

The form `XObject` specified by the `O` entry is subject to the following restrictions; failure to abide by them could result in misalignment of the overlay with the rendered 3D graphics:

The form `XObject` is associated with a specific view (not with the camera position defined by the 3D view dictionary). It should only be drawn when the user navigates using the 3D view, not when the user happens to navigate to the same orientation by manual means.

It should only be drawn if the artwork-to-world matrix has not been altered.

It may only be specified in 3D view dictionaries in which both a camera-to-world matrix (`MS` and associated entries) and a projection dictionary (the `P` entry) are present.

The `CO` entry specifies the distance from the camera to the for the 3D view, which is the point around which the camera should rotate when performing an orbit-style navigation. Figure 9.4 illustrates camera positioning when orbiting around the center of orbit.

**FIGURE 9.4**

The LS

far planes, respectively. A value of **ANF** for **CS** means that the near and far planes are determined automatically based on the objects in the artwork.

The **Subtype** entry specifies the type of projection, which determines how objects are projected onto the near plane and scaled. The possible values are **O** for orthographic and **P** for perspective.

For orthographic projection, objects are projected onto the near plane by simply discarding their  $z$  value. They are scaled from units of the near plane's coordinate system to those of the annotation's target coordinate system by the combined factors specified by the **OS** entry and the **OB** entry.

For perspective projection, a given coordinate  $(x, y, z)$  is projected onto the near plane, defining a 2D coordinate  $(x_p, y_p)$  using the following formulas:

$$x_p = \frac{x}{z} \times z_n$$

$$y_p = \frac{y}{z} \times z_n$$

where  $z_n$  is the  $z$  coordinate of the near plane.

Scaling with perspective projection is more complicated than for orthographic projection. The **FOV** entry specifies an angle that defines a cone centered along the  $z$  axis in the camera coordinate system (see Figure 9.5). The cone intersects with the near plane, forming a circular area on the near plane. Figure 9.6 shows this circle and graphics from the position of the camera.

