

On The Design and Capacity Of Wide Area Sensor Networks

Presented to George Seweryniak Mathematical, Information, and Computational Sciences

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Outline

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Motivation and Goals

Rapid deployment of wireless sensor networks is a critical need

- Deployment techniques remain more of an art than a science
 - Radio propagation environments and path-loss effects are hard to provision for without careful measurement
 - Diverse commercial off the shelf wireless devices have inconsistent behaviors

• An effective methodology for wireless network deployments will result in full coverage and capacity throughout the monitored zone in the least amount of time.

 This methodology will be evaluated as it is applied to an actual SensorNet deployment scenario at ORNL



SensorNet Component Examples

An ORNL-developed system responsible for collecting CBRNE (and other environmental) sensor data and distributing it back to the appropriate authority



Access Point



OAK RIDGE NATIONAL LABORATORY U. S. DEPARTMENT OF ENERGY Radiation and Chemical Agent Detectors





- Network coverage must blanket the entire monitored space
- Ensure network provides full capacity to all sensor nodes
- Received signal must not <u>unexpectedly</u> attenuate to an unusable level with increasing distance from the transmitter
- Each transmitter within a multi-transmitter network must communicate over non-interfering channels
- Hurdles to Overcome :co-channel interference, hidden and exposed terminal phenomena, multi-path fading effects at the receiver



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Focus on Infrastructure Wireless Network

Advantages:

- All traffic from client devices flow through access point
- Access point manages topology
- The client stations do not overload the network with internodal routing protocols
- Closer to realistic deployments

Disadvantages:

- Mobility limited by range of the access point
- Single point of network failure if the access point fails, all client/sensor nodes associated with the AP loose global connectivity

Summer experiments focused on 802.11b Protocol – Infrastructure Mode





Sensor Placement to Track Threats

- Deploy sensors in an X-pattern along each leg to track movement
- Space sensors evenly at 5 meter intervals
- Sensor distribution simplified for lineof-sight deployments (limited multi-path effects considered)



Fig. 1 ORNL East-Campus Quad



A Systematic Deployment Process

Pre-deployment

- 1. Determine the total area of the proposed monitored zone
- 2. Determine the typical coverage area of an access point transmitting at maximum power
- Initially deploy access points and sensors to spatially cover the target area



Fig. 1 ORNL East-Campus Quad



A Systematic Deployment Process

Environment Characterization

- 1. Measure initial signal coverage area of each AP
- 2. Characterize the noise floor at each initial AP and sensor position for each proposed network channel
- 3. Characterize the terrain between the transmitters and receivers and simulate the effect on the RF signal







A Systematic Deployment Process

Simulation and Validation

- Observe current RF coverage and capacity profile within the simulator. -which are based on initial <u>measured</u> values-
- If desired coverage and capacity is not achieved then <u>virtually</u> move AP's to new positions until optimum coverage and capacity is achieved within the simulation
- If the simulated received signal values are acceptable, manually move AP's and sensors into their final positions. Otherwise iterate over previous steps.
- Take a final set of signal measurements to validate the simulator's results
- Finally, document current signal and noise levels at AP and sensor locations for continued network maintenance and future expansion







Netstumbler Measurements

- Analysis software
 - 802.11x network evaluation
 - Commercial tool (http://www.netstumbler.co m)
- Measurements
 - Choose theoretical model
 - Validate and refine coverage choice



Netstumbler Raw Data

SSID	BSSID	Time hh:mm:ss	Distance from TX (m)	Direction from AP	NS RX Signal (dbm)	NS SNR	NS Noise (dbm)	NS Channel	TLM PL test points
Sensornetzz	00:0b:6b:35:fd:15	19:46:41	1	West	-29	60	-89	11	
Sensometzz	00:0b:6b:35:fd:15	19:48:18	5	West	-49	39	-88	11	pt1
Sensometzz	00:0b:6b:35:fd:15	19:49:13	10	West	-39	50	-89	11	pt2
Sensometzz	00:0b:6b:35:fd:15	19:49:54	15	West	-40	49	-89	11	pt3
Sensometzz	00:0b:6b:35:fd:15	19:50:42	20	West	-47	43	-92	11	pt4
Sensometzz	00:0b:6b:35:fd:15	19:51:36	25	West	-49	41	-90	11	pt5
Sensometzz	00:0b:6b:35:fd:15	19:52:26	30	West	-50	40	-90	11	
Sensometzz	00:0b:6b:35:fd:15	19:53:42	1	East	-33	55	-88	11	pt6
Sensometzz	00:0b:6b:35:fd:15	19:54:57	5	East	-38	49	-87	11	pt7
Sensometzz	00:0b:6b:35:fd:15	19:56:30	10	East	-44	45	-89	11	
Sensometzz	00:0b:6b:35:fd:15	19:57:11	15	East	-41	48	-89	11	
Sensometzz	00:0b:6b:35:fd:15	19:57:47	20	East	-41	45	-86	11	
Sensometzz	00:0b:6b:35:fd:15	19:58:39	25	East	-43	44	-87	11	
Sensometzz	00:0b:6b:35:fd:15	19:59:40	30	East	-53	36	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:00:55	1	South	-26	63	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:01:47	5	South	-49	40	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:02:37	10	South	-43	46	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:03:27	15	South	-52	38	-90	11	
Sensometzz	00:0b:6b:35:fd:15	20:04:13	20	South	-51	39	-90	11	
Sensometzz	00:0b:6b:35:fd:15	20:04:13	25	South	-51	39	-90	11	
Sensometzz	00:0b:6b:35:fd:15	20:06:20	30.692	South	-65	22	-87	11	
Sensometzz	00:0b:6b:35:fd:15	20:13:09	1	North	-33	56	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:14:06	5	North	-38	49	-87	11	
Sensometzz	00:0b:6b:35:fd:15	20:15:03	10	North	-37	52	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:16:15	15	North	-42	47	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:17:14	20	North	-46	43	-89	11	
Sensometzz	00:0b:6b:35:fd:15	20:18:13	25	North	-44	47	-91	11	
Sensometzz	00:0b:6b:35:fd:15	20:19:01	30	North	-44	46	-90	11	



