,J) = GA(I,J) - GRA036(I,J)
              END IF
431 CONTINUE
430 CONTINUE
C
        ELSE IF ( M .EQ. 300 ) THEN
C
          DO 440 I = 1, NXI
            DO 441 J = 1, NYI
              DIFF(I,J) = -1000.0
              IF ( GA(I,J) .NE. -1000.0 ) THEN
                DIFF(I,J) = GA(I,J) - GRA300(I,J)
              END IF
441 CONTINUE
440 CONTINUE
C
        END IF
C
      WRITE ( OUP, 622 )
      DO 450 I = M1, M2
        WRITE ( OUP, 605 ) (GRIDX(I),GRIDY(J),DIFF(I,J),J=N1,N2)
        WRITE ( OUD, 606 ) (GRIDX(I),GRIDY(J),DIFF(I,J),J=N1,N2)

```



```

450 CONTINUE
C
C
501 FORMAT(1X,D10.4,3D20.13)
C
502 FORMAT((4D20.13))
503 FORMAT((6(2X,F10.3)))
504 FORMAT((3(2F7.2,F12.4)))
505 FORMAT((3X,65I1))
600 FORMAT(1H1)
601 FORMAT(1H1,T5,'VALUES OF THE COVARIANCE TABLE USED',
*
*      ' IN ITERATION: ',I3,/1H0,/)
602 FORMAT((1H ,5X,D10.4,3(5X,D20.13)))
603 FORMAT(1H0,T2,'GRID(',I2,',',I2,')',2X,'ELON = ',F6.2,1X,
*
*      ',GLAT = ',F6.2,5X,'GRAVITY ANOM = ',F10.4,' +- ',F6.2,
*
*      ', DELTA = ',F6.2,5X,'REC #: ',I3,2X,I8)
604 FORMAT(1H1,T5,I4,' GRID POINTS HAVING NEGATIVE VARIANCE',/,1H0,/,
*
*      T5,'THERE ARE ',I4,' POINTS GRIDDED OUT OF A NET ',
*
*      ' OF ',I5,' GRID POINTS.',/,1H0,/,T8,'THE RANGE OF THE',
*
*      ' GRAVITY ANOMALY IN MGAL IS:',2F12.4,/,1H0)
605 FORMAT((1H ,5(2F7.2,F12.4)))
606 FORMAT((3(2F7.2,F12.4)))
607 FORMAT(1H1,T5,'THE RANGE OF THE VARIANCE IN MGAL IS:',2F12.4,/1H0)
608 FORMAT(1H1,T10,'MODEL GRAVITY ANOMALY AND GEOID UNDULATION:',/1H0)
609 FORMAT((1H ,T5,2F10.2,6F12.3,4X,2F14.4))
610 FORMAT(1H1,T10,'INPUT GEOID UNDULATION:',/,1H0)
611 FORMAT(1H1,T10,'INPUT GEOID STANDARD ERROR:',/,1H0)
612 FORMAT(1H1,T10,'THE BLACK SEA MASK:',/,1H0)
613 FORMAT((1X,5(2F7.2,F12.4)))
614 FORMAT(1H0,/,T8,'THE RELATIVE RMS DIFFERENCES IS : ',F10.4,/,
*
*      T8,'THE RMS RESPECT TO MODEL 300 IS : ',F10.4,/,
*
*      T8,'THE RMS RESPECT TO MODEL 180 IS : ',F10.4,/,
*
*      T8,'THE RMS RESPECT TO MODEL 36 IS : ',F10.4)
615 FORMAT(1H1,T5,I4,' GRID POINTS HAVING NEGATIVE VARIANCE',/,1H0,/,
*
*      T5,'THERE ARE ',I4,' POINTS GRIDDED OUT OF A NET ',
*
*      ' OF ',I5,' GRID POINTS.',/,1H0,/,T8,'THE RANGE OF THE',
*
*      ' GEOIDAL HEIGHT IN METER IS:',2F12.4,/,1H0)
616 FORMAT(1H1,T5,'THE RANGE OF THE VARIANCE IN CM IS:',2F12.4,/1H0)
617 FORMAT(1H0,T2,'GRID(',I2,',',I2,')',2X,'ELON = ',F6.2,1X,
*
*      ',GLAT = ',F6.2,5X,'GEOID HEIGHT = ',F10.4,' +- ',F6.2,
*
*      ', DELTA = ',F6.2,5X,'REC #: ',I3,2X,I8)
618 FORMAT(1H1,///,T30,'OSU MODEL USED: ',I3,////,
*
*      T10,'SUMMARY OF THE RMS OF THE ITERATIONS:',///,
*
*      T10,' RELATIVE ', T26,' RELATIVE ',
*
*      T40,' 300 X 300 ', T56,' 300 X 300 ',
*
*      T70,' 180 X 180 ', T86,' 180 X 180 ',
*
*      T100,' 36 X 36 ', T116,' 36 X 36 ' /
*
*      T2,'ITER',
*
*      T10,'GRAVITY ANOMALY', T26,'GEOID HEIGHT',
*
*      T40,'GRAVITY ANOMALY', T56,'GEOID HEIGHT',
*
*      T70,'GRAVITY ANOMALY', T86,'GEOID HEIGHT',
*
*      T100,'GRAVITY ANOMALY',T116,'GEOID HEIGHT' /
*
*      T10,' (MGAL) ', T26,' (METER) ',
*
*      T40,' (MGAL) ', T56,' (METER) ',
*
*      T70,' (MGAL) ', T86,' (METER) ',
*
*      T100,' (MGAL) ', T116,' (METER) ' /
*
*      T2,'-----',
*
*      T10,'-----', T26,'-----',
*
*      T40,'-----', T56,'-----',
*
*      T70,'-----', T86,'-----',
*
*      T100,'-----',T116,'-----')
621 FORMAT((1H0,/,T2,I3,T12,F9.4,T27,F9.4,T42,F9.4,T57,F9.4,
*
*      T72,F9.4,T87,F9.4,T102,F9.4,T117,F9.4))
622 FORMAT(1H1,T5,'THE DIFFERENCE BETWEEN THE PREDICTED AND ',
*
*      ' THE MODEL GRAVITY ANOMALIES:',/,1H0)
631 FORMAT(1H ,T5,'VALUES OF THE COVARIANCE TABLE USED',
*
*      ' IN ITERATION: ',I3)
632 FORMAT(1H ,T5,'VALUES OF THE CORRESPONDING POWER SPECTRA USED',
*
*      ' IN ITERATION: ',I3)
633 FORMAT(1X,I10,3D20.13)
634 FORMAT(1H1,T5,'VALUES OF THE CORRESPONDING POWER SPECTRA USED',

