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## Research Article

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# Monomial codes seen as invariant subspaces 

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#### Abstract

It is well known that cyclic codes are very useful because of their applications, since they are not computationally expensive and encoding can be easily implemented. The relationship between cyclic codes and invariant subspaces is also well known. In this paper a generalization of this relationship is presented between monomial codes over a finite field $\mathbb{F}$ and hyperinvariant subspaces of $\mathbb{F}^{n}$ under an appropriate linear transformation. Using techniques of Linear Algebra it is possible to deduce certain properties for this particular type of codes, generalizing known results on cyclic codes.


Keywords: Monomial codes, Invariant subspaces
MSC: 94B15, 15B33

## 1 Introduction

It is well known that error correcting codes and cryptographic systems have conflicting objectives, since the first are codes protecting the information of occasional errors due to handling, that is, those searching to solve the difficulties posed by unreliability of the channel, but cryptosystems, also called secret codes, try to ensure its confidentiality, integrity and security. However, they also have complementary objectives. The difficulty for decoding error correcting codes has been used to build cryptographic systems from these codes. Among these systems there is the well known public key McEliece system. In this system the private key of each user is the generator matrix $G$ of a linear code $C$ over a finite field $\mathbb{F}_{q}$ joint with a decoding algorithm. The matrix $G$ is hidden by a permutation matrix thus obtaining the public key, ([1], [2], [3]).

Alongside the use of cryptography to protect communications, there is the technique known as "steganography"whose use is increasing and which consists in the concealment of information. It is used in order to protect information in an anodyne numerical support and it is the support that is sent over a public transmission channel. These techniques of concealment of information are based on cyclic codes over the ring $\mathbb{Z}_{4}$, ([4], [5]). Possibly they can improve the efficiency in dissimulation using a generalization of cyclic codes such as the monomial codes.

A first generalization of cyclic codes were constacyclic codes, introduced by E. R. Berlekamp in [6]. Monomial codes are a broader generalization. Linear algebra as a tool to study such codes was introduced in [7]. Monomial codes are widely used because they can be encoded with shift registers.

Let $p$ be a prime number, $q=p^{k}$ for some $k \geq 1$. A monomial $q$-ary code of length $n$ can be defined through a $n \times n$ generator-matrix with the property that each row (except the last one) $\left(c_{1}, c_{2}, \ldots, c_{n}\right), c_{i} \in G F(q)$ defines the row as $\left(a_{n} c_{n}, a_{1} c_{1}, a_{2} c_{2}, \ldots, a_{n-1} c_{n-1}\right)$, where $a_{1}, \ldots, a_{n}$ are certain fixed elements of $G F(q) \backslash\{0\}$. Cyclic codes $\left(a_{1}=\ldots=a_{n}=1\right)$ and constacyclic codes $\left(a_{1}=\ldots=a_{n-1}=1\right)$ are special subclasses of monomial codes of $G F(q)^{n}$. Monomial codes can also be described in terms of linear algebra, which constitutes our starting

[^0]point that will be the characteristic polynomial of the endomorphism of $G F(q)^{n}$ whose matrix in the canonical basis is the one representing the monomial code.

Recall that, given an endomorphism $\varphi$ of a $\mathbb{F}$-vector space $E$, a $\varphi$-invariant subspace $V \subset E$ is hyperinvariant when it is invariant under all linear transformations commuting with $\varphi$.

## 2 Invariant subspaces of monomial matrices

Let $p$ be a prime number, $q=p^{k}$ for some $k \geq 1$ and $\mathbb{F}=G F(q)$ and $\mathbb{F}^{n}$ thee $n$-dimensional $\mathbb{F}$-vector space.
Let $\bar{a}=\left(a_{1}, \ldots a_{n}\right)$ be a set of $n$ parameters of $\mathbb{F}$ and consider the following linear map

$$
\begin{align*}
\varphi_{\bar{a}}: \mathbb{F}^{n} & \longrightarrow \mathbb{F}^{n} \\
\left(x_{1}, \ldots, x_{n}\right) & \longrightarrow\left(a_{n} x_{n}, a_{1} x_{1}, \ldots, a_{n-1} x_{n-1}\right) \tag{1}
\end{align*}
$$

whose associated matrix with respect to the canonical basis $\left\{e_{1}=(1,0, \ldots, 0), e_{2}=(0,1, \ldots, 0), e_{n}=\right.$ $(0,0, \ldots, 1)\}$ is:

$$
A_{\bar{a}}=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & a_{n}  \tag{2}\\
a_{1} & 0 & \ldots & 0 & 0 \\
0 & a_{2} & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & a_{n-1} & 0
\end{array}\right) .
$$

