# Approaching the Chiral Limit with Dynamical Overlap Fermions

#### T. Kaneko for the JLQCD collaboration

<sup>1</sup>High Energy Accelerator Research Organization (KEK)

<sup>2</sup>Graduate University for Advanced Studies

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#### 1.1 introduction

- JLQCD: studying lattice QCD using computers at KEK
- this talk: algorithmic aspects of production run for  $N_f = 2$ 
  - lattice action / simulation parameters
  - our implementation of HMC
  - production run

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#### 2.1 lattice action

• guark action = overlap w/ std. Wilson kernel

$$D_{\rm ov} = \left(m_0 + \frac{m}{2}\right) + \left(m_0 - \frac{m}{2}\right) \gamma_5 \, \text{sgn}[H_{\rm w}(-m_0)], \quad m_0 = 1.6$$

std. Wilson kernel  $H_W \Rightarrow$  (near-)zero modes of  $H_W$ 

- gauge action = |wasaki| action  $\leftarrow$  low mode density, locality
- extra-fields  $\Rightarrow$  to suppress (near-)zero modes Vranas, 2000; RBC, 2002 (DWF); JLQCD, 2006 (ovr)
  - Wilson fermion ⇒ suppress zero modes
  - twisted mass ghost  $\Rightarrow$  suppress effects of higher modes

Boltzmann weight  $\propto \frac{\det[H_W(-m_0)^2]}{\det[H_W(-m_0)^2 + \mu^2]}$ 

• extra-fields  $\Rightarrow$  do NOT change continuum limit

lattice action simulation parameters

#### 2.2 simulation parameters

- $N_f = 2 \text{ QCD}$
- Iwasaki gauge + overlap quark + extra-Wilson ( $\mu = 0.2$ )
- $\beta = 2.30 \Rightarrow a \approx 0.125 \text{ fm}$
- $16^3 \times 32$  lattice  $\Rightarrow L \simeq 2$  fm
- 6 sea quark masses  $\in [m_{s, phys}/6, m_{s, phys}]$  $m_{sea} = 0.015, 0.025, 0.035, 0.050, 0.070.0.100$
- focus on Q = 0 sector
- test runs (500-1000 traj.)

 $(\beta,\mu) = (2.30,0.2), (2.45,0.0), (2.50,0.2), (2.60,0.0)$ 

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- HMC w/ dynamical overlap quarks on BG/L
  - mult  $D_{\rm W}$  : depends on machine spec.
  - mult  $D_{ov}$ : treatment of sgn[ $H_W$ ]
  - overlap solver : choice of algorithm, 4D or 5D
  - HMC : Hasenbusch precond., multiple time scale
- multiplication of  $D_W \Rightarrow$  assembler code by IBM on BG/L
  - double FPU instruction of PowerPC 440D double pipelines enable complex number add/mult
  - use low-level communication API overlap computation/communication

 $\Rightarrow$   $\sim$  3 times faster than our Fortran code

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## 3.2 multiplication of $D_{ov}$

- multiplication of  $D_{ov} \ni \operatorname{sgn}[H_W]$ 
  - $\sigma[H_W] \Rightarrow [\lambda_{\min}, \lambda_{thrs}] \cup [\lambda_{thrs}, \lambda_{max}], \quad \lambda_{thrs} = 0.045$
  - low mode preconditioning
    eigenmodes w/ λ ∈ [λ<sub>min</sub>, λ<sub>thrs</sub>] ⇒ projected out

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• Zolotarev approx. of  $\text{sgn}[H_W]$  for  $\lambda \in [\lambda_{\text{thrs}}, \lambda_{\text{max}}]$  $N = 10 \Rightarrow \text{accuracy of } |1 - \text{sgn}H_W^2| \sim 10^{-7}$ 

example of  $\lambda[H_W]$  (test runs @  $a \sim 0.1 \,\text{fm}, m_{\text{sea}} \sim m_{\text{s,phys}}$ )



w/o extra-Wilson



multiplication of  $D_{\rm W}$  and  $D_{\rm ov}$  overlap solver HMC

#### 3.3 4D overlap solver

#### inner loop:

• partial fraction form

$$\operatorname{sgn}[H_{\mathsf{W}}] \quad \ni \quad \sum_{l=1}^{N_{\mathsf{p}}} \frac{b_l}{H_{\mathsf{W}}^2 + c_{2l-1}}$$

outer loop:

- relaxed CG (Cundy et al., 2004)
  - $D_{\rm ov}^{\dagger} D_{\rm ov} \Rightarrow \mathbf{CG}$
  - $\bullet$   $\times$  2 faster than unrelaxed CG

residual  $|D_{ov}^{\dagger} D_{ov} x - b|$ vs # of  $D_{W}$  mult ( $m_{sea} = 0.015$ )



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#### 3.3 5D overlap solver

Boriçi, 2004; Edwards et al.,2005

•  $M_5 = ($ Schur decomposition $) \Rightarrow \gamma_5 D_{ov} = H_{ov}$  as Schur complement



algorithm overlap solver HMC

#### 3.3 5D overlap solver

•  $x = D_{ov}^{-1}b$  from 5D linear equation  $M_5 \begin{pmatrix} \chi \\ x \end{pmatrix} = \begin{pmatrix} 0 \\ b \end{pmatrix},$ 

- even-odd precond.: implemented
- Iow-mode precond.: not yet...