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*
* IN ITERATION: ',I3,/,1H0)
635 FORMAT((1H ,5X,I10,3(5X,D20.13)))
999 FORMAT(1H1,/,/,T10,'**** WRONG MODEL: ',I5,' USED. ****',/,/,
* T20,'APPROPRIATE MODELS ARE 36, 180 AND 300 1')
C
C
C STOP
C END
C SUBROUTINE POWSPC ( A, CV, X, P, LCT, LCTF, NFFT, IWK, WK )
C
C.....THIS SUBROUTINE DETERMINE THE POWER SPECTRUM OF A COVARIANCE
C FUNCTION USING IMSL FFT SUBROUTINE
C
C REAL*8 A(LCTF), CV(LCT), P(LCTF), WK(NFFT)
C REAL*8 DI, DR, PMAX
C COMPLEX*16 X(LCTF)
C INTEGER IWK(NFFT)
C
C PMAX = -1.0D0
C ND2 = LCTF/2 + 1
C
C.....FIRST SYMMETRIZE THE COVARIANCE FUNCTION
C
C DO 100 I = 1, LCT-1
C A(I) = CV(LCT+1-I)
C A(LCT-1+I) = CV(I)
C 100 CONTINUE
C
C.....THEN SET THE END POINTS TO HAVE ZERO SLOPE
C
C A(1) = A(2)
C A(LCTF) = A(2)
C
C CALL FFTRC ( A, LCTF, X, IWK, WK )
C
C.....DETERMINE THE REMAINING COEFFICIENTS
C
C DO 110 I = 2, ND2
C X(LCTF+2-I) = DCONJG(X(I))
C 110 CONTINUE
C
C.....DETERMINE THE POWER SPECTRUM
C
C DO 120 I = 1, LCTF
C DR = DREAL(X(I))
C DI = DIMAG(X(I))
C P(I) = DSQRT ( DR*DR + DI*DI )
C 120 CONTINUE
C
C.....NORMALIZE THE COVARIANCE FUNCTION BEFORE THE FOURIER TRANSFORM
C
C DO 130 I = 1, LCTF
C PMAX = DMAX1 ( PMAX, P(I) )
C 130 CONTINUE
C
C DO 140 I = 1, LCTF
C P(I) = P(I)/PMAX
C 140 CONTINUE
C
C RETURN
C END
C SUBROUTINE EMPCVF ( D,CTV, M,N,DXY,MN, G,DG, H,DH, CG,CH,
* CHNS,CHHEW, CHGNS,CHGEW, CGGNS,CGGEW )
C
C REAL*4 CG(M,N), CH(M,N)
C REAL*4 G(M,N), DG(M,N), H(M,N), DH(M,N)
C REAL*4 CHNS(0:MN-1), CHHEW(0:MN-1)
C REAL*4 CHGNS(0:MN-1), CHGEW(0:MN-1)
C REAL*4 CGGNS(0:MN-1), CGGEW(0:MN-1)
C REAL*8 D(MN), CTV(MN,3)

