$$e:\begin{pmatrix}x\\y\\z\end{pmatrix}=\{\vec{p}+\lambda\vec{r}_1+\mu\vec{r}_2\}$$

$$\hat{n}=\vec{r}_1\times\vec{r}_2$$

$$d=\frac{|(\vec{x}-\vec{p})\cdot\hat{n}|}{|n|}$$

$$\begin{pmatrix}a\\b\\c\end{pmatrix}=\left\{\begin{pmatrix}b\\-a\\0\end{pmatrix}\begin{pmatrix}c\\0\\-a\end{pmatrix}\begin{pmatrix}0\\c\\-b\end{pmatrix}\right\}$$

$$d=\left\|\frac{\vec{pq}\cdot\hat{n}}{|n|^2}\right\|$$

$$\measuredangle=\cos^{-1}(\hat{n}_x)=\sin^{-1}(\hat{n}_y)=\begin{pmatrix}\cos^{-1}(x)\\\sin^{-1}(y)\end{pmatrix}$$

$$\left\|\begin{pmatrix}a\\b\end{pmatrix}\right\|=\sqrt{a^2+b^2}$$

$$\|\vec{a}\|=\sqrt{\sum_{i=0}^{i=n}a_i^2}$$

$$\cos(\varphi)=\frac{\langle\vec{a},\vec{b}\rangle}{\|\vec{a}\|\,\|\vec{b}\|}$$