This matrix is called a monomial matrix. We note that this matrix can be written as the product of a diagonal matrix $\operatorname{diag}\left(a_{n}, a_{1}, \ldots, a_{n-1}\right)$ and the permutation matrix

$$
\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & 1 \\
1 & 0 & \ldots & 0 & 0 \\
0 & 1 & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & 1 & 0
\end{array}\right) .
$$

## Properties

This matrix verifies:

1) $A_{a}^{n}=a_{1} \ldots a_{n} I_{n}$
2) if $\prod_{i=1}^{n} a_{i} \neq 0$ then $A_{\bar{a}}^{-1}=\frac{1}{\prod_{i=1}^{n} a_{i}} A_{\bar{a}}^{n-1}=A_{\overline{\bar{a}}}^{t}$, where $\overline{\bar{a}}=\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n}}\right)$.
3) its characteristic polynomial is $p_{a}(s)=\operatorname{det}\left(A_{\bar{a}}-s I_{n}\right)=(-1)^{n}\left(s^{n}-\prod_{i=1}^{n} a_{i}\right)$.

Proposition 2.1. Suppose that $a=\prod_{i=1}^{n} a_{i} \neq 0$. Then, the matrix (2) is equivalent under similarity to

$$
A_{a}=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & a \\
1 & 0 & \ldots & 0 & 0 \\
0 & 1 & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & 1 & 0
\end{array}\right)
$$

Proof. It is easy to prove that

$$
A_{\bar{a}} S=S A_{a}
$$

with

$$
=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & \prod_{i=1}^{n} a_{i} \\
a_{1} & 0 & \ldots & 0 & 0 \\
0 & a_{1} a_{2} & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & \prod_{i=1}^{n-1} a_{i} & 0
\end{array}\right)
$$

In this section we prove that a $\varphi_{\bar{a}}$-invariant subspaces are also $\varphi_{\bar{a}}$-hyperinvariants; that is to say, invariant under all linear maps commuting with $\varphi_{\bar{a}}$, (see [8] and [9] for more information about these subspaces).

We need to know the centralizer of $A_{\bar{a}}$. To do that, we first calculate the centralizer of the matrix $A_{a}$.
Proposition 2.2 ([7). ] The centralizer $\mathcal{C}\left(A_{a}\right)$ is the set of the matrices $X_{a}$ in the form:

$$
X_{a}=\left(\begin{array}{ccccccc}
x_{n} & a x_{1} & a x_{2} & a x_{3} & \ldots & a x_{n-2} & a x_{n-1} \\
x_{n-1} & x_{n} & a x_{1} & a b x_{2} & \ldots & a x_{n-3} & a x_{n-2} \\
\vdots & & \ddots & \ddots & & & \\
\vdots & & & \ddots & \ddots & & \\
x_{3} & x_{4} & x_{5} & x_{6} & \ldots & a x_{1} & a x_{2} \\
x_{2} & x_{3} & x_{4} & x_{5} & \ldots & x_{n} & a x_{1} \\
x_{1} & x_{2} & x_{3} & x_{4} & \ldots & x_{n-1} & x_{n}
\end{array}\right)
$$

Proposition 2.3. The centralizer $\mathcal{C}\left(A_{\bar{a}}\right)$ of $A_{\bar{a}}$ is the set of the matrices $Y_{\bar{a}}=S X_{a} S^{-1}$, if $A_{\bar{a}} S=S A_{a}$.
Proof. Proposition 2.2, we have $X_{a} A_{a}=A_{a} X_{a}$. Then, $S X_{a} S^{-1} A_{\bar{a}}=A_{\bar{a}} S X_{a} S^{-1}$.
Note that if $v=\left(v_{1}, \ldots, v_{n}\right)$ is an eigenvector of $A_{\bar{a}}$, then:

$$
\begin{align*}
a_{n} v_{n} & =\lambda v_{1} \\
a_{1} v_{1} & =\lambda v_{2} \\
a_{2} v_{2} & =\lambda v_{3}  \tag{3}\\
\vdots & \\
a_{n-2} v_{n-2} & =\lambda v_{n-1} \\
a_{n-1} v_{n-1} & =\lambda v_{n}
\end{align*}
$$

In particular, we have that

$$
\begin{equation*}
v=\left(\frac{\lambda^{n-1}}{a_{1} \ldots a_{n-1}}, \frac{\lambda^{n-2}}{a_{2} \ldots a_{n-1}}, \ldots, \frac{\lambda}{a_{n-1}}, 1\right) \tag{4}
\end{equation*}
$$

and the following Proposition holds.
Proposition 2.4. Let $\lambda \in G F(q)^{*}$ be an element such that $\lambda^{n}=\prod_{i=1}^{n} a_{i}$. Then, the one-dimensional subspace $[v]$ spanned by the vector $v$ given in (4) is an hyperinvariant subspace.