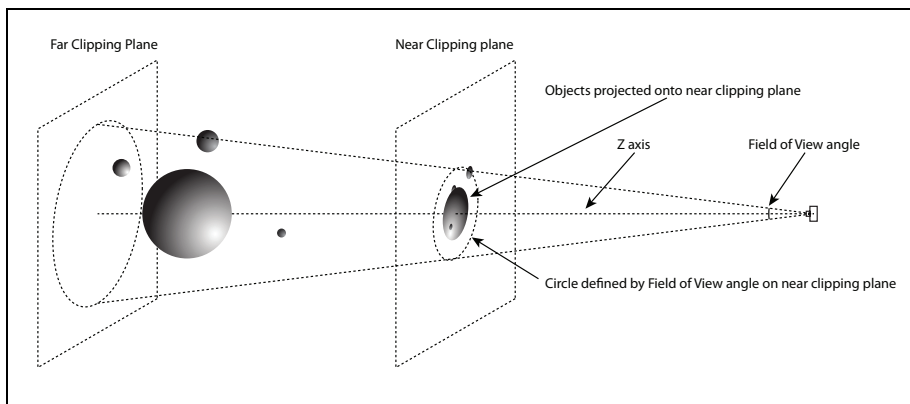


FIGURE 9.5

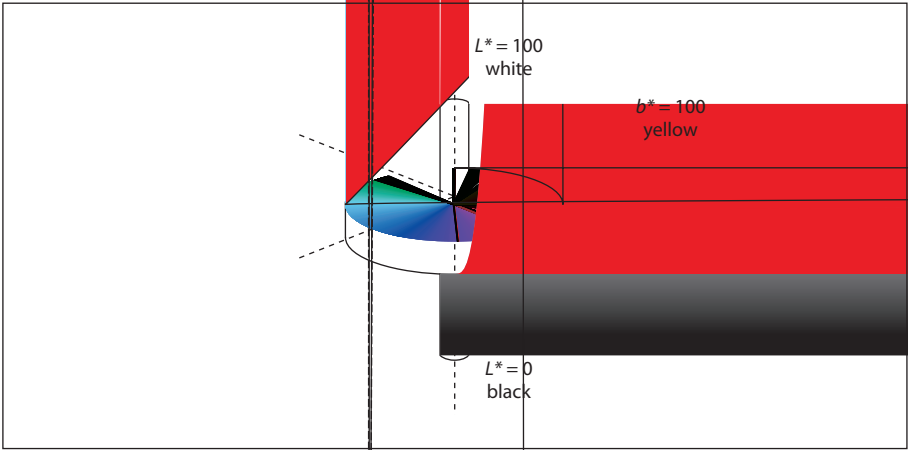
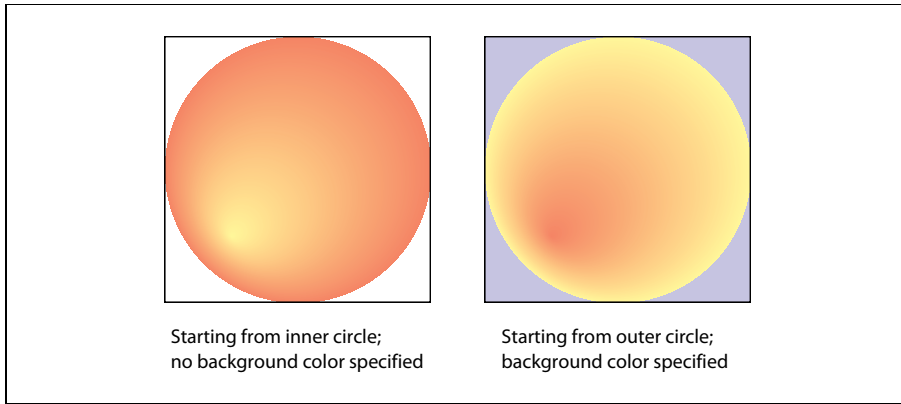


