# On Limits 

Gerard J. Holzmann

Jet Propulsion Laboratory
California Institute of Technology

## speed and memory trends

(we will soon have very large amounts of memory and relatively slow processors)


## the time needed to fill $N$ GB of RAM


[Spin in bitstate mode]

## what are the limits?

- at a fixed clock-speed, there is a limit to the largest problem size we can handle in 1 hour (day / week)
- no matter how much memory we have (RAM or disk)
- even a machine with "infinite memory" but "finite speed" will impose such limits
- we can increase speed by using multi-core algorithms
- but do $10^{n}$ CPUs always get a $10^{n} x$ speedup?
- it will depend on the CPU architecture (NUMA/UMA)
- do we know what the CPU architecture will be for large multi-core machines (think 1,000 CPUs and up)?
- isn't there an easier way?
- can't we find a way to use N x as many CPUs, and get a result that is always " N x better" (by some definition of "better")


## at fixed speed how many CPUs does it take to fill up $N$ GB of RAM in 1 hour?



## the infinitely large problem and the infinitely large machine

- there will always be problems that require more time to verify than we are willing (or able) to wait for
- how do we best use finite time to handle large problems?
- example of an "infinitely large problem:" a Spin Fleet Architecture model from Ivan Sutherland \& students (courtesy


## Sanjit Seshia)

- known error state is just beyond reach
of a breadth-first search (and symbolic methods) - error is too deep
- error is on "wrong" side of the DFS tree
- a bitstate search either fills up memory
or exhausts the available time before the error state is reached
- how do we maximize our chances of
 finding errors like this?


## measurement:

 define a simple, large search problem```
byte pos \(=0\);
int val \(=0\);
int flag \(=1\);
active proctype word()
\{ /* generate all 32 -bit values */
end: do
    :: d_step \{ pos < 32 -> /* leave bit 0 */ flag = flag << 1; pos++ \}
    :: d_step \{ pos < 32 -> val = val | flag; flag = flag << 1; pos++ \}
    od
\}
never \{/* check if some user-defined value \(N\) can be matched */
    do
    : : assert(val != N)
    od
\}
\(2^{32}\) reachable states, 24 byte per state 100 GB to store the full state space what if we only have 64 MB to do the search? \(0.06 \%\) of what is needed
```


## a sample search query

- $2^{32}$ reachable states, 24 bytes per state
- 100 GB to store the full state space
- 64 MB available ( 0.06 \% of 100 GB)
- question:
- seed 100 randomly chosen numbers
- how many of these numbers can be found (matched)?
- using different search techniques
- one obvious candidate: bitstate hashing with depth-first search
- assume 0.5 byte per state on average: $2^{32} \times 0.5 \sim 2 \mathrm{~GB}$
- $64 \mathrm{MB}\left(2^{26}\right)$ is now $3 \%(1 / 32)$ of what is needed to represent all states
- should find matches for ~ 3 of the 100 numbers


## bitstate dfs -w29 <br> $2^{29}$ bits $=2^{26}$ bytes $=64 \mathrm{MB}$

```
$ spin',-DN=-1,'-a word.pml
$ cc -02`=DSÁFETY -DBITSTATE -o pan pan.c
$ ./pan -w29
...
1.4849945e+08 states, stored (3.46% of all 232 states)
hash factor: 3.61531 (best if > 100.)
bits set per state: 3 (-k3)
```

pan: elapsed time 127 seconds
\$
this search does not find a match for the target number -1
if we repeat this $100 x$ for each of the randomly chosen numbers
we should expect 3 or 4 matches

## checking 100 numbers

```
$ > out
$ for r in `cat ../numbers`
$ do
    spin -DN=$r -a word.pml
    cc -02 -DSAFETY -DBITSTATE pan.c
    ./pan -w29 >> out
done
$_grep "assertion violated" out | sort -u | wc -l
we were "entitled" to 3 or 4 matches, and we got 8
(i.e., we were lucky)
numbers matched:
234, -3136, 3435, 19440, 6985, 12435, 4915, 27246
(note: 52 of our targets are negative numbers, we
matched only }1\mathrm{ in this subset)
```


## using iterative search refinement [HS99] (using 128KB, 256KB, ... 64 MB )



## adding search diversification

- dfs: standard depth-first search (the default)
- dfs_r: reverse order in which non-deterministic choices within a process are explored
- using compiler directive -D_TREVERSE (Spin 5.1.5).
- r_dfs: use search randomization on the order in which nondeterministic choices within a process are explored
- using compiler directive -DRANDOMIZE (Spin 4.2.2) randomly selects a starting point in the transition list, and checks transitions for executability in round-robin order from that point use different seeds to create multiple variants (r_dfs1, r_dfs2)
- pick: use embedded $C$ code to define a user-controlled selection method to permute the transitions in a list of non-deterministic choices within a process


## pick: user-defined randomization

(courtesy of rajeev joshi \& alex groce)