Proof.

$$
A_{\bar{a}} v=\lambda v
$$

and given any $Y_{\bar{a}} \in \mathcal{C}\left(A_{\bar{a}}\right)$, then

$$
\begin{aligned}
& Y_{\bar{a}} v= \\
& S\left(x_{n} I+x_{n-1} A_{\bar{a}}+x_{n-2} A_{\bar{a}}^{2}+\ldots+x_{1} A_{\bar{a}}^{n-1}\right) S^{-1} v \\
& =x_{n} v+x_{n-1} S A_{a} S^{-1} v+x_{n-2} S A_{a}^{2} S^{-1} v+\ldots+ \\
& +x_{2} S A_{a}^{n-2} S^{-1} v+x_{1} S A_{\bar{a}}^{n-1} S^{-1} v \\
& =x_{n} v+x_{n-1} \lambda v+x_{n-2} \lambda^{2} v+\ldots+x_{1} \lambda^{n-1} v \\
& =\alpha v
\end{aligned}
$$

with $\alpha=x_{n}+x_{n-1} \lambda+x_{2} \lambda^{2}+\ldots+x_{2} \lambda^{n-2}+x_{1} \lambda^{n-1} \in \mathbb{F}$.
Proposition 2.5. Let $F$ be an invariant subspace of $A_{\bar{a}}$. Then, $F$ is hyperinvariant.
Proof. It suffices to observe that, for all $Y_{\bar{a}} \in \mathcal{C}\left(A_{\bar{a}}\right)$,

$$
S X_{a} S^{-1}=x_{n} I+x_{n-1} A_{\bar{a}}+x_{n-2} A_{\bar{a}}^{2}+\ldots+x_{1} A_{\bar{a}}^{n-1}
$$

Therefore, in this case the lattice of invariant subspaces coincides with the lattice of hyperinvariant subspaces:

$$
\operatorname{Hinv}\left(A_{\bar{a}}\right)=\operatorname{Inv}\left(A_{\bar{a}}\right)
$$

Definition 2.6. $i)$ Let $u=\left(u_{1}, \ldots, u_{n}\right)$ and $v=\left(v_{1}, \ldots, v_{n}\right)$ be two vectors in $\mathbb{F}^{n}$. We define an inner product over $\mathbb{F}$ as follows:

$$
<u, v>=u_{1} v_{1}+\ldots+u_{n} v_{n}
$$

ii) Two vectors $u$, $v$ in $\mathbb{F}^{n}$ are said to be orthogonal if $\langle u, v\rangle=0$.
iii) Let $F$ be a subspace of $\mathbb{F}^{n}$. The dual subspace of $F\left(\right.$ denoted by $\left.F^{\perp}\right)$ is

$$
F^{\perp}=\left\{v \in \mathbb{F}^{n} \mid \forall u \in F,<u, v>=0\right\} .
$$

Proposition 2.7. Let $F$ be an invariant subspace of $A_{\bar{a}}$. Then $F^{\perp}$ is an invariant subspace of $A_{\overline{\bar{a}}}^{-1}$.
Proof. Let $v \in F^{\perp}$. For all $u \in F$ (consequently, $A_{\bar{a}} u \in F$ ) we have

$$
\begin{aligned}
& 0=<A_{\bar{a}} u, v>=<u, A_{\bar{a}}^{t} v>=<u, \prod_{i=1}^{n} a_{i} A_{\overline{\bar{a}}}^{n-1} v> \\
& =<u, A_{\overline{\bar{a}}}^{-1} v>
\end{aligned}
$$

Thus $A_{\overline{\bar{a}}}^{-1} v \in F^{\perp}$.
Let $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$ be the algebraic extension of $\mathbb{F}=G F(q)$ and let $\lambda_{1}, \ldots, \lambda_{n}$ be the eigenvalues of $\varphi_{\bar{a}}$ with $\lambda_{i}=\sqrt[n]{\prod_{i=1}^{n}} \lambda^{i}, i=1, \ldots, n$, where $\lambda$ is a primitive $n^{\text {th }}$ root of unity and $\sqrt[n]{\prod_{i=1}^{n} a_{i}}$ is a fixed, but otherwise arbitrary zero of the polynomial $s^{n}-\prod_{i=1}^{n} a_{i}$, where $0 \neq \prod_{i=1}^{n} a_{i} \in \mathbb{F}$.