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C
C.....REMOVE THE MODEL VALUE FROM THE DATA
C
DO 100 I = 1, M
  DO 101 J = 1, N
    IF ( DH(I,J) .NE. -1000.0 .AND. H(I,J) .NE. -1000.0 ) THEN
      CH(I,J) = DH(I,J) - H(I,J)
    END IF
    IF ( DG(I,J) .NE. -1000.0 .AND. G(I,J) .NE. -1000.0 ) THEN
      CG(I,J) = DG(I,J) - G(I,J)
    END IF
  101 CONTINUE
100 CONTINUE
C
C.....PERFORM THE CONVOLUTION
C
DO 200 K = 0, MN-1
C
  SHH = 0.
  SHG = 0.
  SGG = 0.
  CHHNS(K) = 0.
  CHGNS(K) = 0.
  CCGNS(K) = 0.
  DO 210 J = 1, N
    DO 211 I = K+1, M
      IF ( CH(I-K,J) .NE. -1000.0 .AND. CH(I,J) .NE. -1000.0 ) THEN
        SHH = SHH + CH(I-K,J)*CH(I,J)
      END IF
      IF ( CH(I-K,J) .NE. -1000.0 .AND. CG(I,J) .NE. -1000.0 ) THEN
        SHG = SHG + CH(I-K,J)*CG(I,J)
      END IF
      IF ( CG(I-K,J) .NE. -1000.0 .AND. CG(I,J) .NE. -1000.0 ) THEN
        SGG = SGG + CG(I-K,J)*CG(I,J)
      END IF
    211 CONTINUE
  210 CONTINUE
  C1 = ((M-K)*N)
  CHHNS(K) = SHH / C1
  CHGNS(K) = SHG / C1
  CCGNS(K) = SGG / C1
C
  SHH = 0.
  SHG = 0.
  SGG = 0.
  CHHEW(K) = 0.
  CHGEW(K) = 0.
  CGGEW(K) = 0.
  DO 220 I = 1, M
    DO 221 J = K+1, N
      IF ( CH(I,J-K) .NE. -1000.0 .AND. CH(I,J) .NE. -1000.0 ) THEN
        SHH = SHH + CH(I,J-K)*CH(I,J)
      END IF
      IF ( CH(I,J-K) .NE. -1000.0 .AND. CG(I,J) .NE. -1000.0 ) THEN
        SHG = SHG + CH(I,J-K)*CG(I,J)
      END IF
      IF ( CG(I,J-K) .NE. -1000.0 .AND. CG(I,J) .NE. -1000.0 ) THEN
        SGG = SGG + CG(I,J-K)*CG(I,J)
      END IF
    221 CONTINUE
  220 CONTINUE
  C2 = (M*(N-K))
  CHHEW(K) = SHH / C2
  CHGEW(K) = SHG / C2
  CGGEW(K) = SGG / C2
C
  D(K+1) = DBLE ( K * DXY )
  CTV(K+1,1) = DBLE (( C1*CHHNS(K) + C2*CHHEW(K) ) / ( C1 + C2 ))
  CTV(K+1,2) = DBLE (( C1*CHGNS(K) + C2*CHGEW(K) ) / ( C1 + C2 ))
  CTV(K+1,3) = DBLE (( C1*CCGNS(K) + C2*CGGEW(K) ) / ( C1 + C2 ))

