n_1

"Physicists are like 3% of rats."

-Max Zolotorev, Lawrence Berkeley National Laboratory

If you have any questions, suggestions or corrections to the solutions, don't hesitate to e-mail me at dfk@uclink4.berkeley.edu!

Problem 1

(a)

As demonstrated in last week's problem set (problem 8), an ideal quarter-wave plate is described by a unitary Jones matrix. This means that the irradiance of the light beam is unaffected by traversing the plate. Also, the mirror is a perfect conductor, so 100% of the light is reflected. So the final wave's irradiance must be the same as the incident wave's.

(b)

The wave, initially polarized along the \hat{x} direction, first passes through the quarter wave plate, whose fast axis is oriented at -45° with respect to the initial light polarization:

$$\begin{bmatrix} E_x \\ E_y \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -i \\ -i & 1 \end{bmatrix} \begin{bmatrix} E_0 \\ 0 \end{bmatrix} = \frac{E_0}{\sqrt{2}} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$
(1)

Then the light bounces off a perfectly conducting mirror. This reverses the sign of the Poynting vector, which in turn changes the sign of the B-field relative to the E-field, since (as can be shown from Maxwell's equations):

$$\vec{E} = E_0 \hat{\eta} e^{i \left(\vec{k} \cdot \vec{r} - \omega t\right)}$$
$$\vec{B} = \frac{1}{v} \hat{k} \times \vec{E},$$
(2)

where v = c/n is the phase velocity of light in a medium and $\hat{\eta}$ is the direction of the light's electric field. The light electric field undergoes a phase shift of π upon relection (as can be deduced from the boundary conditions), but for circularly polarized light the direction of rotation (clockwise or counter-clockwise) of the electric field with respect to a fixed coordinate system is preserved. However, we are now viewing it from the opposite direction (since \vec{k} changed sign). Therefore the handedness of polarization has changed upon reflection:

$$\begin{bmatrix} E'_x \\ E'_y \end{bmatrix} = \frac{E_0}{\sqrt{2}} \begin{bmatrix} 1 \\ i \end{bmatrix}$$
(3)

This result can also be arrived at using Fowles's reflection matrix (page 52). The beam now passes back through the quarter waveplate, but now the wave sees the fast-axis oriented at $+45^{\circ}$. So we find that:

$$\begin{bmatrix} E_x''\\ E_y'' \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & i\\ i & 1 \end{bmatrix} \cdot \frac{E_0}{\sqrt{2}} \begin{bmatrix} 1\\ i \end{bmatrix} = -iE_0 \begin{bmatrix} 0\\ 1 \end{bmatrix}$$
(4)

In other words the resultant light is linearly polarized in the \hat{y} direction.

Problem 2

First let's derive Fowles' result regarding the acceptance angle α for a fiber-optic cable (pages 46-47).

 n_2

ß

 n_2

At the first phase transition as the light enters the fiber-optic cable, we have from Snell's law:

 $\sin \alpha = n_1 \sin \beta$. (5) We want $\theta = \pi/2 - \beta$ to be greater than or equal to the critical angle, $\sin^{-1} n$ for total internal reflectance, where n =

 n_2/n_1 . With a little

Figure 1

trigonometry it can be shown that for these conditions,

 α

$$\sin\beta = \frac{\sqrt{n_1^2 - n_2^2}}{n_1}.$$
 (6)

Combining Eqs. (5) and (6) yields:

$$\sin \alpha = \sqrt{n_1^2 - n_2^2},\tag{7}$$

which proves Fowles's assertion.

The next step is to compute the solid angle of light accepted by the fiber-optic cable, given by:

$$\Delta\Omega = \int_0^{2\pi} \int_0^\alpha \sin\theta d\theta d\phi = 2\pi (1 - \cos\alpha). \tag{8}$$

(9)

Divided by the total solid angle (4π) , this yields the fraction T of the total light where E_r , E_i , E_t are the reflected, incident and transmitted electric field amplitransmitted by the core to the end of the cable:

$$T = \frac{(1 - \cos \alpha)}{2}.$$

Problem 3

A vector field $\mathbf{F}(\vec{r})$ is equal to the curl of a vector potential $\mathbf{A}(\vec{r})$, so we know that the divergence of $\mathbf{F}(\vec{r})$ is zero:

$$\nabla \cdot \mathbf{F}(\vec{r}) = \nabla \cdot (\nabla \times \mathbf{A}(\vec{r})) = 0.$$
(10)

Then we know that:

$$\int \nabla \cdot \mathbf{F}(\vec{r}) dV = \oint \mathbf{F}(\vec{r}) \cdot d\vec{A} = 0$$
(11)

Choose a volume of vanishing thickness $\vec{\delta}$ about a surface of area A (where $\vec{\delta}$ is always normal to the surface), then from Eq. (11) we have that:

$$\mathbf{F}_{\perp}\left(\vec{r}+\vec{\delta}\right)A - \mathbf{F}_{\perp}(\vec{r})A + O(\delta) = 0 \tag{12}$$

where $O(\delta)$ indicates a term of order δ , which arises from some finite amount of "flux" of $\mathbf{F}(\vec{r})$ out the sides of the volume.