Let $v_{i}, i=1, \ldots, n$ be the respective eigenvectors. More particularly we have

$$
A_{\bar{a}} v_{i}=\lambda_{i} v_{i}, v_{i}=\left(\frac{\lambda_{i}^{n-1}}{a_{1} \ldots a_{n-1}}, \frac{\lambda_{i}^{n-2}}{a_{2} \ldots a_{n-1}}, \ldots, \frac{\lambda_{i}}{a_{n-1}}, 1\right)
$$

$i=1, \ldots, n$,
where $A_{\bar{a}}$ is the matrix associated to

$$
\varphi_{\bar{a}}: \mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]^{n} \longrightarrow \mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]^{n}
$$

(defined as in 2).
Let us consider the basis $v=\left(v_{1}, \ldots, v_{n}\right)$ of eigenvectors of $\varphi_{\bar{a}}$. Applying basis change to $A_{\bar{a}}$, we obtain the following diagonal matrix

$$
D_{\bar{a}}=\left(\begin{array}{cccc}
\lambda_{1} & 0 & \ldots & 0 \\
0 & \lambda_{2} & \ldots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \ldots & \lambda_{n}
\end{array}\right)=S^{-1} A S
$$

and taking into account (4) we have

$$
S=\left(\begin{array}{cccc}
\frac{\lambda_{1}^{n-1}}{a_{1} \ldots a_{n-1}} & \frac{\lambda_{2}^{n-1}}{a_{1} \ldots a_{n}-1} & \cdots & \frac{\lambda_{n}^{n-1}}{a_{1} \ldots a_{n-1}} \\
\frac{\lambda_{1}^{n-2}}{a_{2} \ldots a_{n-1}} & \frac{\lambda_{2}^{n-2}}{a_{2} \ldots a_{n-1}} & \cdots & \frac{\lambda_{n}^{n-2}}{a_{2} \ldots a_{n-1}} \\
\vdots & \vdots & & \vdots \\
\frac{\lambda_{1}}{a_{n-1}} & \frac{\lambda_{2}}{a_{n-1}} & \cdots & \frac{\lambda_{n}}{a_{n-1}} \\
1 & 1 & \cdots & 1
\end{array}\right)
$$

We define now the following vectors:

$$
\begin{align*}
& u_{i}=\left(\lambda_{i} a_{1} \ldots a_{n-1}, \lambda_{i}^{2} a_{2} \ldots a_{n-1}, \ldots, \lambda^{n-1} a_{n-1}, \lambda_{i}^{n}\right)  \tag{5}\\
& 1 \leq i \leq n
\end{align*}
$$

Proposition 2.8. The set of vectors defined in (5) verify the following relationship.

$$
<u_{i}, v_{j}>=\left\{\begin{array}{lr}
a_{1} \ldots a_{n} n & \text { if } i=j \\
0 & \text { if } i \neq j
\end{array}\right.
$$

Proof.

$$
\begin{aligned}
& <u_{i}, v_{j}>=\sum_{\ell=1}^{n} \lambda_{i}^{\ell} \lambda_{j}^{n-\ell}=\sum_{\ell=1}^{n} \frac{\lambda_{i}^{\ell} \lambda_{j}^{n-\ell} \lambda_{j}^{\ell}}{\lambda_{j}^{\ell}}= \\
& \sum_{\ell=1}^{n}\left(\frac{\lambda_{i}}{\lambda_{j}}\right)^{\ell} \lambda_{j}^{n}=a_{1} \ldots a_{n} \sum_{\ell=1}^{n}\left(\frac{\lambda_{i}}{\lambda_{j}}\right)^{\ell}= \\
& \left\{\begin{array}{l}
a_{1} \ldots a_{n} \sum_{\ell=1}^{n} 1^{\ell}=a_{1} \ldots a_{n} n \text { if } i=j \\
a_{1} \ldots a_{n} \sum_{\ell=1}^{n}(\lambda)^{\ell}=0(\text { with } \lambda \text { a root of unit }) \text { if } i \neq j
\end{array}\right.
\end{aligned}
$$

From this Proposition the inverse matrix of the matrix $S$ can easily obtained.

## 3 Monomial codes as invariant subspaces

Definition 3.1. A code $C$ of length $n$ over the field $\mathbb{F}$ is called monomial with respect to $a_{1}, \ldots, a_{n}$, if whenever $c=\left(c_{1}, \ldots, c_{n}\right)$ belongs to $C$, then $s c=\left(a_{n} c_{n}, a_{1} c_{1}, \ldots, a_{n-1} c_{n-1}\right)$ is also in $C$.