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C
200 CONTINUE
C
RETURN
END
SUBROUTINE PREDIC ( IT, PVAL,VAR, EX,GY,GH, SGY,CGY, IREC,
*
* SE, X1,Y1,SY1,CY1,
* CM,CMS,CMI,JREC, IDIAG,CP, SRC,AP,
* SD,CTV,CVUU,SCUU,CVUG,SCUG,CVGG,SCGG,
* LCT, DTR, IER, NIER )
C
REAL*8 SE(IREC)
REAL*8 EX(IREC), GY(IREC), GH(IREC), SGY(IREC), CGY(IREC)
REAL*8 CP(IREC), SRC(IREC), AP(IREC)
REAL*8 CM(JREC), CMI(JREC), CMS(JREC)
REAL*8 SD(LCT), CTV(LCT,3)
REAL*8 CVUU(LCT), SCUU(LCT-1,3)
REAL*8 CVUG(LCT), SCUG(LCT-1,3)
REAL*8 CVGG(LCT), SCGG(LCT-1,3)
REAL*8 D1, D2, CSD, DSD, VDSO, DTR
REAL*8 X1, Y1, SY1, CY1, PVAL, VAR
REAL*8 R1, R2
INTEGER IDIAG(IREC)
C
C.....RESET THE ERROR COUNTER
C
IER = 0
C
IF ( IT. EQ. 1 ) THEN
R1 = CTV(1,1)
R2 = CTV(1,3)
ELSE IF ( IT. EQ. 2 ) THEN
R1 = CTV(1,3)
R2 = CTV(1,1)
END IF
C
C.....CLEAR THE COVARIANCE MATRIX ARRAY
C
CALL DCLR( CM, JREC )
CALL DCLR( CMI, JREC )
CALL DCLR( CMS, JREC )
C
DO 100 I = 1, IREC
CM(IDIAG(I)) = R1 + SE(I)*SE(I)
100 CONTINUE
C
C.....EVALUATE ALL THE SINE AND COSINE TERMS
C
DO 200 I = 1, IREC
SGY(I) = DSIN(GY(I))
CGY(I) = DCOS(GY(I))
200 CONTINUE
C
C.....CONSTRUCT THE OFF-DIAGONAL TERMS OF THE SIGNAL COVARIANCE MATRIX
C
DO 300 J = 2, IREC
DO 301 I = 1, J-1
C
CSD = SGY(I)*SGY(J) + CGY(I)*CGY(J)*DCOS(EX(I)-EX(J))
DSD = DACOS(CSD)/DTR
IF ( IT. EQ. 1 ) THEN
CALL ICSEVU ( SD,CVUU,LCT, SCUU,LCT-1, DSD, VDSO, 1, IER )
ELSE IF ( IT. EQ. 2 ) THEN
CALL ICSEVU ( SD,CVGG,LCT, SCGG,LCT-1, DSD, VDSO, 1, IER )
END IF
K = (J*(J-1))/2 + I
CM(K) = VDSO
C
301 CONTINUE
300 CONTINUE

```