```
c_decl {`#define MAX_CHOICES 32 /* max nr of choices in calls to "pick" */
    int choices[MAX_CHOICES];
    int last_seed = 3;
};
c_track "choices" "sizeof(int)_* MAX_CHOICES" "UnMatched";
c_track "&last_seed" "sizeof(int)" MAX_CHOICES "UnMatched";
inline pick(v, min, max matmax-min+1 ;
    c_code {
            int i, j, t; /* temporary C vars */
            srandom(last seed) ;
            for (i = 0; i
            f choices[i]= i;
            for (i = 0; i < now.tmp-1; i++)
                j = (random()% (now.tmp - i));
                    choices[i] choices[1] choices[i+j];
                    choices[i+j] = t;
            }
    * randomize search order each time a node is revisited */
    do /* cover all choices */
    :: d_step { tmp < max-min -> tmp++ }
            v = min +c_expr { choices[now.tmp] };
            c_code { last_seed += now.tmp; now.tmp = 0; }
    od
}
int n, x, y, tmp;
active proctype main()
    do n < 3 -> \ n++;
                        pick(x,'1, 3
                        print#("n=%d, x = %d, y = %d\n", n, x, y)
    :: else
        pri
```


iterative search refinement +
search diversification: nr matches increases to 49


## fraction of memory used compared with fraction of targets matched



## swarm

## \$ swarm -F config.lib -c6 > script swarm: 456 runs, avg time per cpu 3599.2 sec \$ sh ./script

sample configuration file:

| \# ranges |  |  |
| :--- | :--- | :--- |
| w | 20 | 32 |
| d min and max -w parameter |  |  |
| d | 100 | 10000 \# min and max search depth |
| k | 20 | 5 |
| \# min and max nr of hash functions |  |  |

## swarm verification of some large models

| Verification Model | State <br> vector size | System states reached in standard bitstate dfs (-w29) | Time for bitstate dfs (in minutes using 1 cpu ) | Number of swarm jobs (1 hour limit 6 cpus) |
| :---: | :---: | :---: | :---: | :---: |
| EO1 | 2736 | 320.9M | 43 | 86 |
| Fleet | 1440 | 280.5 M | 58 | 228 |
| DEOS | 576 | 22.3M | 2 | 456 |
| Gurdag | 964 | 86.2M | 17 | 231 |
| CP | 344 | 165.7 M | 18 | 451 |
| DS1 | 3426 | 208.6M | 159 | 100 |
| NVDS | 180 | 151.2M | 6 | 516 |
| NVFS | 212 | 139.5M | 45 | 265 |

## performance

| Verification Model | Number of Control States |  |  | \% of Control States Reached |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Total | Unreached |  |  |  |
|  |  | standard dfs | dfs + swarm | standard dfs | dfs + swarm |
| EO1 | 3915 | 3597 | 656 | 8 | 83 |
| Fleet | 171 | 34 | 16 | 80 | 91 |
| DEOS | 2917 | 1989 | 84 | 32 | 97 |
| Gurdag | 1461 | 853 | 0 | 41 | 100 |
| CP | 1848 | 1332 | 0 | 28 | 100 |
| DS1 | 133 | 54 | 0 | 59 | 100 |
| NVDS | 296 | 95 | 0 | 68 | 100 |
| NVFS | 3623 | 1529 | 0 | 58 | 100 |

## synopsis

- there is a growing performance gap
- memory sizes continue to grow
- but cpu speed no longer does (for now)
- the standard approaches to handling large problem sizes have stopped working
- we have to get smarter about defining incomplete searches in very large state spaces
- the best use of currently available computational resources (and human time)
- may be to switch to the use of embarrassingly parallel methods, in combination with search diversification