The shift (the map $c \rightarrow s c$ ) can be represented in a matrix form

$$
\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & a_{n} \\
a_{1} & 0 & \ldots & 0 & 0 \\
0 & a_{2} & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & a_{n-1} & 0
\end{array}\right)\left(\begin{array}{c}
c_{1} \\
c_{2} \\
c_{3} \\
\vdots \\
c_{n}
\end{array}\right)=\left(\begin{array}{c}
a_{n} c_{n} \\
a_{1} c_{1} \\
a_{2} c_{2} \\
\vdots \\
a_{n-1} c_{n}
\end{array}\right)
$$

Note that this matrix is the matrix (2).
In the particular case where $a_{i}=1$, for all $i$, the code is a cyclic code and if $a_{1}=\ldots=a_{n-1}=1$ is a constacyclic code (see [10]).

Applying Proposition 2.1 the study can be reduced to the case of constacyclic codes. Nevertheless, we will not make use of this result, but directly consider monomial codes.

We are interested in the case where $a_{n} \neq a_{i}$ for some $i=2, \ldots, a_{n-1}$ and $\prod_{i=1}^{n} a_{i} \neq 0$. In particular, we need to consider $q>2$. As an immediate consequence of Definition 3.1 we have the following Proposition.

Proposition 3.2. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is monomial if, and only if, $C$ is an $A_{\bar{a}}$-invariant subspace of $\mathbb{F}^{n}$.

And after Proposition 2.5 we have the following result.
Proposition 3.3. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is monomial if, and only if, $C$ is an $A_{\bar{a}}$-hyperinvariant subspace of $\mathbb{F}^{n}$.

Suppose now that $(n, q)=1$ and $p_{\bar{a}}(t)=(-1)^{n}\left(t^{n}-\prod_{i=1}^{n} a_{i}\right)$ has no multiple roots and splits into distinct irreducible factors.

General Linear Algebra theory over finite fields yields the following statement.
Proposition 3.4. Let $C$ be a monomial code, and

$$
p_{\bar{a}}(s)=(-1)^{n} p_{\bar{a}_{1}}(s) \cdot \ldots \cdot p_{\bar{a}_{r}}(s)
$$

the decomposition of $p_{\bar{a}}(s)$ into irreducible factors. Then $C=\operatorname{Ker} p_{\bar{a}_{i_{1}}}\left(A_{\bar{a}}\right) \oplus \ldots \oplus \operatorname{Ker} p_{\bar{a}_{i_{s}}}\left(A_{\bar{a}}\right)=\operatorname{Ker} h\left(A_{\bar{a}}\right)$, $h(s)=p_{\bar{a}_{i_{1}}}(s): .: p_{\bar{a}_{i_{t}}}(s)$ for some minimal $A_{\bar{a}}$-invariant subspaces Ker $p_{\bar{a}_{i_{j}}}\left(A_{\bar{a}}\right)$ de $\mathbb{F}^{n}$.

Example 3.5. Consider the matrix $A_{\bar{a}}$ with $a_{n}=2, a_{1}=4, a_{2}=\ldots=a_{n-1}=1, n=8$ and $q=5$. Then $p(s)=p_{\bar{a}}(s)=s^{8}-1$. Factorizing $p(s)$ into irreducible factors over $\mathbb{F}=G F(5)$ we have $p_{\bar{a}}(s)=$ $p_{1}(s) p_{2}(s) p_{3}(s) p_{4}(s) p_{5}(s) p_{6}(s)=(s+1)(s+2)(s+3)(s+4)\left(s^{2}+2\right)\left(s^{2}+3\right)$. The factors $p_{i}(s)$ define minimal $A_{\bar{a}}$-invariant subspaces, $F_{i}=\operatorname{Ker} p_{i}\left(A_{\bar{a}}\right)$, for $i=1,2,3,4,5,6$.

Let us consider
$C=F_{1} \oplus F_{5}=\operatorname{Ker}\left(p_{1}\left(A_{\bar{a}}\right)\right) \oplus \operatorname{Ker}\left(p_{5}\left(A_{\bar{a}}\right)\right)$
$\operatorname{Ker}\left(A_{\bar{a}}^{3}+A_{\bar{a}}^{2}+2 A_{\bar{a}}+2 I\right)=$
$\left(\begin{array}{llllllll}2 & 0 & 0 & 0 & 0 & 1 & 3 & 3 \\ 2 & 2 & 0 & 0 & 0 & 0 & 3 & 4 \\ 2 & 4 & 2 & 0 & 0 & 0 & 0 & 3 \\ 4 & 4 & 4 & 2 & 0 & 0 & 0 & 0 \\ 0 & 3 & 4 & 4 & 2 & 0 & 0 & 0 \\ 0 & 0 & 3 & 4 & 4 & 2 & 0 & 0 \\ 0 & 0 & 0 & 3 & 4 & 4 & 2 & 0 \\ 0 & 0 & 0 & 0 & 3 & 4 & 4 & 2\end{array}\right)$