```

C
C.....DUPLICATE THE COVARIANCE MATRIX FOR STORAGE
C
      DO 310 I = 1, JREC
        CMS(I) = CM(I)
      310 CONTINUE
C
C.....INVERT THE COVARIANCE MATRIX
C
      CALL LINVIP ( CMS,IREC,CMI, IDGT, D1,D2, IER )
      CALL SOLVE ( CMS, SRC, IDIAG, IREC, .TRUE., .FALSE. )
      CALL SYMINV ( CMS, SRC, IDIAG, IREC, CMI )
C
      IF ( IER. EQ. 0 ) THEN
C.....CONSTRUCT THE COVARIANCE VECTOR
C
        DO 330 I = 1, IREC
          CSD = SY1*SGY(I) + CY1*CGY(I)*DCOS(X1-EX(I))
          DSD = DACOS(CSD)/DTR
          CALL ICSEVU ( SD,CVUG,LCT, SCUG,LCT-1, DSD, VSD, 1, IER )
          CP(I) = VSD
C
        330 CONTINUE
C
C.....DETERMINE THE PREDICTED VALUE AT A GRID POINT
C
      CALL VMULSF ( CMI,IREC, GH,1,IREC, SRC,IREC )
      CALL DCLR ( SRC, IREC )
      CALL VSMXVT ( CMI, GH, SRC, IDIAG, IREC )
      PVAL = DOT ( CP, SRC, IREC )
C
C.....DETERMINE THE VARIANCE OF THE PREDICTED VALUE
C
      CALL VMULSF ( CMI,IREC, CP,1,IREC, AP,IREC )
      CALL VMULSF ( CM,IREC, AP,1,IREC, SRC,IREC )
      CALL DCLR ( AP, IREC )
      CALL DCLR ( SRC, IREC )
      CALL VSMXVT ( CMI, CP, AP, IDIAG, IREC )
      CALL VSMXVT ( CM, AP, SRC, IDIAG, IREC )
      VAR = R2 - 2.0D0*DOT(AP,CP,IREC) + DOT(AP,SRC,IREC)
C
      IF ( VAR. GT. 0.0 ) THEN
        VAR = DSQRT(VAR)
      ELSE
        IER = 1
        NIER = NIER + 1
      END IF
C
      END IF
C
      RETURN
      END
      FUNCTION DOT ( A,B,N)
C
C Compute the dot product of the two N-vectors A and B.
C
      INTEGER N, I
      REAL*8 DOT
      REAL*8 A(1),B(1)
C
      DOT=0.0
C
      DO 100 I=1,N
100 DOT=DOT + A(I)*B(I)
C
      RETURN
      END
      SUBROUTINE SYMINV ( A, B, IDIAG, NEQ, AINV )

```