Measured Path Loss Comparison with Empirically Modeled Path Loss

Path-Loss Models

– Log-Distance

 $\overline{PL}(dB) = PL(d_o) + 10nLog(d/d_0)$

- n = path loss exponent which indicates the rate at which the path loss increases with distance
- d₀ = the close-in reference distance





– Log-Normal

 $\overline{PL}(dB) = PL(d_o) + 10nLog(d/d_0) + X_{stdev}$

- n = the path loss exponent which indicates the rate at which the path loss increases with distance
- d₀ = the close-in reference distance determined by measurement
- n = 2 for free-space environments
- d₀ = the close-in reference distance 1-meter





Visual Representation of Results

Visualization of Wireless SensorNet Deployment



Nestumbler Measured Path Loss vs. Empirical Path Loss Models

Nestumbler Measured Path Loss vs. Empirical Path Loss Models West of Transmitter



Distance (meters)

Distance from TX (m)	Direction from AP	NS RX Signal Dbm	TX dbm	NS Path Loss	Log- Distance AvgPL (dbm) (n=2)	Log- normal Shadowing	Xo
1	West	-29	20	49	50.25	55.100551	4.850551
5	West	-49	20	69	64.2294	64.381576	0.152176
10	West	-39	20	59	70.25	76.633773	6.383773
15	West	-40	20	60	73.77183	71.137395	-2.63443
20	West	-47	20	67	76.2706	78.786635	2.516036
25	West	-49	20	69	78.2088	78.785342	0.576542
30	West	-50	20	70	79.79243	73.612043	-6.18038



Nestumbler Measured Path Loss vs. Empirical Path Loss Models

Nestumbler Measured Path Loss vs. Empirical Path Loss Models East of Transmitter



Distance (m)

Distance from TX (m)	Direction from AP	NS RX Signal Dbm	TX dbm	NS Path Loss	Log- Distance AvgPL (dbm) (n=2)	Log- normal Shadowing	Xo
1	East	-33	20	53	50.25	40.615801	-9.6342
5	East	-38	20	58	64.2294	52.437624	-11.7918
10	East	-44	20	64	70.25	76.479005	6.229005
15	East	-41	20	61	73.77183	81.620079	7.848253
20	East	-41	20	61	76.2706	78.459078	2.188478
25	East	-43	20	63	78.2088	86.499061	8.290261
30	East	-53	20	73	79.79243	80.082183	0.289758



Nestumbler Measured Path Loss vs. Empirical Path Loss Models Nestumbler Measured Path Loss vs. Empirical Path Loss Models

South of Transmitter



Distance (m)

Distance from TX (m)	Direction from AP	NS RX Signal Dbm	TX dbm	NS Path Loss	Log- Distance AvgPL (dbm) (n=2)	Log- normal Shadowing	Xo
1	South	-26	20	46	50.25	64.542038	14.29204
5	South	-49	20	69	64.2294	72.747612	8.518212
10	South	-43	20	63	70.25	53.954549	-16.2955
15	South	-52	20	72	73.77183	91.217525	17.4457
20	South	-51	20	71	76.2706	76.736239	0.465639
25	South	-51	20	71	78.2088	71.372055	-6.83674
30.692	South	-65	20	85	79.9905	70.839519	-9.15099



Nestumbler Measured Path Loss vs. Empirical Path Loss Models Nestumbler Measured Path Loss vs. Empirical Path Loss Models North of Transmitter

🛏 NS Path Loss = 📮 = Log-Distance Path Loss 🔫 = Log-Normal Path Loss



Distance (m)

Distance from TX (m)	Direction from AP	NS RX Signal Dbm	TX dbm	NS Path Loss	Log- Distance AvgPL (dbm) (n=2)	Log- normal Shadowing	X _o
1	North	-33	20	53	50.25	65.617913	15.36791
5	North	-38	20	58	64.2294	66.938046	2.708646
10	North	-37	20	57	70.25	78.127206	7.877206
15	North	-42	20	62	73.77183	78.3385	4.566674
20	North	-46	20	66	76.2706	77.943268	1.672668
25	North	-44	20	64	78.2088	81.350926	3.142125
30	North	-44	20	64	79.79243	82.923333	3.130908





- Manual wireless network deployments are inefficient
- Multi-path and other environmental interference effects force multiple iterations of all wireless network deployment techniques.
- Measurements combined with empirical models will increase the efficiency and effectiveness of SensorNet network deployments.
- Interference and path-loss detection tools need to improve to better characterize multi-path and RF attenuation effects
- A wireless sensor network environmentally configurable test bed would provide great exercise for this simulator.





- Considered a manual deployment of a wireless networks in infrastructure mode
 - Infrastructure-mode coverage of sensor networks
 - Incorporated COTS Tools and Technologies
- Developed Wireless Network Deployment Process
 - All wireless network deployments are an iterative process
 - Measured Signal Strength with available COTS tools
 - Matching RF theory and practice will greatly assist with the choice of an appropriate empirical model to make wireless networks more effective
- Future Work
 - Develop and implement an automated wireless deployment tool
 - Explore more RF path-loss models to better characterize <u>any</u> environment



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Questions?