This is a monomial code, $C=\operatorname{Ker} h\left(A_{\bar{a}}\right)$ with $h(s)=p_{1}(s) p_{5}(s)=s^{3}+s^{2}+2 s+2$.
Example 3.6. With the notations as in the Example above,

$$
g(s)=\frac{P_{\bar{a}}(s)}{h(s)}=p_{2}(s) p_{3}(s) p_{4}(s) p_{6}(s)=s^{5}+9 s^{4}+29 s^{3}+53 s^{2}+78 s+72
$$

It is straightforward to check that

$$
\begin{aligned}
& \left(A_{\bar{a}}^{5}+9 A_{\bar{a}}^{4}+29 A_{\bar{a}}^{3}+53 A_{\bar{a}}^{2}+78 A_{\bar{a}}+72 I\right)\left(v_{1}\right)=0 \\
& \left(A_{\bar{a}}^{5}+9 A_{\bar{a}}^{4}+29 A_{\bar{a}}^{3}+53 A_{\bar{a}}^{2}+78 A_{\bar{a}}+72 I\right)\left(v_{2}\right)=0 \\
& \left(A_{\bar{a}}^{5}+9 A_{\bar{a}}^{4}+29 A_{\bar{a}}^{3}+53 A_{\bar{a}}^{2}+78 A_{\bar{a}}+72 I\right)\left(v_{3}\right)=0
\end{aligned}
$$

with

$$
v_{1}=(1,4,2,1,3,4,2,1), v_{2}=(1,0,4,0,2,0,1,0), v_{3}=(0,3,0,4,0,2,0,1)
$$

Corollary 3.7. Let $C$ be a monomial code. There exists $g(s)$ verifying $p_{\bar{a}}(s)=g(s) \cdot h(s)$ with $\operatorname{gcd}(g(s), h(s))=1$ such that $g\left(A_{\bar{a}}\right) c=0, \forall c \in C$.

Considering the inner product introduced in definition 2.6.
Proposition 3.8. Let $C$ be a monomial code with respect $a_{1}, \ldots, a_{n}$. Then, its dual code $C^{\perp}$ is a monomial code with respect $\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n}}$.

Proof. The statement follows from Proposition 2.7.
In the case $a_{1}=\ldots=a_{n}=1$ we obtain the well known result about cyclic codes.

Corollary 3.9. The dual of a cyclic code is a cyclic code.

## 4 Parity matrices of monomial codes

Let $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$ be the algebraic extension considered in Section 2.
Let $C$ be a monomial code and $g(s)$ as in corollary 3.7. Let us consider a basis $v=\left(v_{1}, \ldots, v_{n}\right)$ of eigenvectors of $\varphi_{\bar{a}}$.

In this basis, the matrix of $\varphi_{\bar{a}}$ is a diagonal matrix, which will be denoted by $D_{\bar{a}}$.

Since $D_{\bar{a}}$ is a diagonal matrix, the matrix $g\left(D_{\bar{a}}\right)$ is also diagonal and

$$
g\left(A_{\bar{a}}\right)=g\left(S D_{\bar{a}} S^{-1}\right)=S g\left(D_{\bar{a}}\right) S^{-1}
$$

Condition $g\left(A_{\bar{a}}\right) c=0$ is equivalent to $g\left(D_{\bar{a}}\right) c^{\prime}=0$ where $c^{\prime}=S^{-1} c$.
Without loss of generality we can assume that $\lambda_{1}, \ldots, \lambda_{n}$ are ordered in such a way that $g\left(\lambda_{i}\right)=0$, for all $1 \leq i \leq k$ and $g\left(\lambda_{i}\right)=\alpha_{i} \neq 0$, for all $k+1 \leq i \leq n$. With $h(s)$ as in corollary $3.7, h\left(\lambda_{i}\right) \neq 0$, for all $1 \leq i \leq k$ and $h\left(\lambda_{i}\right)=0$, for all $k+1 \leq i \leq n$. Given $c=\left(c_{1}, \ldots, c_{n}\right) \in C$ and $c^{\prime}=\left(c_{1}^{\prime}, \ldots, c_{n}^{\prime}\right)=s^{-1} c$ we have that $g\left(D_{\bar{a}}\right)=\left(0, \ldots, 0, \alpha_{k+1} c_{k+1}^{\prime}, \ldots, \alpha_{n} c_{n}^{\prime}\right)$. Equivalently:

Then we can deduce the following proposition.
Proposition 4.1. Let $u_{i_{j}}, 1 \leq j \leq r=n-k$ be a family of vectors as in (5) corresponding to $\lambda_{i_{j}}$, with $g\left(\lambda_{i_{j}}\right)=$ $\alpha_{i_{j}} \neq 0$. Then $c$ is a codeword of the monomial code $C$ if and only if

$$
u_{i_{j}} c=0, \text { for all } 1 \leq j \leq r
$$

As a consequence the matrix $A=\left(u_{i_{j}}\right) \in M_{(n-k) \times n}\left(\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]\right)$ is a parity matrix of the monomial code over the field $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$.