```

C..      Divide by row diagonal, and reduce diagonal term in column J
C
      IR = JR + 1
      K = J - JD
      DO 200 I = IR, JD-1
          ID = IDIAG(K+I)
          IF (A(ID).EQ.0.0) GOTO 200
          D = -A(I)
          A(I) = A(I)/A(ID)
          A(JD) = A(JD) + D*A(I)
200      CONTINUE
C
      ENDIF
C
C..      Reduce RHS
      IF (BACK) B(J) = B(J) - DOT(A(JR+1),B(IS-1),JH-1)
C
390     JR = JD
400     CONTINUE
C
C
      IF (.NOT.BACK) RETURN
C
C
C      Divide by diagonal pivots
C
      DO 700 I = 1,NEQ
          ID = IDIAG(I)
          IF (A(ID).NE.0.0) B(I) = B(I)/A(ID)
700     CONTINUE
C
C      Backsubstitute
C
      J = NEQ
      JD = IDIAG(J)
C
801     D = -B(J)
          J = J - 1
          IF (J.LE.0) RETURN
C
          JR = IDIAG(J)
          IF (JD-JR.GT.1) THEN
              IS = J - JD + JR + 2
              K = JR - IS + 1
              DO 810 I = IS, J
810             B(I) = B(I) + A(I+K)*D
          ENDIF
C
          JD = JR
          GOTO 801
C
C
      END
      SUBROUTINE VSMXVT ( A, B, C, JDIAG, NEQ )
C.....THIS SUBROUTINE FORMS C = C + A*B WHERE A IS A SYMMETRIC MATRIX
C      STORED IN PROFILE FORM, B, C ARE VECTORS, AND JDIAG LOCATES THE
C      DIAGONALS IN A.
C
      IMPLICIT REAL*8 (A-H,O-Z)
      DIMENSION A(1), B(1), C(1), JDIAG(1)
C
      JS = 1
      DO 200 J = 1, NEQ
          JD = JDIAG(J)
          IF ( JS. LE. JD ) THEN
              BJ = B(J)
              AB = A(JD)*BJ
              IF ( JS. NE. JD ) THEN
                  JB = J - JD

```

```

                JE = JD - 1
                DO 100 JJ = JS, JE
                    AB = AB + A(JJ)*B(JJ+JB)
                    C(JJ+JB) = C(JJ+JB) + A(JJ)*BJ
100             CONTINUE
                END IF
                C(J) = C(J) + AB
                END IF
                JS = JD + 1
200 CONTINUE
C
    RETURN
    END
    SUBROUTINE DCLR (A,NA)
C
    INTEGER NA, I
    REAL*8   A(1)
C
    DO 100 I = 1, NA
        A(I) = 0.0D0
100 CONTINUE
C
    RETURN
    END
/*
// EXEC LINKGOV,REGION=5000K
/*
//SYSLIB DD DSN=SYS2.IMSLD,DISP=SHR
//      DD DSN=SYS2.IMSLS,DISP=SHR
/*
// * * * * *
/*
//      BLACK SEA GRIDDED COLLOCATION GEOIDAL HEIGHT DATA
/*
// * * * * *
/*
//GO.FT05F001 DD DSN=ZMAYA.ALTIM.DATA(TABLE1),DISP=SHR
//GO.FT06F001 DD SYSOUT=*
//GO.FT08F001 DD DSN=ZMAYA.BLACKC4H.GRID,DISP=SHR
//GO.FT09F001 DD DSN=ZMAYA.BLACKC4H.COVN,DISP=SHR
//GO.FT10F001 DD DSN=ZMAYA.ALTIM.DATA(BRH180),DISP=SHR
//GO.FT11F001 DD DSN=ZMAYA.ALTIM.DATA(BRG180),DISP=SHR
//GO.FT12F001 DD DSN=ZMAYA.ALTIM.DATA(BRH36),DISP=SHR
//GO.FT13F001 DD DSN=ZMAYA.ALTIM.DATA(BRG36),DISP=SHR
//GO.FT14F001 DD DSN=ZMAYA.ALTIM.DATA(BRH300),DISP=SHR
//GO.FT15F001 DD DSN=ZMAYA.ALTIM.DATA(BRG300),DISP=SHR
//GO.FT16F001 DD DSN=ZMAYA.BLACK.MASK,DISP=SHR
//GO.FT17F001 DD DSN=ZMAYA.ALTIM.DATA(BSGAB0R),DISP=SHR
//GO.FT18F001 DD DSN=ZMAYA.ALTIM.COVN(BSGAB0R),DISP=SHR
//GO.FT19F001 DD DSN=ZMAYA.ALTIM.DATA(BSGUB0R),DISP=SHR
//GO.FT20F001 DD DSN=ZMAYA.ALTIM.COVN(BSGUB0R),DISP=SHR
//GO.FT21F001 DD DSN=ZMAYA.ALTIM.DIFF(BSGUB0R),DISP=SHR
//GO.FT22F001 DD DSN=ZMAYA.ALTIM.CVTB(B0R),DISP=SHR
/*
// EXEC NOTIFYTS

```


A listing of PROGRAM JORDAN