PLATE 3

RGB

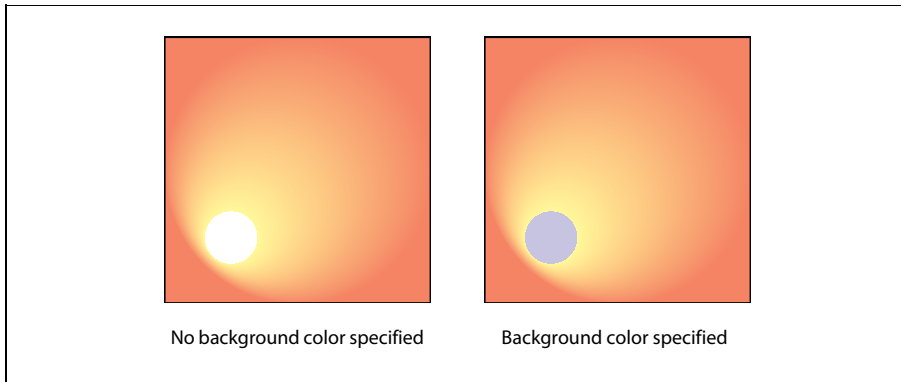
RGB



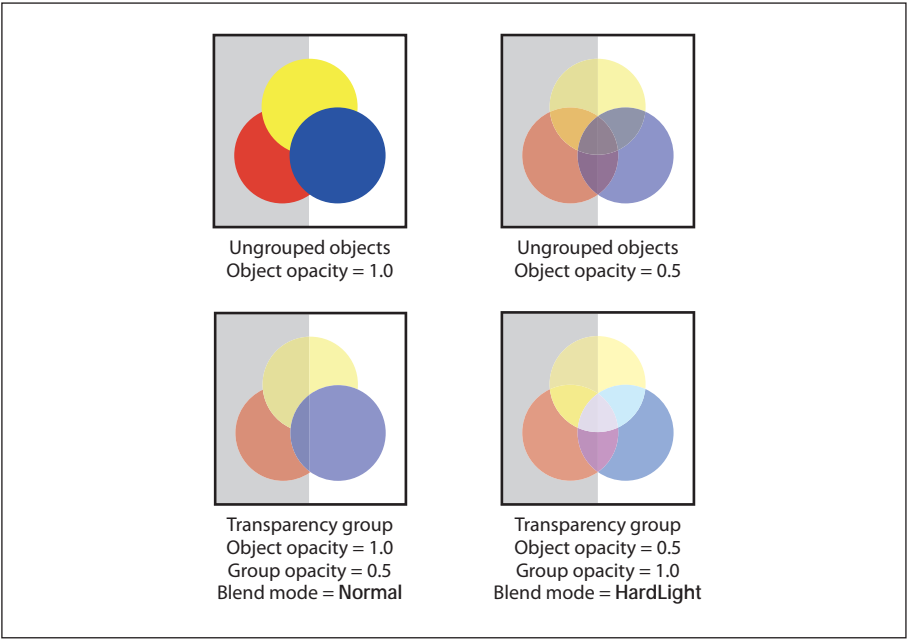


**PLATE 12**

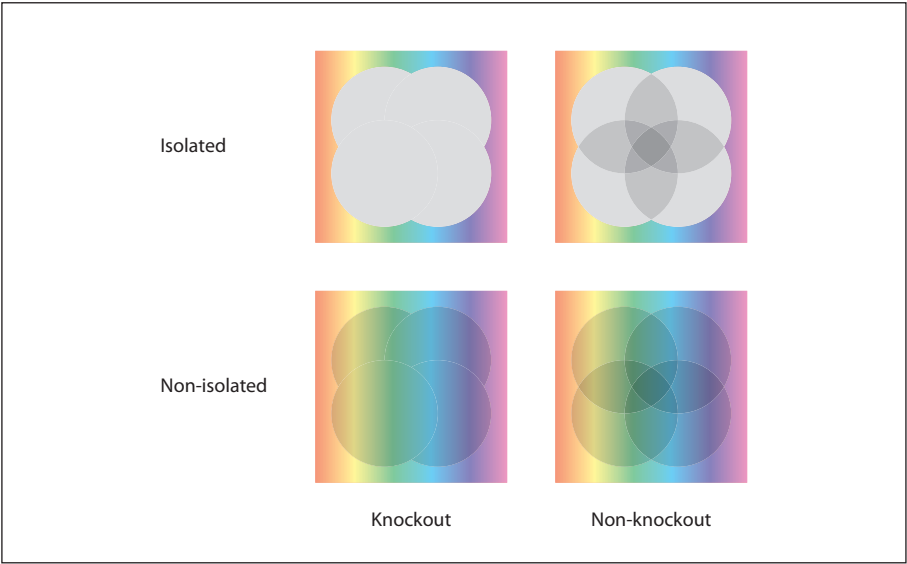
( 3 ( ) , 313)