The condition for continuity of $\mathbf{F}_{\perp}(\vec{r})$ is that for each $\epsilon > 0$, there exists a $\delta > 0$ such that $|\mathbf{F}_{\perp}(\vec{r}+\vec{\delta})-\mathbf{F}_{\perp}(\vec{r})| < \epsilon$. From Eq. (12) we know that:

$$|\mathbf{F}_{\perp}\left(\vec{r}+\vec{\delta}\right)-\mathbf{F}_{\perp}(\vec{r})|=\frac{O(\delta)}{A}.$$
(13)

Given any $\epsilon > 0$, clearly we can choose δ to make:

$$\frac{O(\delta)}{A} < \epsilon. \tag{14}$$

Therefore $\mathbf{F}_{\perp}(\vec{r})$ is continuous.

Problem 4

From Strovink's treatment of reflection/refraction at a plane interface between insulators, we have for normal incidence:

$$\frac{E_r}{E_i} = \frac{Z_2 - Z_1}{Z_1 + Z_2}
\frac{E_t}{E_i} = \frac{2Z_2}{Z_1 + Z_2},$$
(15)

tudes, respectively, and

$$Z_{1,2} = \sqrt{\frac{\mu_{1,2}}{\epsilon_{1,2}}}.$$
 (16)

In particular, for the ferromagnetic material described, $Z_2 \rightarrow \infty$ while Z_1 is finite, so:

$$\frac{E_t}{E_i} = \frac{2Z_2}{Z_1 + Z_2} \to 2.$$
 (17)

Problem 5

(a)

Plane waves propagating in the $\pm z$ directions must satisfy Eqs. (15) at the interfaces (z = 0 and z = L). At either interface we have, since $Z_2 \to 0$,

$$\frac{E_t}{E_i} = \frac{2Z_2}{Z_1 + Z_2} \to 0.$$
(18)

Therefore **E** vanishes in the material, i.e. **E**=0 for z < 0 and z > L. So at the interfaces. E=0.

The magnetic fields of the plane waves propagating in the $\pm z$ directions between the materials must satisfy $\mathbf{E}_+ \times \mathbf{H}_+ = -\mathbf{E}_- \times \mathbf{H}_-$ (i.e. the Poynting vectors of right- and left-traveling waves must be oriented in opposite directions). So while the electric fields cancel $(\mathbf{E}_{+} = -\mathbf{E}_{-})$ at the interfaces the magnetic fields must add $(\mathbf{H}_{+} = \mathbf{H}_{-})!$ Also we have the boundary condition $\mathbf{H}_{\parallel} = \mathbf{H}_{\mu}$, so that if **H** is finite on one side of the interface, it must also exist on the other side. So there can be components of **H** everywhere.

Our requirements from part (a) set up a standing wave, where the components of **E** and **H** are π out of phase. The wave is time independent in order to assure that E=0 at the interfaces for all times t, so we can postulate:

$$\mathbf{E} = \vec{E_0} \sin kz,\tag{19}$$

which works so long as $k = N\pi/L$ where N is an integer. So we get the condition on angular frequency from $k = \omega/c$, which implies

$$\omega = \frac{N\pi c}{L}.$$
(20)

Problem 6

We have two regions as shown in Figure 2, with k_1 and k_2 in each (defined as in the problem, where they are dependent on the potential V and the particle's total energy U, which is conserved, U = T + V). In region 1 we have the wavefunctions:

$$Ae^{i(k_1x-\omega t)} + Be^{-i(k_1x+\omega t)},\tag{21}$$

and in region 2 we have a transmitted wavefunction:

$$Ce^{i(k_2x-\omega t)}.$$
(22)

Continuity of the wavefunctions across the boundary (x=0) demands: $\mathbf{1}$ V(x)A + B = C.(23) $\mathbf{U} = \mathbf{T} + \mathbf{V}$ Since $\frac{\partial \psi}{\partial x}$ is also continuous: $k_1(A-B) = k_2C.$ (24) ΔV Region 1 Region 2 Substituting Eq. (23) into (24), we get: $\frac{B}{A} = \frac{k_1 - k_2}{k_1 + k_2}$ (25)Figure 2 If we assume $n \propto k$, then we get the formula for normal reflection of an EM wave at a dielectric interface with $\mu = \mu_0$: ъ

$$\frac{B}{A} = \frac{n_1 - n_2}{n_1 + n_2} \tag{26}$$

Problem 7

Fowles 3.1



Figure 3) are given by the proportionality:

$$A \propto e^{ikr} + e^{ik(r+a\sin\theta)} + e^{ik(r+2a\sin\theta)}$$
(27)

or,

х

$$A \propto e^{ikr} \left(1 + e^{ika\sin\theta} + e^{2ika\sin\theta} \right) \tag{28}$$



The interference pattern is given by the norm square of the amplitude:

$$I(\theta) \propto |A|^2 \propto \left(1 + \cos(ka\sin\theta)\right)^2 \tag{29}$$

The pattern that you get when you plot this function depends on what value you choose for ka. Let's take a = 1 mm and $k = 12,000 \text{ mm}^{-1}$, then our pattern is shown in Figure 4 as a function of θ .

Problem 8

Fowles 3.6

Light passes through the gas cell twice, so the optical path difference d_{op} is given by:

$$d_{op} = c\Delta t = \frac{2l}{c/n} - \frac{2l}{c} = 2l(n-1)$$
(30)

n changes as the gas fills the cell, and since $I \propto 1 + \cos(2\pi d_{op}/\lambda)$, a new fringe appears every time $d_{op} = 1/2$. Thus the total number of fringes N is given by:

$$N = 2\frac{2l(n-1)}{\lambda} = \frac{4l(n-1)}{\lambda}.$$
(31)

Plugging in the suggested values gives us N = 203 fringes.