Example 4.2. Over $\mathbb{F}=G F(5)$ we consider a monomial code $C$ with $a_{n}=a_{1}=2, a_{2}=\ldots=a_{-1}=1$ and $n=4$ defined by $g(s)=s^{2}-2$. Over $\mathbb{F}[\sqrt{2}, 4 \sqrt{2}, \sqrt{3}, 4 \sqrt{3}]$, the polynomial $h(s)=s^{2}+2=(s-\sqrt{3})(s-4 \cdot \sqrt{3})$.

Then

$$
\left(\begin{array}{lllll}
\sqrt{3} \cdot 2 & 3 & 3 \cdot \sqrt{3} & 4 \\
3 \cdot \sqrt{3} & 3 & 2 \cdot \sqrt{3} & 4
\end{array}\right)
$$

is a parity matrix of the code $C$ over $\mathbb{F}[\sqrt{2}, 4 \sqrt{2}, \sqrt{3}, 4 \sqrt{3}]$.

## 5 Hamming distance of monomial codes

Remember that the Hamming weight (for short, weight) of a vector $v$ is the number of its nonzero entries and is denoted $w_{H}(v)$. We have $w_{H}(x)=d_{H}(x, 0)$. The minimum weight of a code C is the minimum nonzero weight among all codewords of $C$,

$$
w_{\min }(C)=\min _{0 \neq x \in C}\left(w_{H}(x)\right)
$$

Taking into account that $d_{H}(x, y)=d_{H}(x-z, y-z)$ for all $z$ and that in particular $d_{H}(x, y)=d_{H}(x-y, y-y)=$ $d_{H}(x-y, 0)$ we have that over a field, the Hamming distance is translation invariant and, in particular, for linear codes, the minimum weight is equal to the minimum distance.

We are going to obtain a bound for the minimum distance of two parametric monomial codes in a similar way to that presented by Roos in [11] for cyclic codes.

Let $\mathbb{F}$ be a finite field and

$$
A=\left(\begin{array}{l}
\mathbf{a}_{1} \ldots \mathbf{a}_{n}
\end{array}\right)=\left(\begin{array}{ccc}
a_{11} \ldots & \ldots & a_{n 1} \\
\vdots & & \vdots \\
a_{1 \ell} \ldots & \ldots & a_{n \ell}
\end{array}\right)
$$

Let $C$ be a linear code over $\mathbb{F}$ having $A$ as a parity matrix and $d_{H}(A)$ the minimum distance of $C$.
Remember that $d_{H}(A)=d$ if and only if every set of $d-1$ columns is linearly independent and some set of $d$ columns of $A$ is linearly dependent.

$$
\begin{aligned}
& \text { For any matrix } X=\left(\begin{array}{ccc}
x_{11} & \ldots & x_{1 n} \\
\vdots & & \vdots \\
x_{m 1} & \ldots & x_{m n}
\end{array}\right) \text { with nonzero columns } \mathbf{x}_{i} \in \mathbb{F}^{m} \text { for } 1 \leq i \leq n \text { we consider } \\
& \qquad A(X)=\left(\mathbf{x}_{1} \otimes \mathbf{a}_{1} \ldots \mathbf{x}_{n} \otimes \mathbf{a}_{n}\right)
\end{aligned}
$$

The following result is well known due to Roos ([12]).
Lemma 5.1. If $d_{H}(A) \geq 2$ and every $m \times\left(m+d_{H}(A)-2\right)$ submatrix of $X$ has full rank, then $d_{H}(A(X)) \geq$ $d_{H}(A)+m-1$.

Definition 5.2. Let $M=\left[\lambda_{i_{1}}, \ldots, \lambda_{i_{\ell}}\right]$ be a set of $\ell$ roots of $s^{n}-\prod_{i=1}^{n} a_{i}$ in $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$. We will say that $M$ is a consecutive set of length $\ell$, if there exists a primitive $n$-root of the unit $\lambda$ and an exponent $i$ such that $M=\left[\sqrt[n]{\prod_{i=1}^{n} a_{i}} \lambda^{i}, \ldots, \sqrt[n]{\prod_{i=1}^{n} a_{i}} \lambda^{i+\ell-1}\right]$.