```

//ZMAYABJC JOB (G0109,360,2),AYAU,TIME=(00,30),CLASS=O,MSGCLASS=X
// EXEC FORTVC
//SYSIN DD *
C
  PARAMETER ( SN = 1.27 )
  PARAMETER ( SG = 11.20 )
  PARAMETER ( D = 0.38 )
  PARAMETER ( DR = 0.25 )
  PARAMETER ( RMIN = 0.0 )
  PARAMETER ( RMAX = 10.0 )
  PARAMETER ( SN2 = SN*SN )
  PARAMETER ( SG2 = SG*SG )
  PARAMETER ( L = RMAX/DR + 1 )
C
  REAL*8      R(L), CNN(L), CNG(L), CGG(L)
  REAL*8      RD, RDS, RD2, EXPRD, B10, B11, BK0, BK1
  REAL*8      DSN2, DSG2, DD, DDR, CNST
  REAL*8      MMBSI0, MMBSI1, MMBSK0, MMBSK1
  INTEGER     OUP, OUC
C
  DATA       OUP / 6 /, OUC / 8 /
C
  DSN2 = DBLE(SN2)
  DSG2 = DBLE(SG2)
  DDR = DBLE(DR)
  DD = DBLE(D)
  CNST = DBLE(2.*SN*SG)/DSQRT(6.0D0)
C
  R(1) = DBLE(RMIN)
  DO 100 I = 2, L
    R(I) = R(I-1) + DDR
100 CONTINUE
C
  CNN(1) = DSN2
  CGG(1) = DSG2
  CNG(1) = CNST
  DO 200 I = 2, L
C
  RD = R(I)/DD
  RDS = RD*RD
  RD2 = RD/2.0D0
  EXPRD = DEXP(-RD)
  B10 = MMBSI0(1, RD2, IER)
  B11 = MMBSI1(1, RD2, IER)
  BK0 = MMBSK0(1, RD2, IER)
  BK1 = MMBSK1(1, RD2, IER)
C
  CNN(I) = DSN2 * ( 1.0D0 + RD + RDS/3.0D0 ) * EXPRD
C
  CGG(I) = DSG2 * ( 1.0D0 + RD - RDS/2.0D0 ) * EXPRD
C
  CNG(I) = CNST * ( RD2*(1.0D0-(RDS/2.0D0))*(B10*BK1-B11*BK0)
*                + (RDS/4.0D0)*(B10*BK0+B11*BK1) )
C
200 CONTINUE
C
  WRITE ( OUP, 600 )
  WRITE ( OUP, 601 ) (R(I), CNN(I), CNG(I), CGG(I), I=1, L)
  WRITE ( OUC, 801 ) (R(I), CNN(I), CNG(I), CGG(I), I=1, L)
C
600 FORMAT(1H1, //, T5, 'THE COVARIANCE FUNCTION C(NN), C(NG) & C(GG):',
*        //)
601 FORMAT((1H ,5X,D10.4,3(5X,D20.13)))
801 FORMAT((1X,D10.4,3D20.13))
C
  STOP
  END

```

```
//*  
// EXEC LINKGOV,REGION=5000K  
//*  
//SYSLIB DD DSN=SYS2.IMSLD,DISP=SHR  
//* DD DSN=SYS2.IMSLS,DISP=SHR  
//*  
//GO.FT06F001 DD SYSOUT=*  
//GO.FT08F001 DD DSN=ZMAYA.ALTIM.DATA(BJ180),DISP=SHR  
//*  
// EXEC NOTIFYTS
```



Report Documentation Page

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