 $\Rightarrow \text{ need small } x_{\min} \text{ and large } N_{p}$  $\Leftrightarrow \text{CPU time } \propto N_{p}$ 

•  $\sim$  4 times faster than 4D CG



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multiplication of  $D_{\rm W}$  and  $D_{\rm ov}$ overlap solver HMC

## 3.4 HMC w/ 4D solver

Hasenbusch preconditioning (Hasenbusch, 2001)

$$det[D_{ov}(m)^{2}] = det[D_{ov}(m')^{2}] det\left[\frac{D_{ov}(m)^{2}}{D_{ov}(m')^{2}}\right] = "PF1" \cdot "PF2"$$

• 
$$m' = 0.2$$
 ( $m_{sea} = 0.015, 0.025$ ), 0.4 ( $m_{sea} = 0.035 - 0.100$ )

#### force (ave,max) at $m_{sea} = 0.015$

CPU time for force calc (512nodes)





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algorithm

multiplication of  $D_{\rm W}$  and  $D_{\rm ov}$  overlap solver HMC

## 3.4 HMC w/ 4D solver

- multiple time scale integration
  - au=0.5

3 nested loops:

PF2 :	outer-most loop :	N <sub>MD</sub> times / traj.
PF1 :	intermediate :	$N_{\sf MD} {R_{\sf PF}}$
gauge,ex-Wilson :	inner-most :	$N_{\sf MD}R_{\sf PF}{f R_{\sf G}}$

$m_{sea}$	$N_{\rm MD}$	$R_{PF}$	$R_{G}$	m'	$P_{HMC}$
0.015	9	4	5	0.2	0.89
0.025	8	4	5	0.2	0.90
0.035	6	5	6	0.4	0.74
0.050	6	5	6	0.4	0.79
0.070	5	5	6	0.4	0.81
0.100	5	5	6	0.4	0.85

algorithm multiplication of D<sub>W</sub> overlap solver HMC

## 3.5 HMC w/ 5D solver

• Hasenbusch precond. + multiple time scale

$$\det[D_{\mathsf{ov}}(m)^2] = \det[D_{\mathsf{ov},\mathsf{5D}}(m')^2] \det\left[\frac{D_{\mathsf{ov},\mathsf{5D}}(m)^2}{D_{\mathsf{ov},\mathsf{5D}}(m')^2}\right] \det\left[\frac{D_{\mathsf{ov}}(m)^2}{D_{\mathsf{ov},\mathsf{5D}}(m')^2}\right]$$

= "PF1" · "PF2" · "noisy Metropolis test"

- sufficiently high " $N_s$ " to achieve reasonable  $P_{\rm HMC}$
- factor of 2-3 faster than HMC w/ 4D solver

$m_{\sf sea}$	$N_{MD}$	$R_{PF}$	$R_{G}$	m'	$P_{HMC}$
0.015	13	6	8	0.2	0.68
0.025	10	6	8	0.2	0.82
0.035	10	6	8	0.4	0.87
0.050	9	6	8	0.4	0.87
0.070	8	6	8	0.4	0.90
0.100	7	6	8	0.4	0.91

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algorithm

multiplication of  $D_{\rm W}$  and  $D_{\rm ov}$  overlap solver HMC

## 3.6 reflection / refraction

- extra-Wilson fermion
  - $\Rightarrow$  suppress zero-modes of  $H_W$
  - ⇒ switch off reflection/refraction step
    - reflection/refraction is not rare event!
      - (at a = 0.11 fm w/o extra-Wilson)
  - $\Rightarrow$  factor of  $\sim$  3 faster