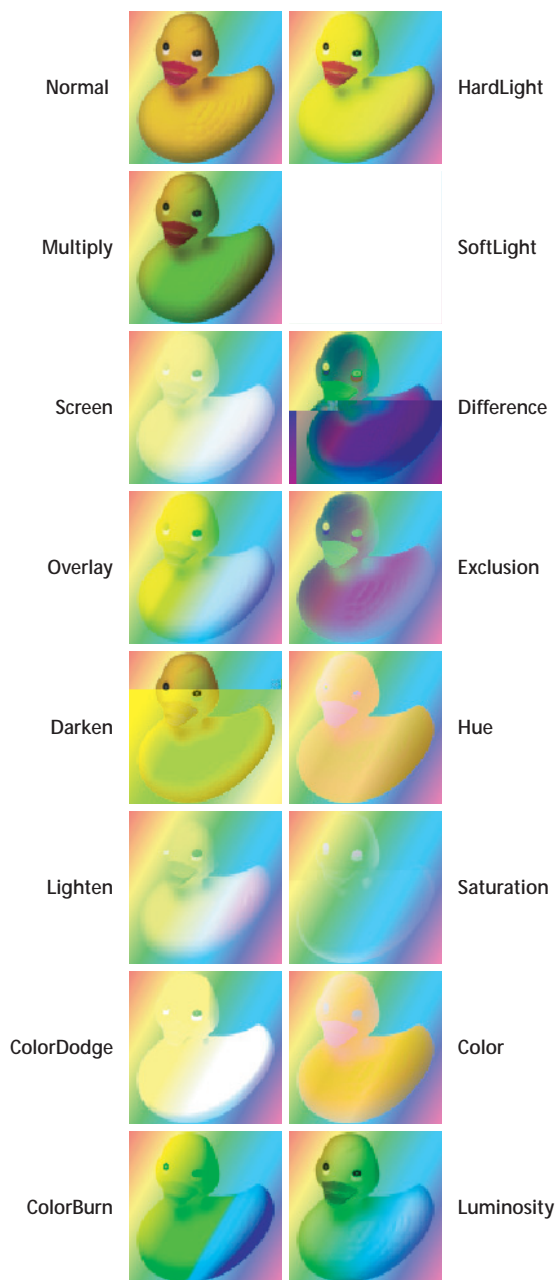
**PLATE 13**



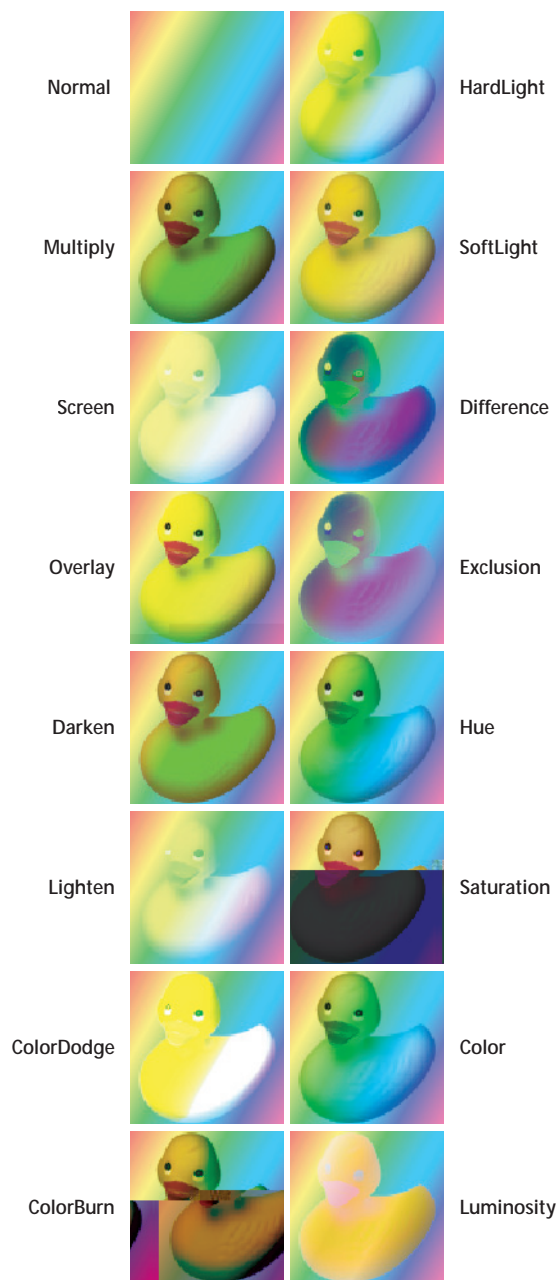
**PLATE 16** ( 7.1, , 515)



**PLATE 17** ( 7.3.4, , 539  
7.3.5, , 540)



Duck in foreground, rainbow in background



Rainbow in foreground, duck in background