Definition 5.3. a) Let $\Lambda=\left[\lambda_{j_{1}}, \ldots, \lambda_{j_{\ell}}\right]$ be a set of zeros of the polynomial $s^{n}-\prod_{i=1}^{n} a_{i}$. We define the matrix

$$
A_{\Lambda}=\left(\begin{array}{cccc}
\lambda_{j_{1}} a_{1} \ldots a_{n-1} & \lambda_{j_{1}}^{2} a_{2} \ldots a_{n-1} & \ldots & \lambda_{j_{1}}^{n} \\
\vdots & \vdots & \vdots \\
\lambda_{j_{\ell}} a_{1} \ldots a_{n-1} & \lambda_{j_{\ell}}^{2} a_{2} \ldots & a_{n-1} & \ldots \\
\lambda_{j_{\ell}}^{n}
\end{array}\right) \in M_{\ell \times n}\left(\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]\right)
$$

b) Let $U=\left[x_{1}, \ldots, x_{m}\right]$ be a set of consecutive zeros of the polynomial $s^{n}-1$. We define the matrix

$$
X_{U}=\left(\begin{array}{cccc}
x_{1} & x_{1}^{2} & \ldots & x_{1}^{n} \\
\vdots & \vdots & & \vdots \\
x_{m} & x_{m}^{2} & \ldots & x_{m}^{n}
\end{array}\right) \in M_{m \times n}\left(\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]\right)
$$

Let $C$ be the monomial code defined by the polynomial $p_{\bar{a}}(s)=g(s) \cdot h(s)$ over the splitting field $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$ of $p_{\bar{a}}(s)$ and consider now as $\Lambda$ the set of all zeros of $h(s)$. Following 4.1 the matrix $A_{\Lambda}$ is a parity matrix of the code $C$, if the minimum distance of $C$ over $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$ is $d_{H}\left(A_{\Lambda}\right)$. Then, the minimum distance of $C$ over $\mathbb{F}$ is at least $d_{H}\left(A_{\Lambda}\right)$, since $C$ over $\mathbb{F}$ is a subfield subcode of $C$ over $\mathbb{F}\left[\lambda_{1}, \ldots, \lambda_{n}\right]$.

Remark 5.4. Notice that the minors of $A_{\Lambda}$ are of Vandermonde type.
Theorem 5.5. Let $\Lambda$ be the set defined in 5.3 and $U$ be a consecutive set of roots of $s^{n}-1$ such that $d_{H}\left(A_{\Lambda}\right)-2 \geq 0$. Then, $d_{H}\left(A_{\Lambda}\left(X_{U}\right)\right) \geq d_{H}\left(A_{\lambda}\right)+\operatorname{card} U-1$.

Proof. It suffices to observe that in this particular setup $d_{H}\left(A_{\Lambda}\right) \geq 2$, then we can apply Lemma 5.1.
As a Corollary we obtain the following result.
Theorem 5.6. Let $C$ be a monomial code of length $n$ over $\mathbb{F}$, and $p_{\bar{a}}=g(s) h(s)$. For some integers $\ell, m \geq 1$, suppose that $h(s)$ has a string of $m$ consecutive zeros: $h\left(\lambda_{\ell}\right)=h\left(\lambda_{\ell+1}\right)=\ldots=h\left(\lambda_{\ell+m-1}\right)=0$. Then, the minimum distance of $C$ is at least $d$.

Example 5.7. Let $n=9, q=7, a_{n}=2, a_{1}=3, a_{2}=\ldots=a_{n-1}=1$ and let $\alpha$ be a 18 th-primitive root of unity. Taking into account that $\left(x^{18}-1\right)=\left(x^{9}-1\right)\left(x^{9}+1\right), \alpha$ is a root of $x^{9}+1$ and $\alpha^{2}=\beta$ is a primitive root of $x^{9}-1$. We want to classify the zeros with respect to the various irreducible polynomial divisors of $x^{9}+1$. We will determine the cyclotomic cosets of 7 modulo 18 containing the odd integers: $C_{1}=[1,7,13], C_{3}=[3]$, $C_{5}=[5,17,11], C_{9}=[9], C_{15}=[15]$.

Let the zeros of $h(s)$ be $\alpha^{i}$ with $i \in C_{1} \cup C_{5}$, so $h(s)=(s-\alpha)\left(s-\alpha^{7}\right)\left(s-\alpha^{13}\right)\left(s-\alpha^{5}\right)\left(s-\alpha^{17}\right)\left(s-\alpha^{11}\right)$. Given that $\beta_{i}=\alpha \beta^{i}=\alpha^{2 i+1}$ the zeros of $h(s)$ can be written as $\beta_{2}, \beta_{3} ; \beta_{5}, \beta_{6} ; \beta_{8}, \beta_{9}$. Since $h(s)$ has a string of two consecutive zeros. Then, the two parametric monomial code has a minimum distance $d \geq 3$.

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