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#### 4.1 production run

#### 10,000 traj. (× $\tau$ = 0.5) have been accumulated

$m_{\sf sea}$	$N_{MD}$	$R_{PF}$	$R_{G}$	m'	traj.	$P_{HMC}$	$M_{\rm PS}/M_{\rm V}$
0.015	9	4	5	0.2	2800	0.89	0.34
0.025	8	4	5	0.2	5200	0.90	0.40
0.035	6	5	6	0.4	4600	0.74	0.46
0.050	6	5	6	0.4	4800	0.79	0.54
0.070	5	5	6	0.4	4500	0.81	0.60
0.100	5	5	6	0.4	4600	0.85	0.67
$m_{\rm sea}$	$N_{\rm MD}$	$R_{PF}$	$R_{G}$	m'	traj	$P_{HMC}$	$M_{\rm PS}/M_{\rm V}$
m <sub>sea</sub>	N <sub>MD</sub> 13	<i>R</i> <sub>РF</sub>	<i>R</i> G	<i>m'</i> 0.2	traj 7200	<i>Р</i> <sub>НМС</sub> 0.68	M <sub>PS</sub> /M <sub>V</sub>
m <sub>sea</sub> 0.015 0.025	N <sub>MD</sub> 13 10	<i>R</i> <sub>РF</sub> 6 6	R <sub>G</sub> 8 8	<i>m'</i> 0.2 0.2	traj 7200 4800	Р <sub>НМС</sub> 0.68 0.82	M <sub>PS</sub> /M <sub>V</sub> 0.34 0.40
m <sub>sea</sub> 0.015 0.025 0.035	N <sub>MD</sub> 13 10 10	R <sub>PF</sub> 6 6 6	R <sub>G</sub> 8 8 8	<i>m'</i> 0.2 0.2 0.4	traj 7200 4800 5400	<i>Р</i> <sub>НМС</sub> 0.68 0.82 0.87	M <sub>PS</sub> /M <sub>V</sub> 0.34 0.40 0.46
<i>m</i> <sub>sea</sub> 0.015 0.025 0.035 0.050	N <sub>MD</sub> 13 10 10 9	R <sub>PF</sub> 6 6 6 6	R <sub>G</sub> 8 8 8 8 8	m' 0.2 0.2 0.4 0.4	traj 7200 4800 5400 5200	<i>Р</i> <sub>НМС</sub> 0.68 0.82 0.87 0.87	M <sub>PS</sub> /M <sub>V</sub> 0.34 0.40 0.46 0.54
<i>m</i> <sub>sea</sub> 0.015 0.025 0.035 0.050 0.070	N <sub>MD</sub> 13 10 10 9 8	R <sub>PF</sub> 6 6 6 6 6	R <sub>G</sub> 8 8 8 8 8 8	m' 0.2 0.2 0.4 0.4 0.4	traj 7200 4800 5400 5200 5500	<i>Р</i> <sub>НМС</sub> 0.68 0.82 0.87 0.87 0.90	<i>M</i> <sub>PS</sub> / <i>M</i> <sub>V</sub> 0.34 0.40 0.46 0.54 0.60

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## 4.2 basic properties of HMC

area preserving



- a few spikes per *O*(10,000) trajectories: *P*<sub>spike</sub> ≤ 0.03 %
- $\langle \exp[-\Delta H] \rangle = 1$  in all runs
- o does not need "replay" trick

#### reversibility



- $\Delta U = \sqrt{\sum |U(\tau+1-1) U(\tau)|^2 / N_{dof}}$
- $\epsilon$  : stop. cond. for MS/overlap solver
  - $\Delta U \lesssim 10^{-8}$ : comparable to previous simulations

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## 4.3 effects of low modes of $D_{ov}$



- as approaching to ε-regime cost is governed by λ<sub>ov,min</sub> rather than m<sub>sea</sub>
- too small volume?

 $M_{\rm PS} L \gtrsim 2.7$ ,  $\exp[-M_{\rm PS} L] \Rightarrow \lesssim 1-2\%$  effects on  $M_{\rm PS}$ larger L for  $m_{\rm sea} \ll 0.015$ 

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#### • mild $m_{\text{sea}}$ dep. of $N_{\text{inv,H}}$ and $N_{\text{MD}}$ $\downarrow \downarrow$ CPU time $\propto 1/m_{\text{sea}}^{-\alpha}$ , w/ $\alpha \sim 0.53$ $\uparrow$ naive expectation: $N_{\text{inv}} \propto 1/m_{\text{sea}}$ , $N_{\text{MD}} \propto 1/m_{\text{sea}}$

#### CPU time [min] on BG/L×10 racks

	HMC	-4D	HMC-5D		
$m_{\rm sea}$	traj.	time	traj.	time	
0.015	2800	6.1	7200	2.6	
0.025	5200	4.7	4800	2.2	
0.035	4600	3.0	5400	1.5	
0.050	4800	2.6	5200	1.3	
0.070	4500	2.1	5500	1.1	
0.100	4600	2.0	5400	1.0	

# BG/L × 10 racks × 1 month ⇒ 4000 traj. at all m<sub>sea</sub>

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#### 4.4 autocorrelation



- plaquette: local
  - $\Rightarrow$  small  $m_q$  dependence
- N<sub>inv,H</sub>: long range
  - $\Rightarrow$  rapid increase as  $m_q \rightarrow 0$  $\Rightarrow$  may need large statistics



#### 5. summary

- algorithm for JLQCD's dynamical overlap simulations
  - Hasenbusch precond. + multiple time scale MD + · · ·
  - 5D solver
  - extra-Wilson fermion to suppress (near-)zero modes
    - $\Rightarrow$  cheap approx. for sgn[ $H_W$ ],  $\Rightarrow$  turn off reflection/refraction
- effects due to fixed (global) topology (R.Brower et al., 2003)
  - topological properties  $(\chi_t,...) \Rightarrow$  talks by T-W.Chiu, T.Onogi
  - Q-dependence of observables  $\leftarrow$  simulations w/  $Q \neq 0$
  - suitable for  $\epsilon$ -regime  $\Rightarrow$  talk by S.Hashimoto
- on-going/future plans
  - spectrum/matix elements ⇒ talks by J.Noaki, N.Yamada
  - simulations of  $N_f = 3 \text{ QCD}$
  - extend to larger volumes

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